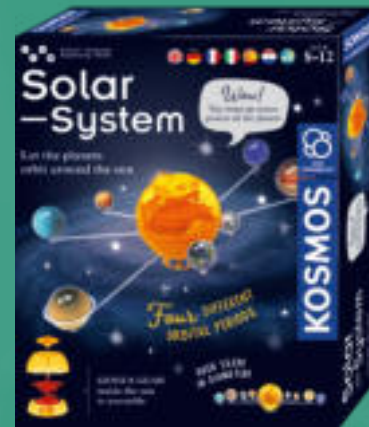


MORE EXCITING EXPERIMENTS!



YOUR INTELLIGENT ROBOT



LET THE PLANETS
ORBIT AROUND
THE SUN



YOUR XXL HYDRAULIC HAND



LET
KNOWLEDGE
GROW.

Do you have any
questions?
Our customer service
team will be glad to
help you!

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Manual

Cyborg —Hand

Your XXL hydraulic hand

THIS HAND GIVES YOU
new abilities

Agile!

Control your fingers
precisely or **grab**
large objects



SCAN QR CODE FOR FULL-COLOUR MANUAL

LANGUAGES:
English, Deutsch,
Français, Italiano,
Español, Nederlands
AND MANY MORE



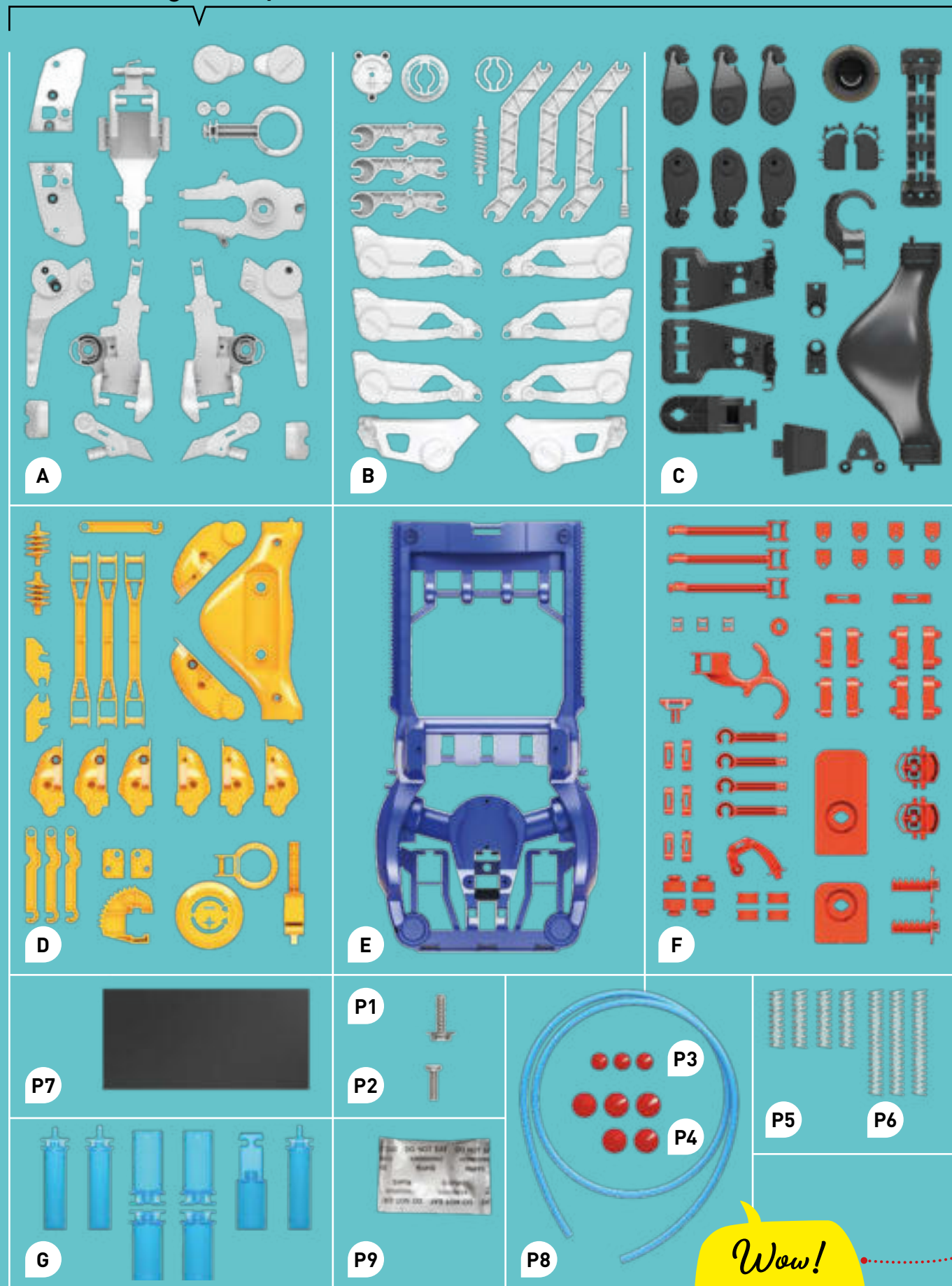
or go to: www.kosmos.de/int/Cyborg-Hand

STEM
EXPERIMENT KIT

KOSMOS



What's in your experiment kit:



Wow!
— So many
components!

Imprint

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— TABLE OF CONTENTS

| | |
|--|----|
| Kit Contents | 2 |
| Table of Contents | 3 |
| Important Information | 4 |
| Adventure Comic Part 1 | 6 |
| ASSEMBLING STARTS ON PAGE 10 | |
| Assembling the palm rest, hand frame, and fingers | 11 |
| Assembling the hydraulic systems | 18 |
| Experiment 1: The power of air and water | 22 |
| Experiment 2: Hydraulic transmission | 23 |
| Check It Out: Hydraulics | 26 |
| Assembling the thumb | 27 |
| Assembling the cyborg hand | 30 |
| Right- and left-handed configurations | 34 |
| Adventure Comic Part 2 | 38 |

USING THE CYBORG HAND STARTS ON PAGE 40

| | |
|--|----|
| Basic usage instructions | 41 |
| Settings | 42 |
| Experiment 3: Picking up small objects | 46 |
| Experiment 4: Grabbing large objects | 47 |
| Check It Out: Exoskeletons | 48 |
| Troubleshooting | 50 |
| Check It Out: Cyborgs | 52 |
| Experiment 5: Mysterious air pressure | 54 |
| Imprint | 55 |

TIPS

YOU WILL FIND ADDITIONAL INFO
IN THE CHECK IT OUT SECTIONS ON
PAGES 26, 48 AND 52

Checklist:

| ✓ No. | Description | Quantity | Item No. |
|-------|-----------------------------|----------|----------|
| ○ P1 | Wide-headed screw | 3 | 723606 |
| ○ P2 | Screws | 20 | 723606 |
| ○ P3 | Caps, small | 3 | 723605 |
| ○ P4 | Caps, large | 5 | 723604 |
| ○ P5 | Short spring | 4 | 723605 |
| ○ P6 | Long spring | 3 | 723605 |
| ○ P7 | Foam Pads | 19 | 724809 |
| ○ P8 | Tubing | 1 | 723604 |
| ○ P9 | Lubricant packet | 1 | 723607 |
| ○ A | Frame A with parts A1 – A16 | 1 | 723601 |
| ○ B | Frame B with parts B1 – B11 | 1 | 723597 |
| ○ C | Frame C with parts C1 – C14 | 1 | 723598 |
| ○ D | Frame D with parts D1 – D18 | 1 | 723599 |
| ○ E | Main hand frame part | 1 | 723600 |
| ○ F | Frame F with parts F1 – F20 | 1 | 723596 |
| ○ G | Frame G with parts G1 – G3 | 1 | 723602 |



YOU WILL ALSO NEED:

Scissors or diagonal pliers, nail file, ruler,
felt-tip pen, plastic cup or mug filled
with tap water, phillips screwdriver

Yay!
— Let's begin!

WARNING!

Not suitable for children under three years. Small parts. Choking hazard. Long tubes. Strangulation hazard. Keep the packaging and instructions as they contain important information.

The right tool

Using the right tool can make assembling your models easier and it can also make your models work better in the end. It is best to cut the Plastic parts out of their frames With a small diagonal cutter (such as those used for electronics work) or model pliers. Using these tools, the parts can be precisely cut so that no burrs remain on the parts and there is no need to file them down.

If you don't have these pliers at home, you can use scissors and a nail file. Normal scissors do not cut as precisely as a diagonal cutter, so you may have to file some of the rough edges down with the nail file.



Build and experiment

Exoskeletons and hydraulics are exciting scientific topics that are easy to understand, especially with the help of a cyborg hand!

You can build one with the parts in this kit. You need patience to build it and set it up. To stay focused, it is advisable not to build the model all in one sitting, but rather to take breaks in between building sessions.

Try to follow the instructions carefully and, if in doubt, ask an adult for help.

— IMPORTANT INFORMATION

— This experiment kit is recommended for children 10 years and older.

Dear Parents!

Children want to explore, understand, and create new things.

They want to try things and do it by themselves. They want to gain knowledge!

They can do all of this with KOSMOS experiment kits.

With every single experiment, they grow smarter and more knowledgeable.

Before building and experimenting, read the instructions together with your child and discuss the safety instructions.

Support your child with advice and a helping hand, especially during tricky assembly steps or experiments.

To prevent damage to the work surface on which your child is building and experimenting, provide them with a mat or other surface protection. When experimenting with water, it is a good idea to have some paper towels ready to wipe up spills.

When cutting the plastic parts out of the frames with the diagonal cutter or scissors, special care must be taken, not just because of the sharp edges on the tools, but also because the plastic parts can yield sharp edges or burrs. These can be removed with the help of the diagonal cutter or a nail file. Supervise your child when they are using the sharp tools until you trust that they can handle the tools independently.

We hope you and your child have a lot of fun building and playing with the cyborg hand.

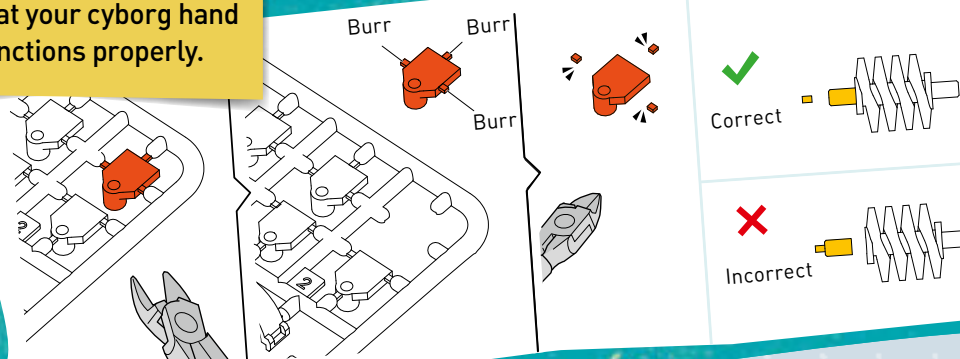


TIPS

! Make sure that all burrs are removed from the plastic parts before assembly so that your cyborg hand functions properly.

IMPORTANT:

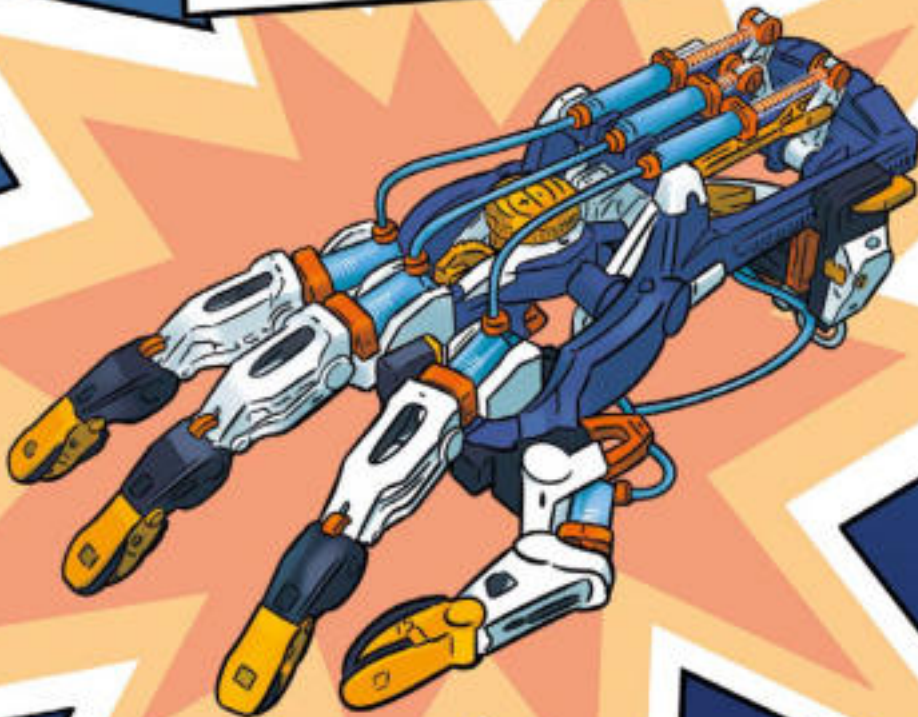
REMOVE THE PARTS FROM THE FRAMES ONLY WHEN THEY ARE NEEDED. REMOVE EXCESS MATERIAL BEFORE ASSEMBLY WITH THE HELP OF A DIAGONAL CUTTER OR A NAIL FILE.



THE

CYBORG-HAND

... AND THE
ENERGY CRYSTALS



TOM & IZZY

IT'S QUIET IN THE JUNKYARD.
EVERYONE HAS GONE TO SLEEP ...
... EXCEPT TOM AND IZZY.

HERE, WHERE OTHER PEOPLE JUST
SEE JUNK, OUR HEROES SEE
ENDLESS POSSIBILITIES.

THE
THRUST
MUST BE
INCREASED
BY A FACTOR
OF 10.

I FOUND
SOMETHING!

IT'S
THE PIECE
WE NEEDED!

WE
NEED MORE
THRUST ...

... TO OVERCOME
GRAVITY.

HMM ... THAT
COULD WORK.

... AS LONG
AS IT ISN'T
BROKEN.

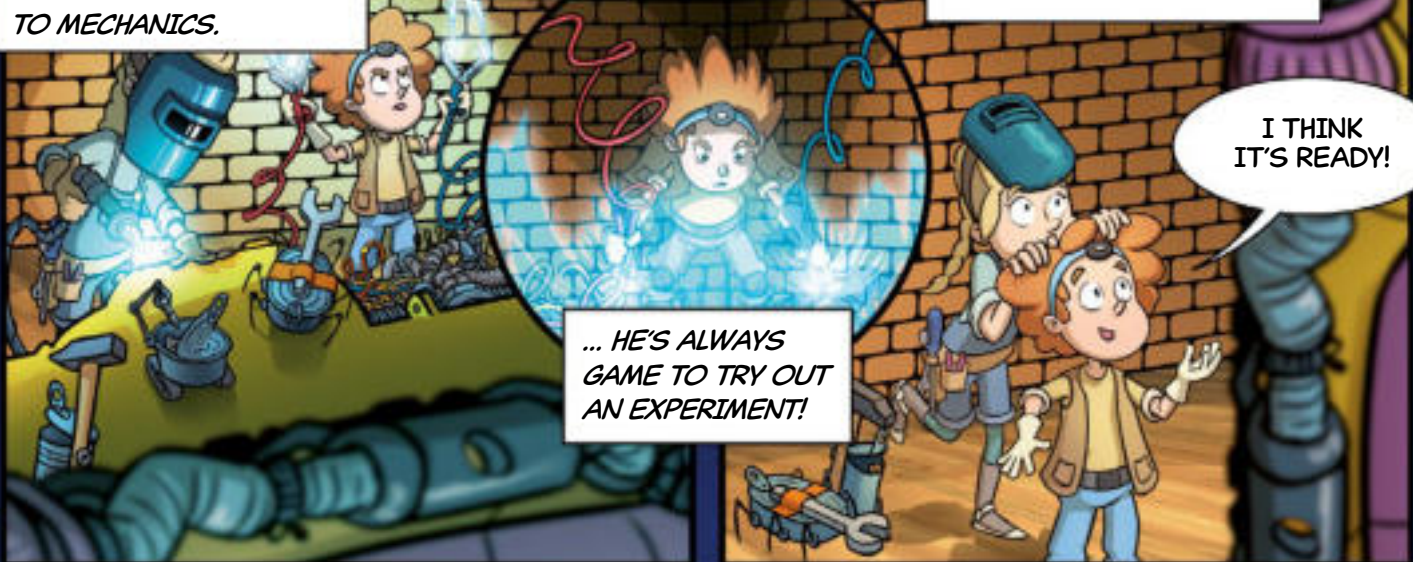
DON'T
WORRY! THIS
SMALL LEAK
WILL BE EASY
TO PLUG.

ALRIGHT,
LET'S GET
TO WORK!

IZZY CAN REPAIR ANYTHING. SHE IS A GENIUS WHEN IT COMES TO MECHANICS.

TOM, ON THE OTHER HAND, IS A SCIENTIST THROUGH AND THROUGH ...

TOGETHER, THEY CAN BUILD ANYTHING!



... HE'S ALWAYS GAME TO TRY OUT AN EXPERIMENT!



WHERE SHOULD WE FLY NEXT?

WHEREVER WE WANT!

WE CAN GO ANYWHERE!

REALLY HOPE THAT THE SURFACE SCAN WE PERFORMED FROM ORBIT WAS ACCURATE, AND THERE ARE IN FACT ENERGY SOURCES HERE THAT WE CAN USE TO PROPEL OUR SPACESHIP.

NO WORRIES, TOM. IF ALL ELSE FAILS, WE CAN WALK BACK TO EARTH ON FOOT, HAHA!

THAT IS NOT FUNNY, IZZY! IF WE DON'T FIND HIGH-ENERGY CRYSTALS, WE'LL NEVER GET OUT OF HERE AND ...

THERE'S ONE!

OH ...

WAIT, IZZY! IT MIGHT NOT BE SAFE TO HANDLE THAT WITH BARE HANDS ...

DON'T BE SILLY!

OOF!

I DID WARN YOU. ANYWAY, IT SHOULD NOT BE A PROBLEM WITH MY SUPER INSULATED GLOVES, BECAUSE ...

OOF!

BZZZZZZZ

HAHAHA! IT SEEMS WE NEED SOMETHING ELSE TO HANDLE THIS ...

I HAVE AN IDEA!



Assembling THE CYBORG HAND

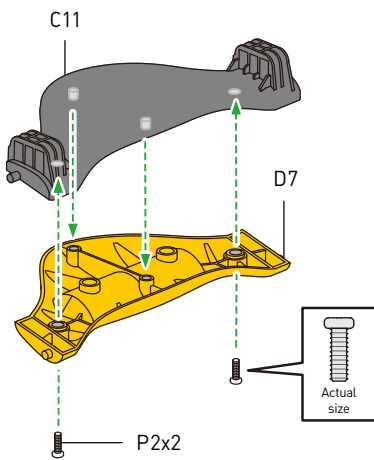
Are you ready to build? Let's begin the construction of your cyborg hand. You will start with the palm rest, the hand frame, and the fingers. Always wait to separate a plastic part from its frame until it is called for in the assembly instructions. This way, you can make sure that you don't lose any parts.

Let the
— building
begin!

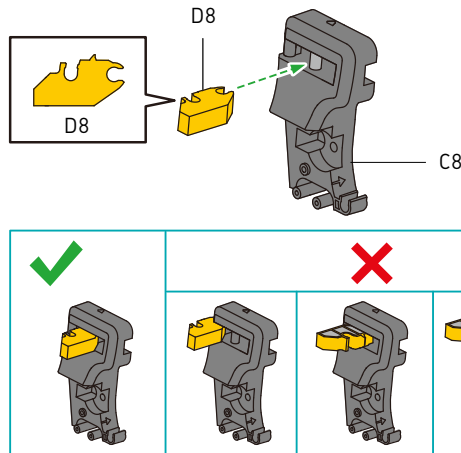


ASSEMBLING THE PALM REST

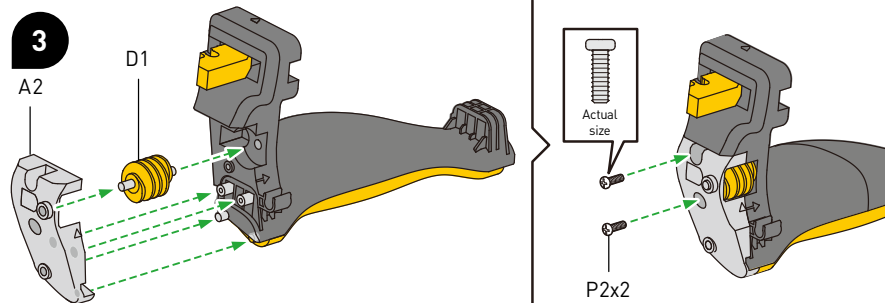
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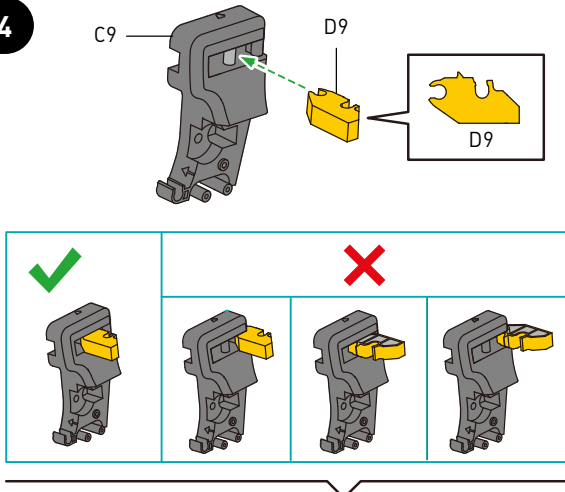
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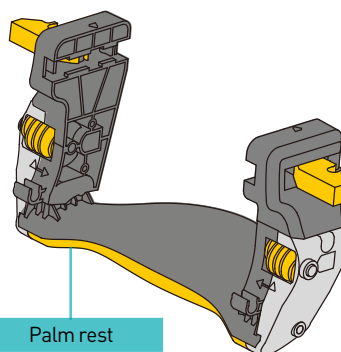
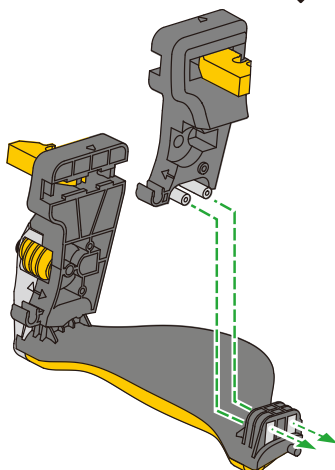
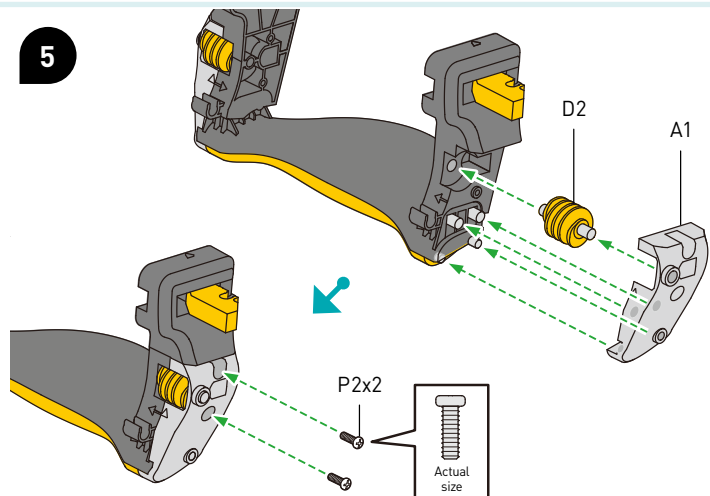
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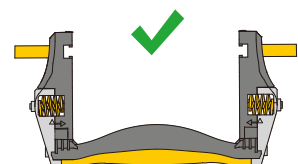


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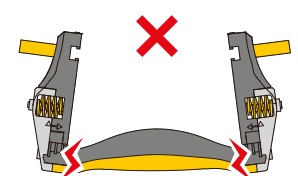


Palm rest

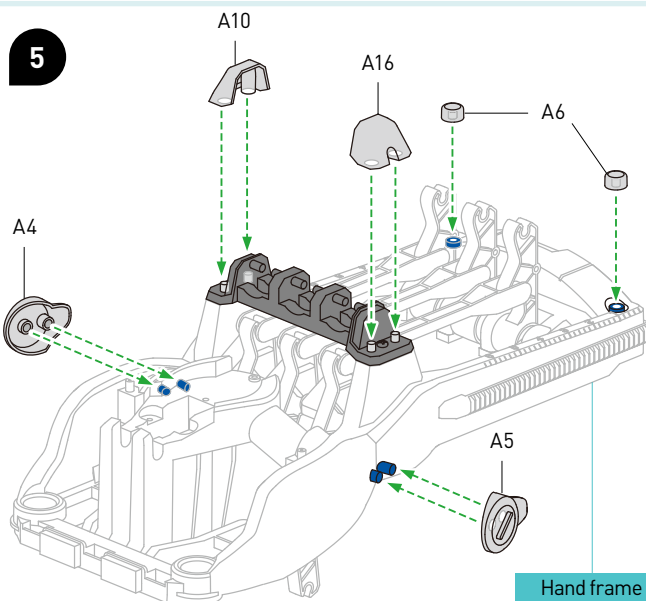
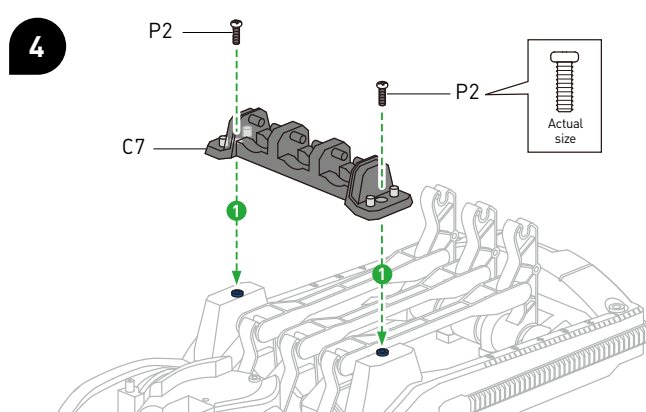
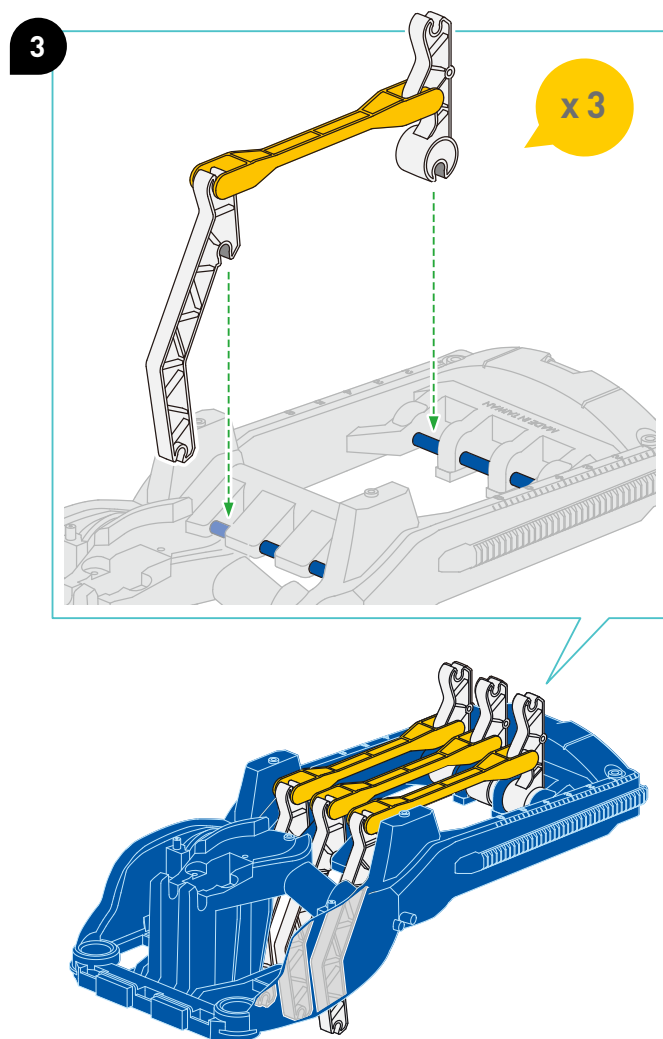
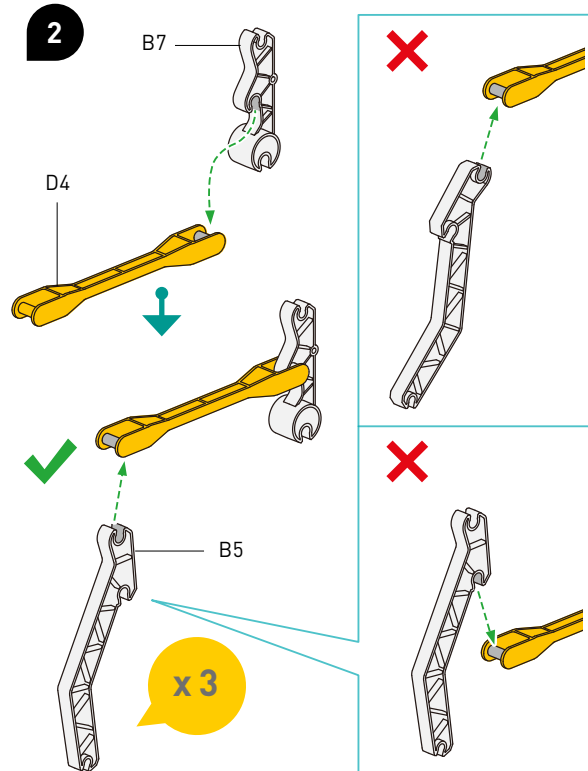
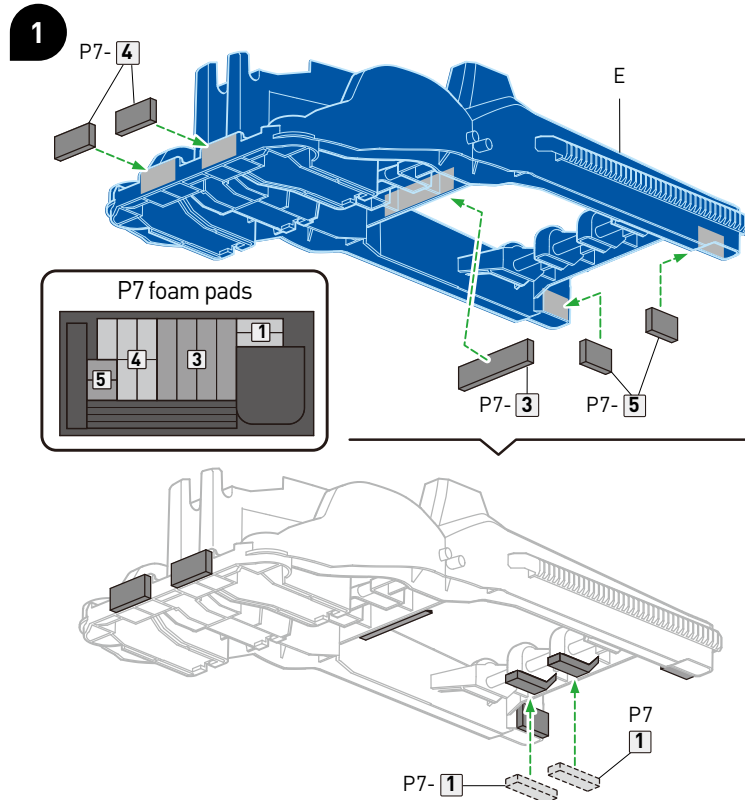
Front view



Do not squeeze.
The assembly could break.

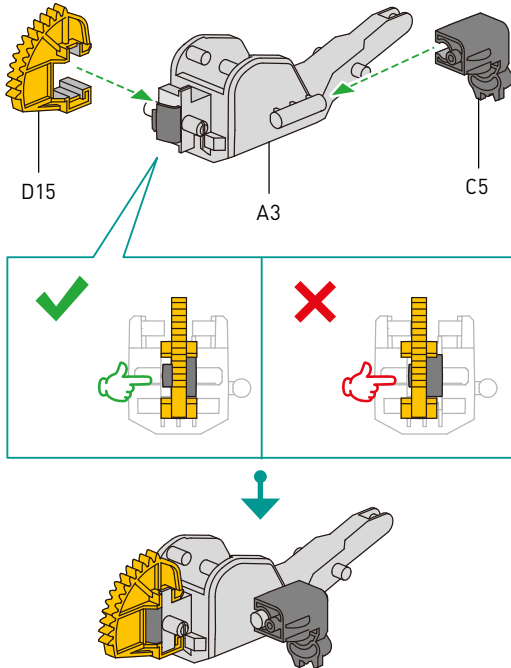


ASSEMBLING THE HAND FRAME

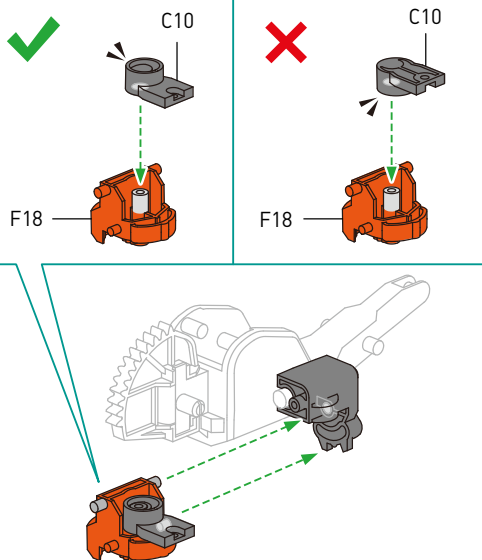


ASSEMBLING THE FINGERS

1



2

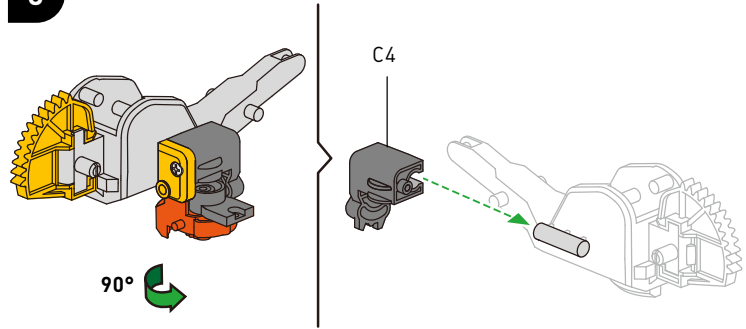


D13

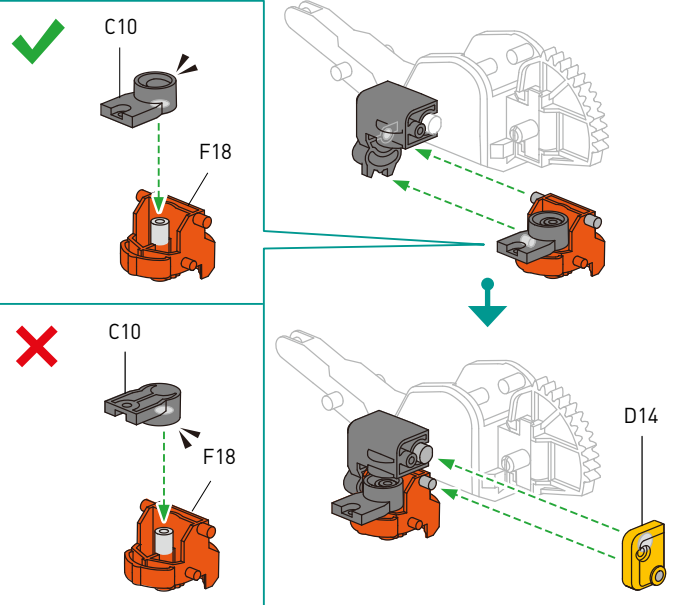
P2

Actual size

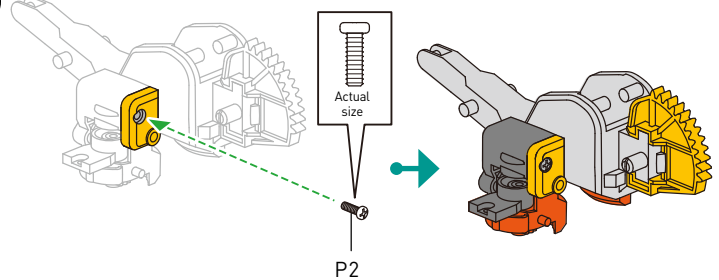
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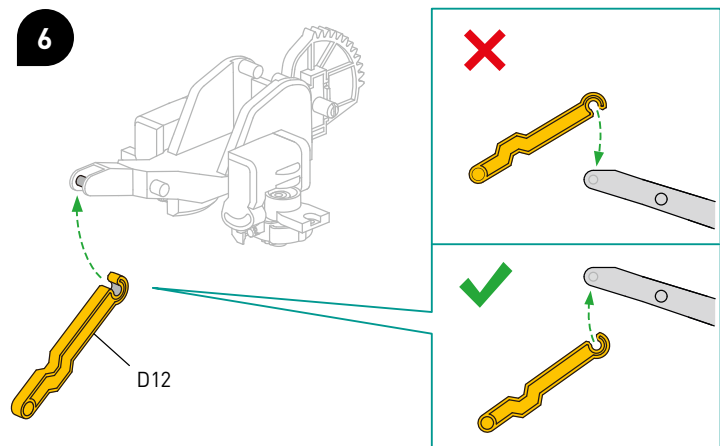
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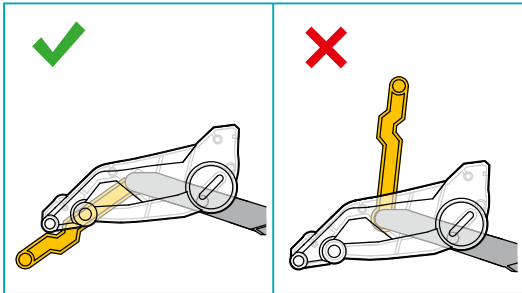
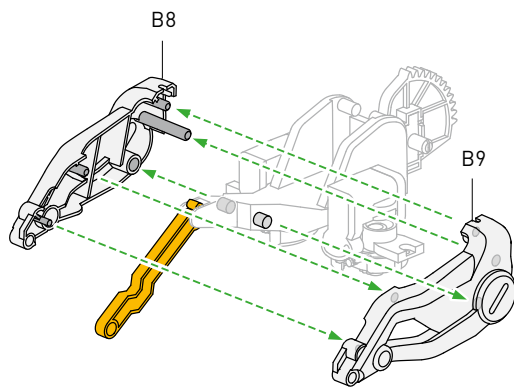


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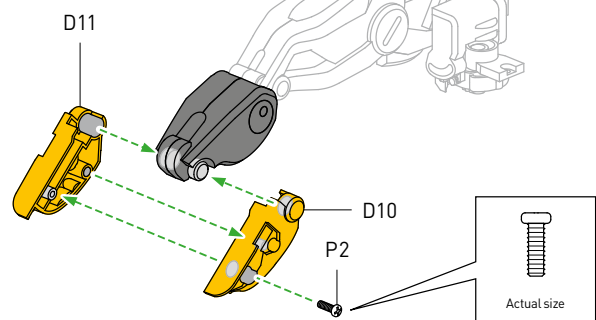
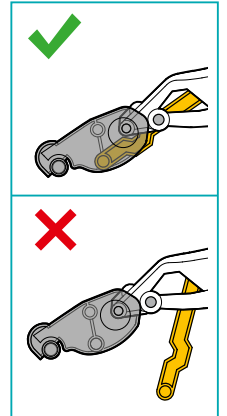
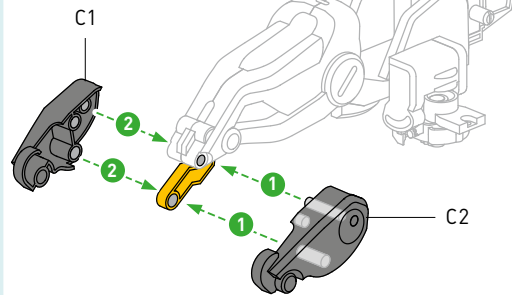


ASSEMBLING THE FINGERS

7

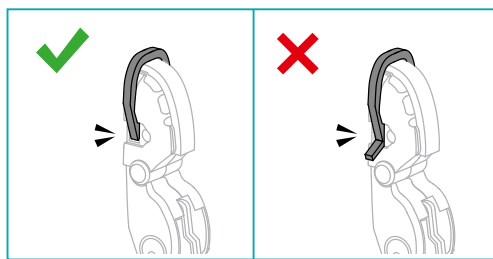
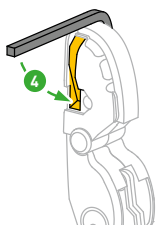
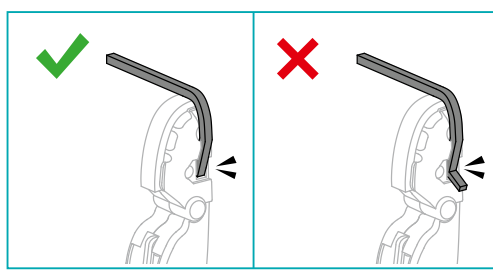
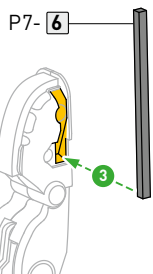
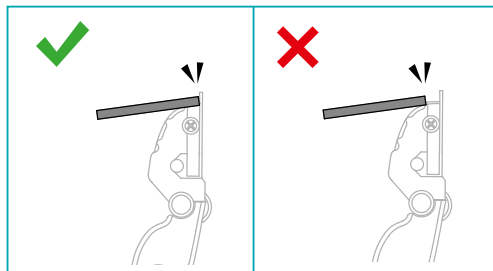
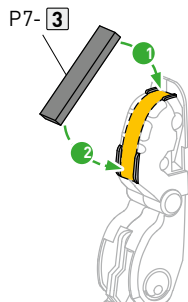
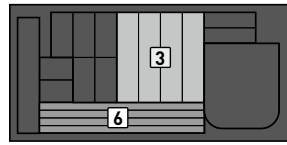


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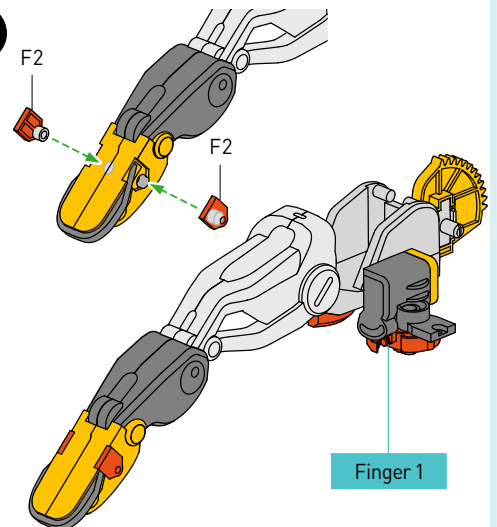


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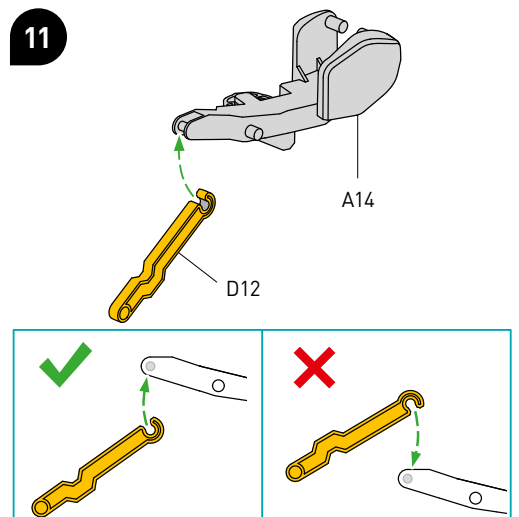
P7 foam pads



10

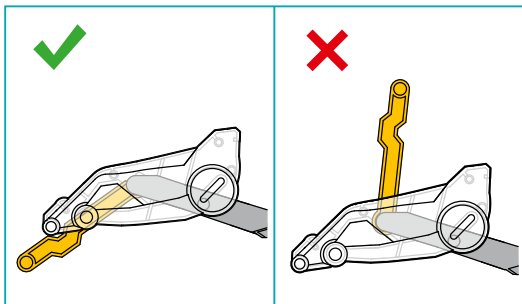
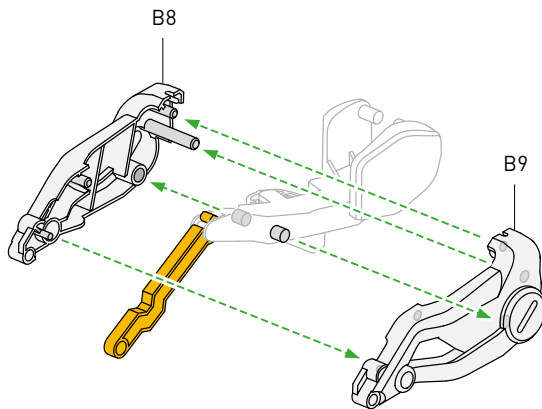


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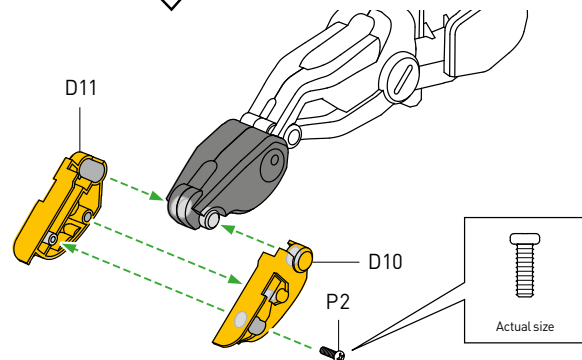
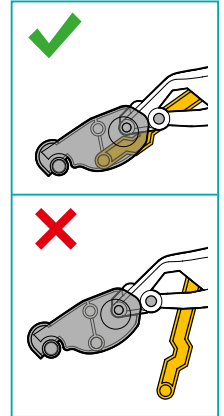
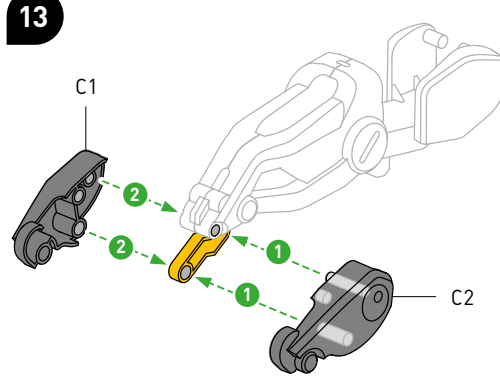




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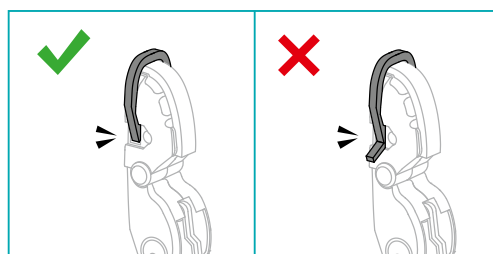
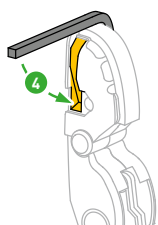
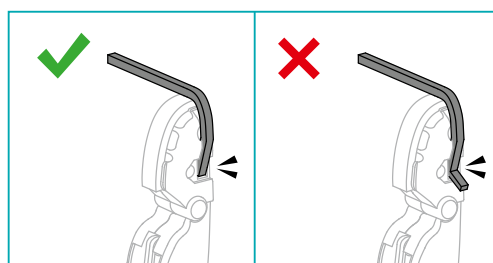
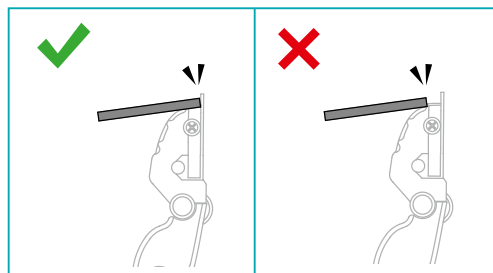
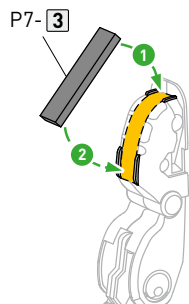
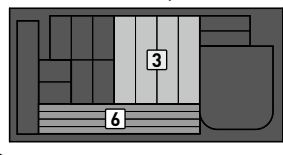


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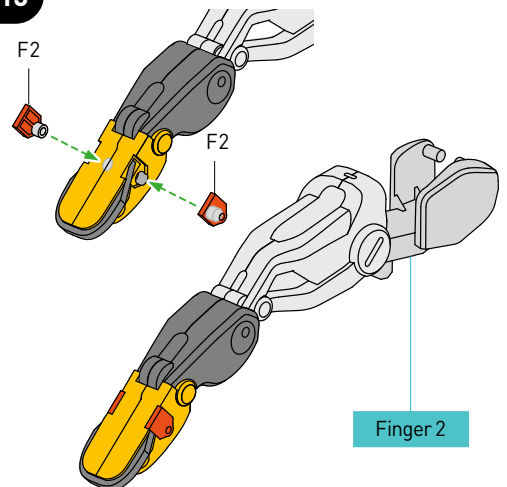


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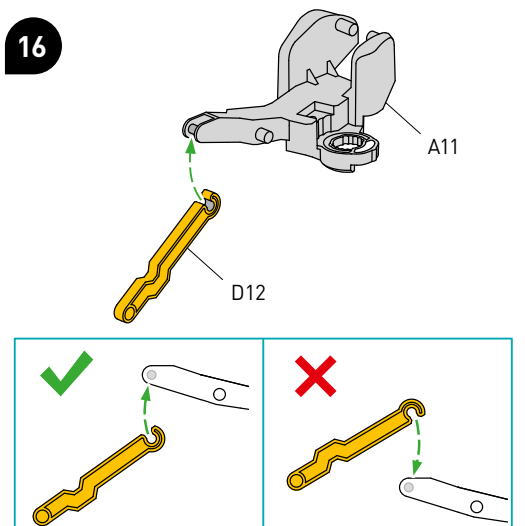
P7 foam pads



15

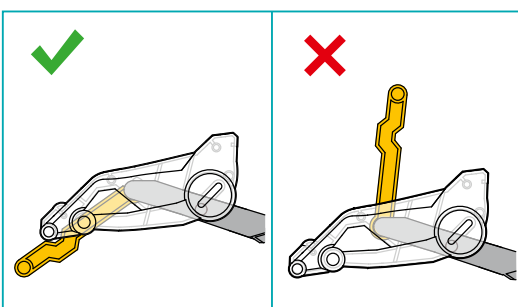
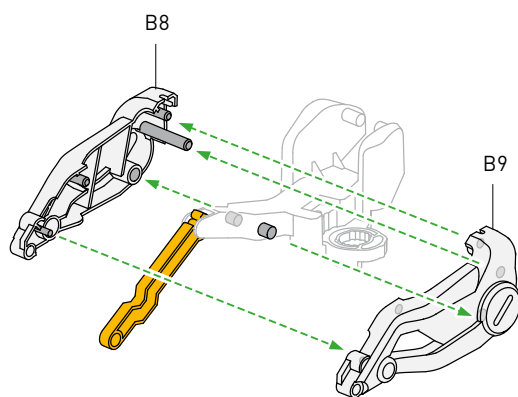


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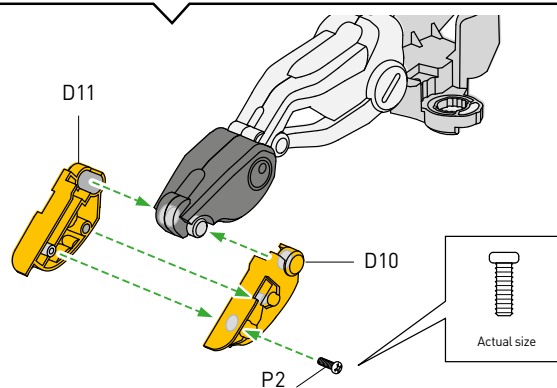
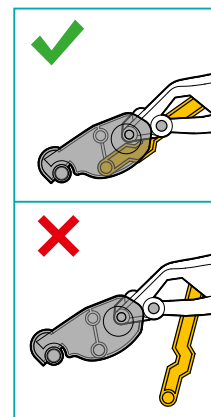
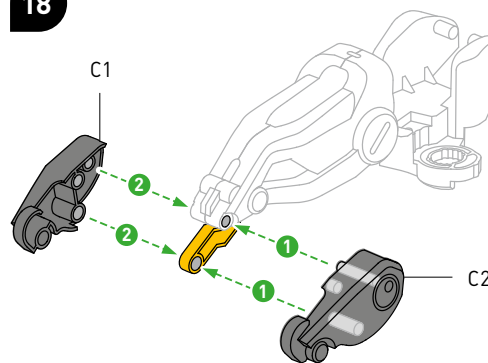


ASSEMBLING THE FINGERS

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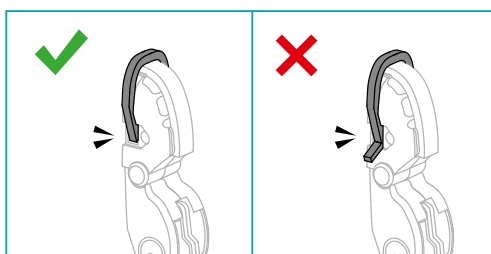
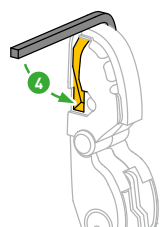
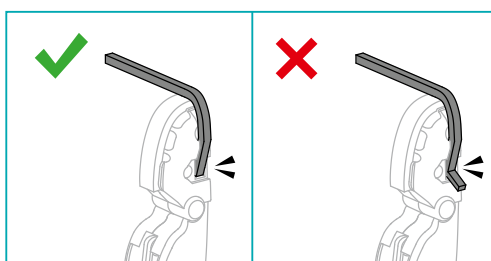
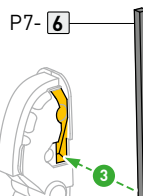
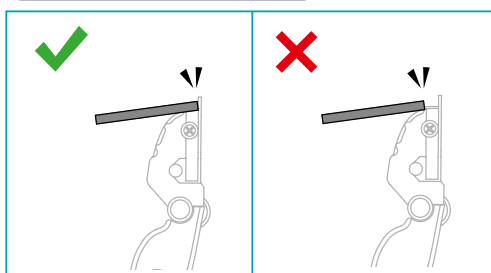
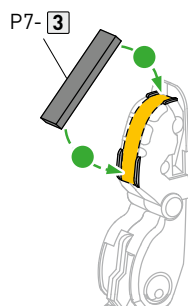
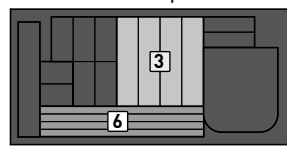


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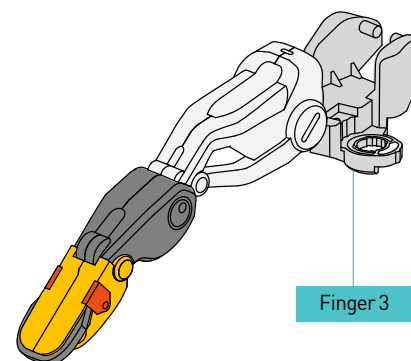
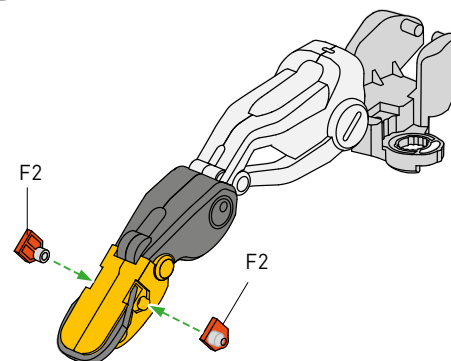


19

P7 foam pads



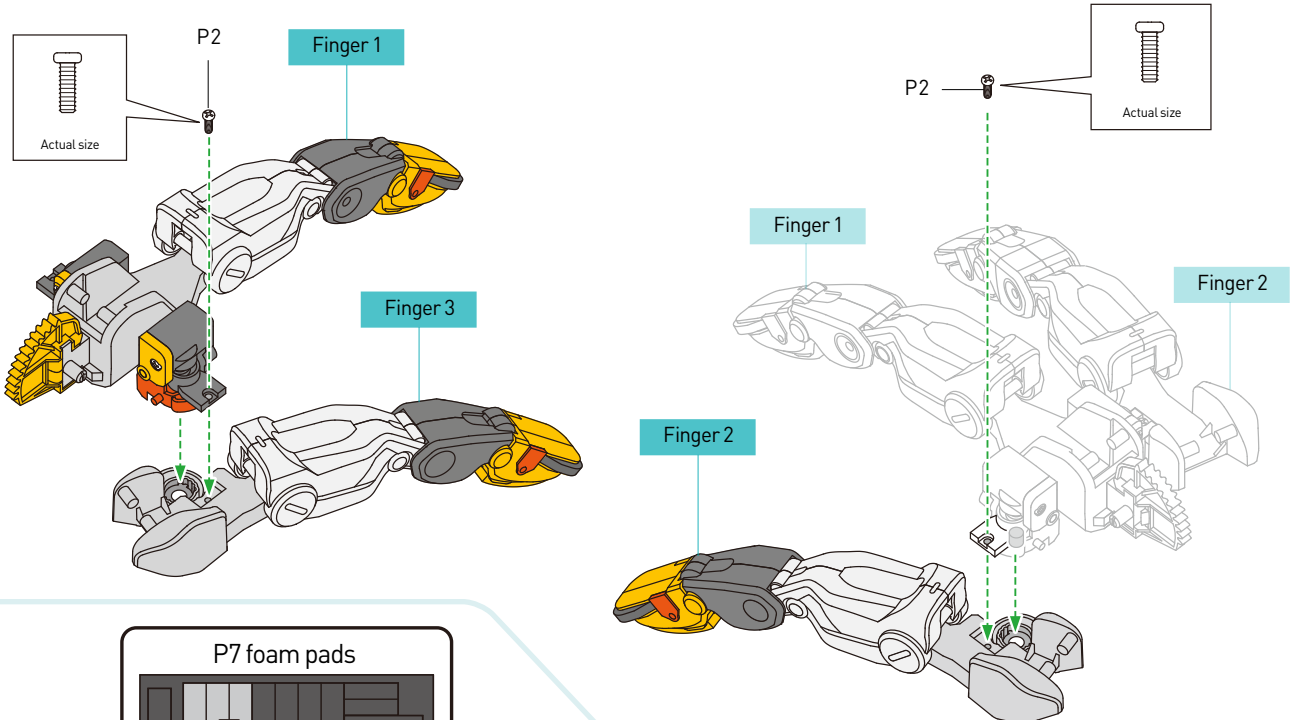
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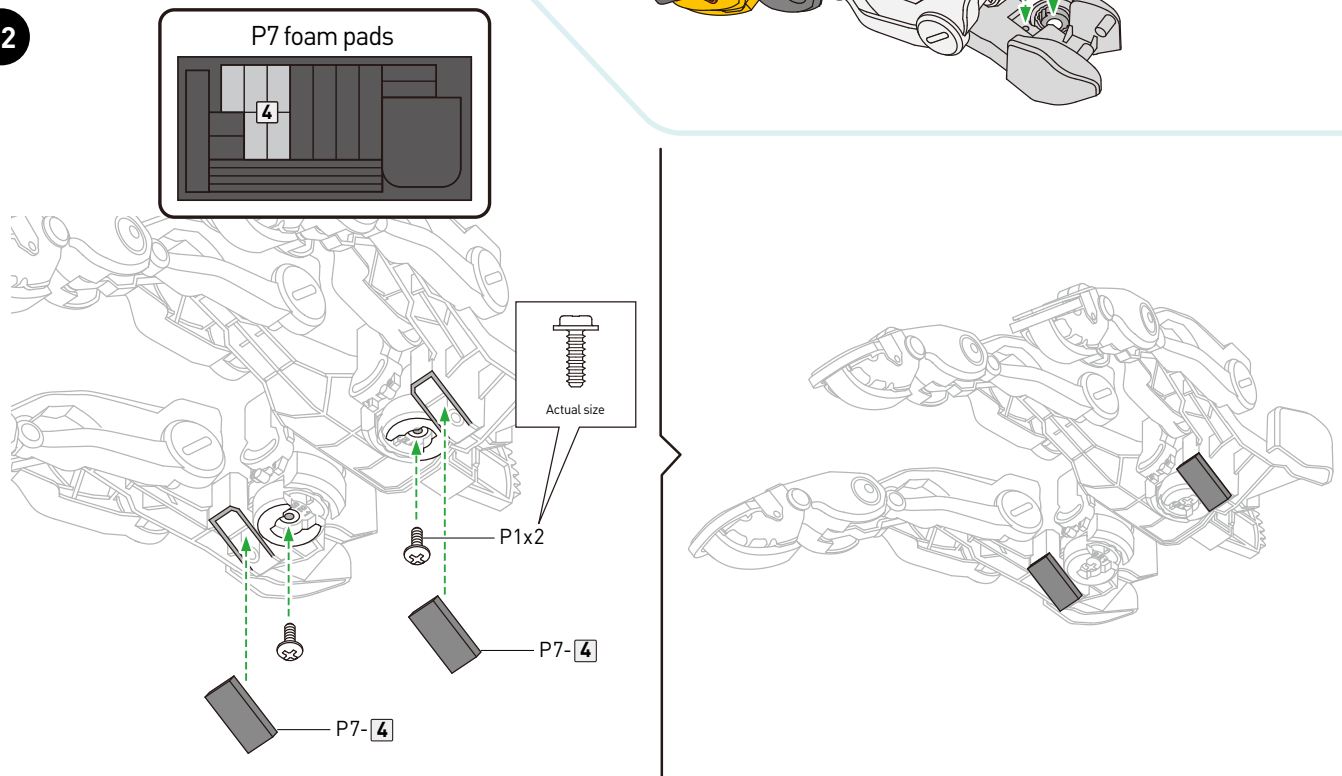
Finger3



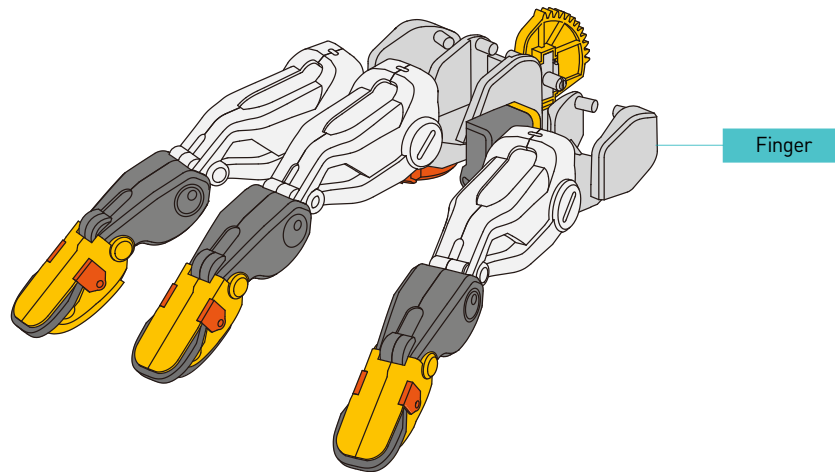
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22



23





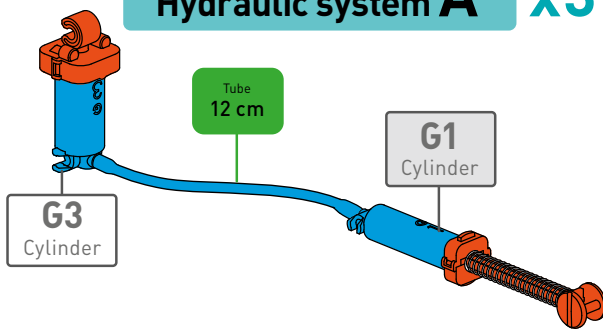
Wow . . .
— the hand
moves!

Assembling THE HYDRAULIC SYSTEMS

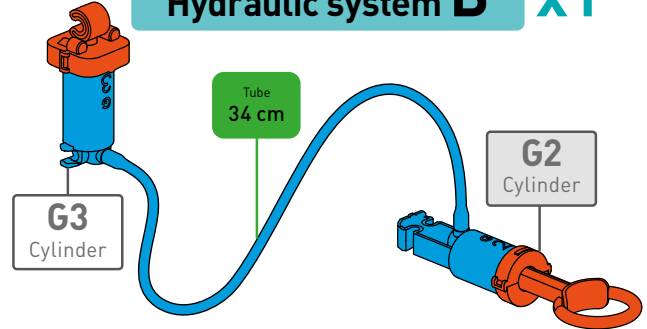
The cylinders, pistons, and tubes make up the hydraulic systems, which are some of the most important components of your cyborg hand. Filled with water, they transfer motion from your fingers to the fingers of the cyborg hand. Let's assemble the hydraulic systems now.

ASSEMBLING THE HYDRAULIC SYSTEMS

Hydraulic system A x3



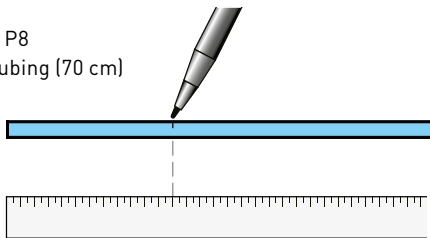
Hydraulic system B x1



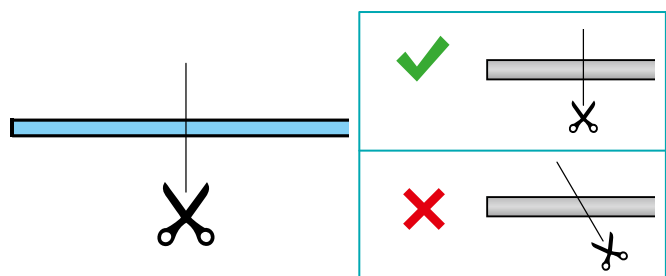
CUT THE TUBING TO LENGTH

Measure and mark

P8
Flexible tubing (70 cm)



Cutting

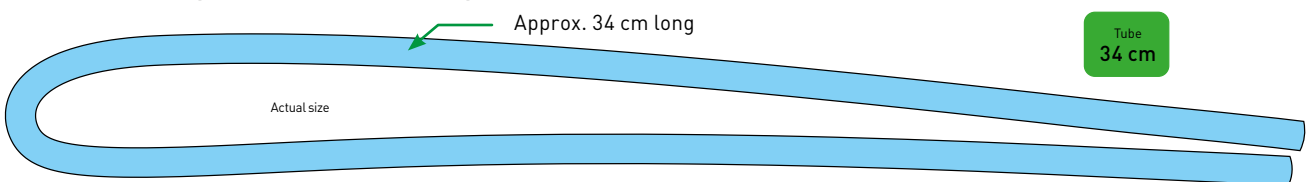


Cut three tubes of this length:

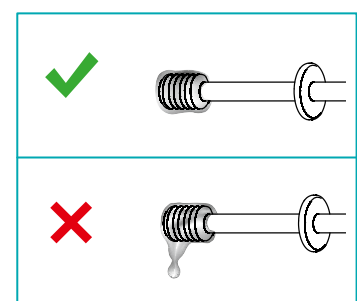
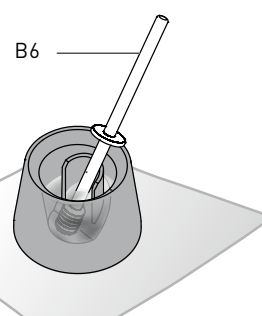
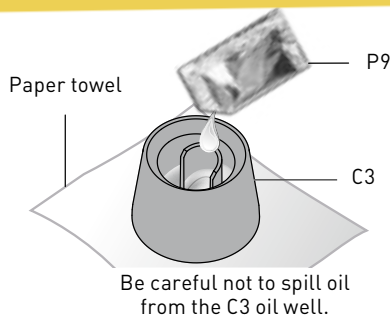


Tube 12 cm x3

The remaining tube will be this long:



HOW TO OIL THE CYLINDERS

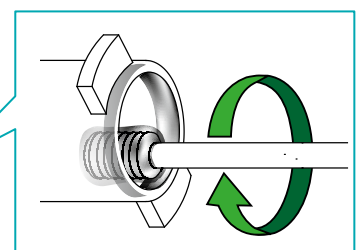
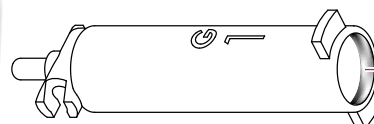


= Oil

Note! Oil components
when you see:

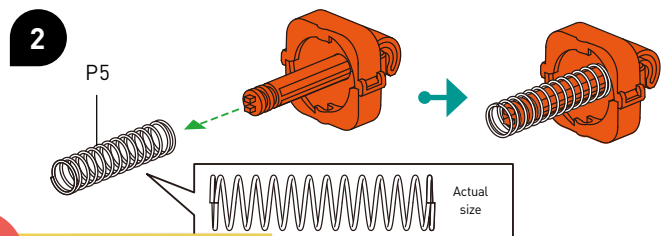
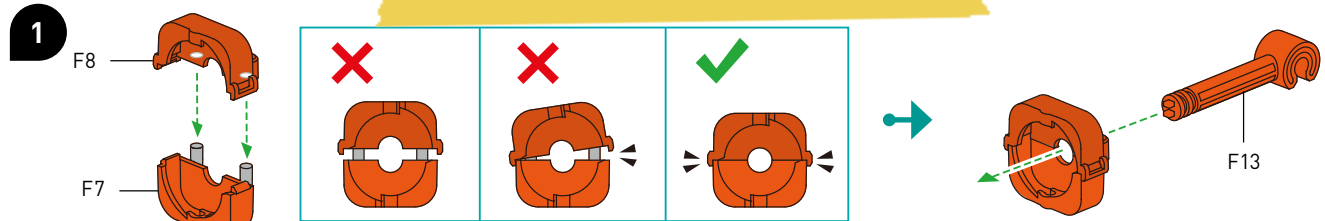


! Oil only the area shaded in gray.
Work carefully and do not
touch the oil with your hands or get
it into your eyes. Dispose of leftover oil
in the household trash after assembly.
Do not pour it down the drain.

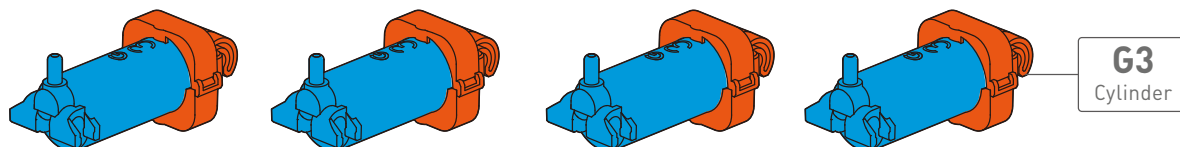
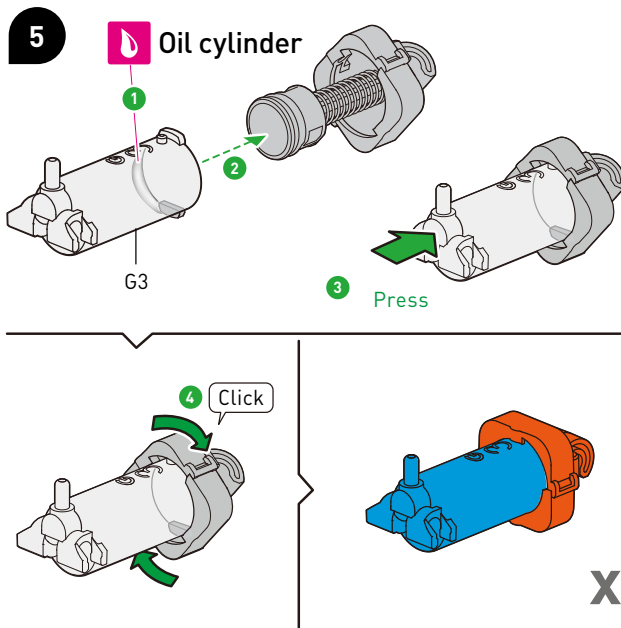
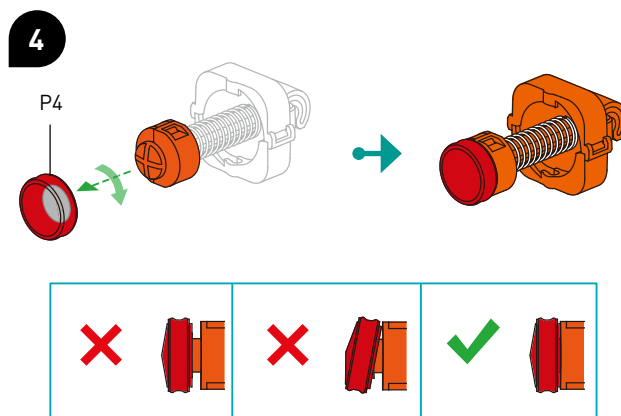
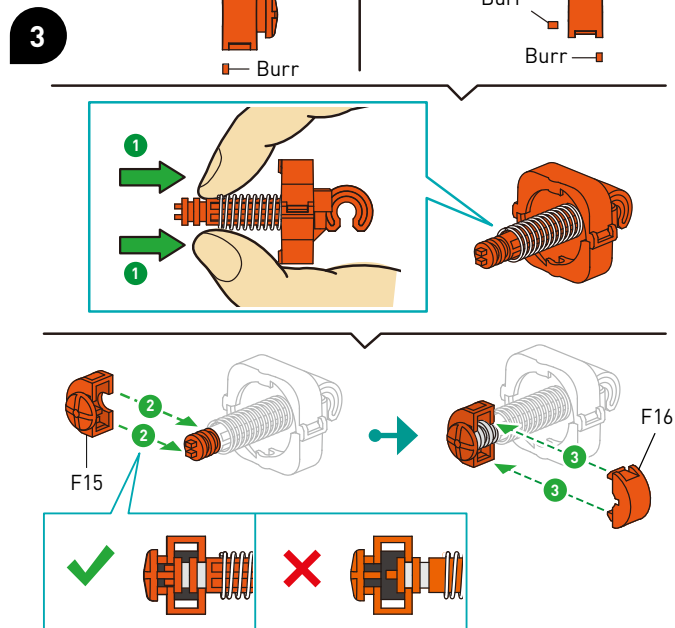
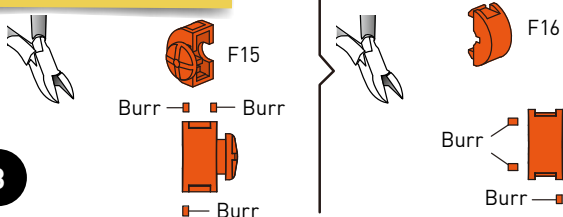


ASSEMBLING THE HYDRAULIC SYSTEMS

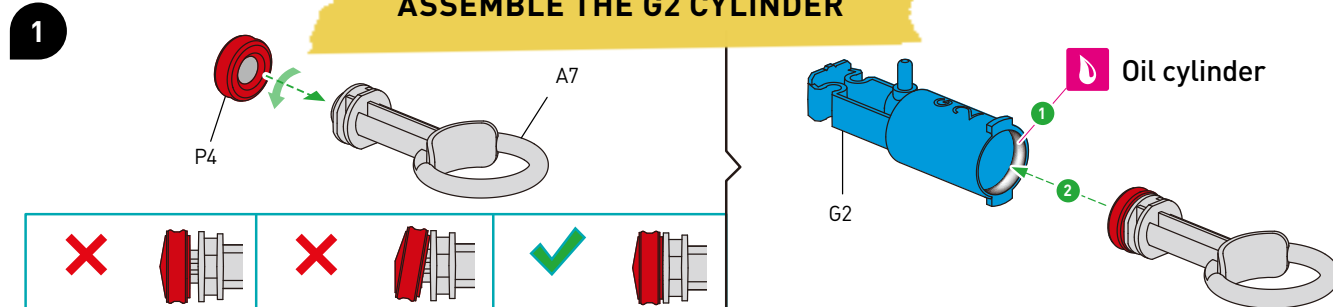
ASSEMBLE THE G3 CYLINDERS



Remove burrs before assembly

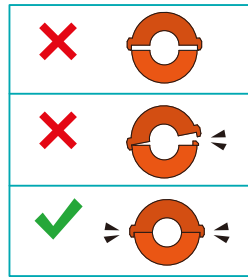
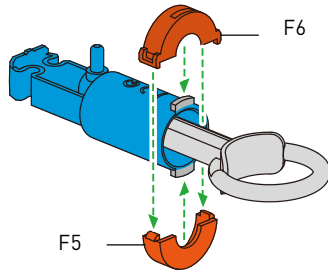


ASSEMBLE THE G2 CYLINDER

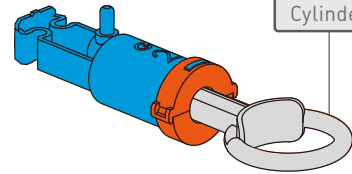




2

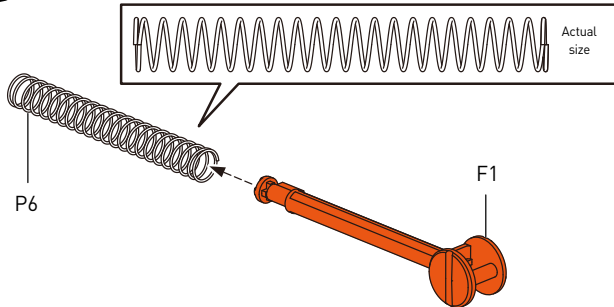


G2
Cylinder

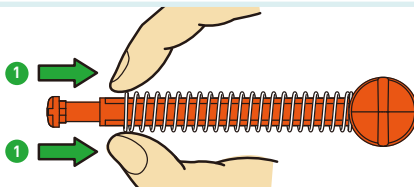


ASSEMBLE THE G1 CYLINDERS

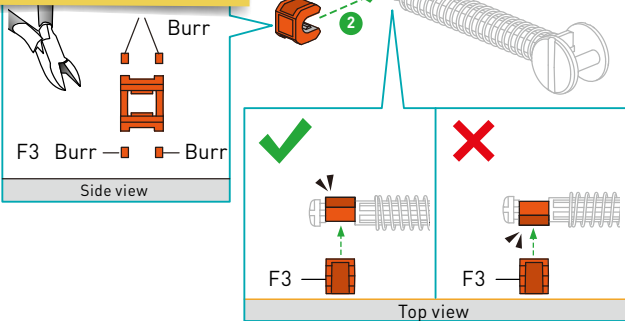
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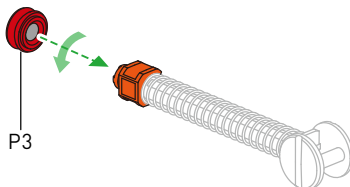
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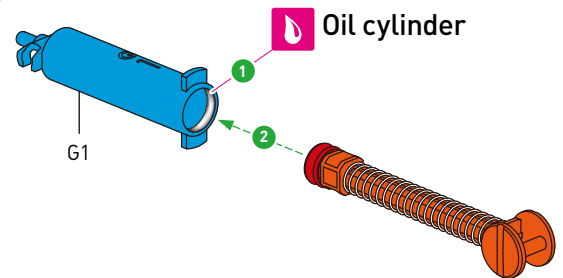
**Remove burrs
before assembly**



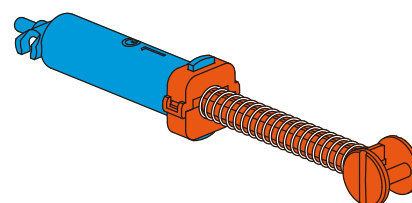
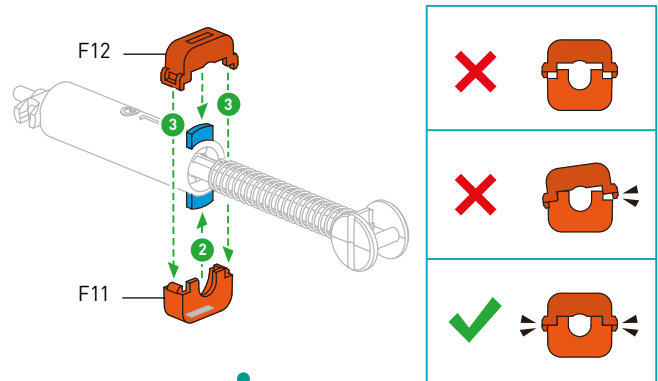
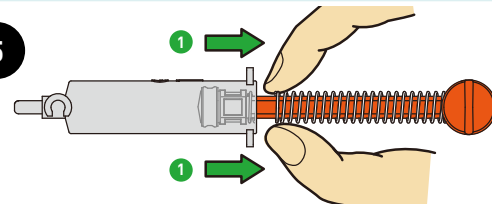
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4

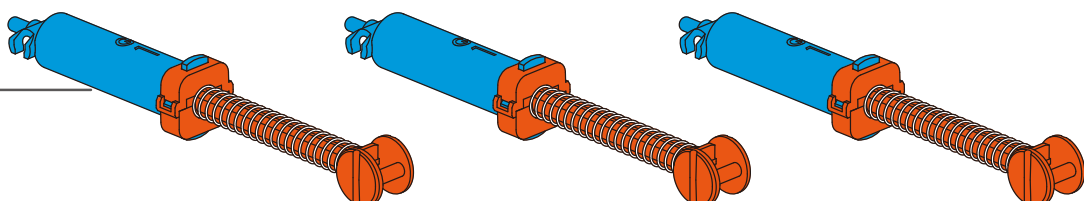


5



x3

G1
Cylinder





EXPERIMENT 1

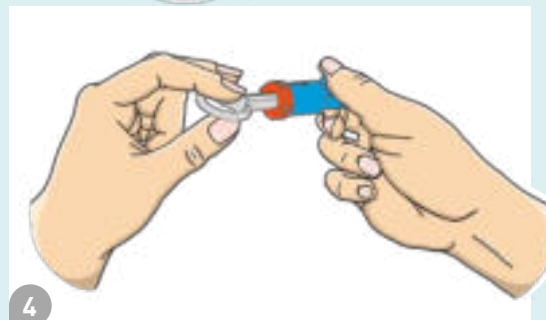
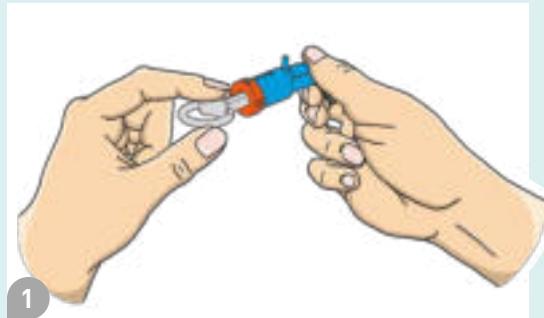
The power of air and water

You will need

- G2 hydraulic cylinder
- Cup of water

Here's how

1. Pull the piston of the G2 cylinder outward and then seal the opening of the tube connection nozzle with your finger.
2. Now push the piston in. It will slide in about a centimeter or two, but will spring back when released.
3. Now, fill the G2 cylinder completely with water. To do this, dip the opening of the tube connection nozzle into a cup filled with water, push the piston all the way in, and then pull it out again.
4. Again, seal the opening of the tube connection nozzle with your finger and push the piston in. You will hardly be able to move it in at all, and you will not feel the same springy, elastic feeling you felt when the cylinder was filled with air.



WHAT'S HAPPENING?

— Air is elastic. Air-filled balls used in sports take advantage of this scientific fact. The elastic air in bicycle and car tires absorbs vibrations and shocks while the vehicles are moving.

Unlike air, water can hardly be squeezed. This applies generally to all liquids, including oil. Under the influence of pressure, the density of all real substances changes, but especially with gases. This is much less the case with liquids and solids than with air. The amount by which a substance can be compressed is referred to as its **compressibility**.

EXPERIMENT 2

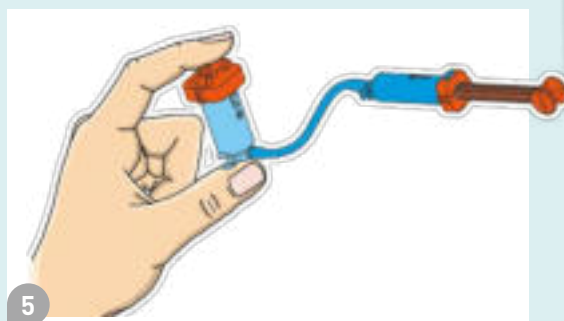
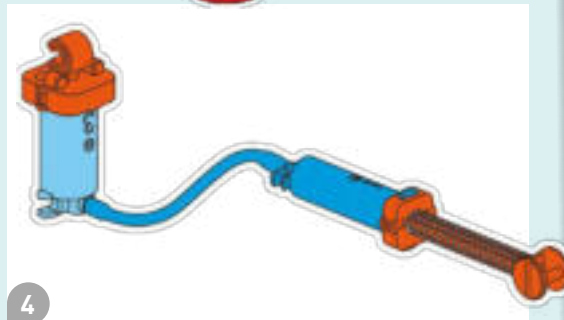
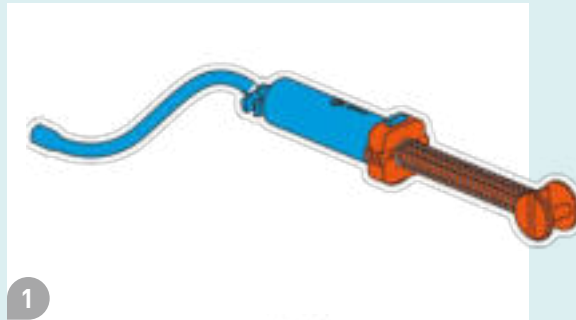
Hydraulic transmission

You will need

- G1 hydraulic cylinder
- G3 hydraulic cylinder
- Cup of water

Here's how

1. Attach one of your tubes to the tube connection nozzle on the G1 cylinder.
2. Now dip the free end of the tube into a cup filled with water. Push the piston all the way in and pull it out again so that the cylinder is filled with water.
3. Remove the free end of the tube from the cup and carefully push the piston of the cylinder in until there is no more air in the tube and cylinder. Then immerse the tube in the water again and pull the piston out of the cylinder as far as it will go.
4. Attach the free end of the tube to the tube connection nozzle on the G3 cylinder.
5. Now push the piston of G1 inward, and the piston of G3 will move outward accordingly. Try to block this outward movement: You will feel the force you exert on one piston transmitted to the other piston.
6. Empty the water from the cylinders and repeat the experiment with air. Can you move the G3 piston by pushing on the G1 piston?



KEYWORDS

DID YOU KNOW ...

... that this method of power transmission is widely used in technology? Devices that work with compressed air are called **pneumatic**; those with liquids such as water or (much more often) special oils are called **hydraulic**. You can find out more about this on page 26.

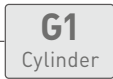


WHAT'S HAPPENING?

— The force with which you push in on the piston of the G1 cylinder is transmitted from the water or air to the piston of the G3 cylinder. However, some of the force is lost in the air-filled system because the air compresses. Since the **compressibility** of water is lower, the hydraulic cylinders in your cyborg hand are filled with water to make it more powerful.

CONNECT G1 TO G3

1



Cup of
water

1 Pull the piston outward.



Water

2 Push the piston fully into the cylinder.



3 Repeat step 1 to fill the cylinder completely with water.



2



Tube
12 cm

3



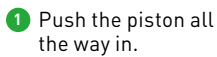
Tube
12 cm

Fill the cylinder and tube completely with water.



Water

4



G3
Cylinder



G1
Cylinder

x3

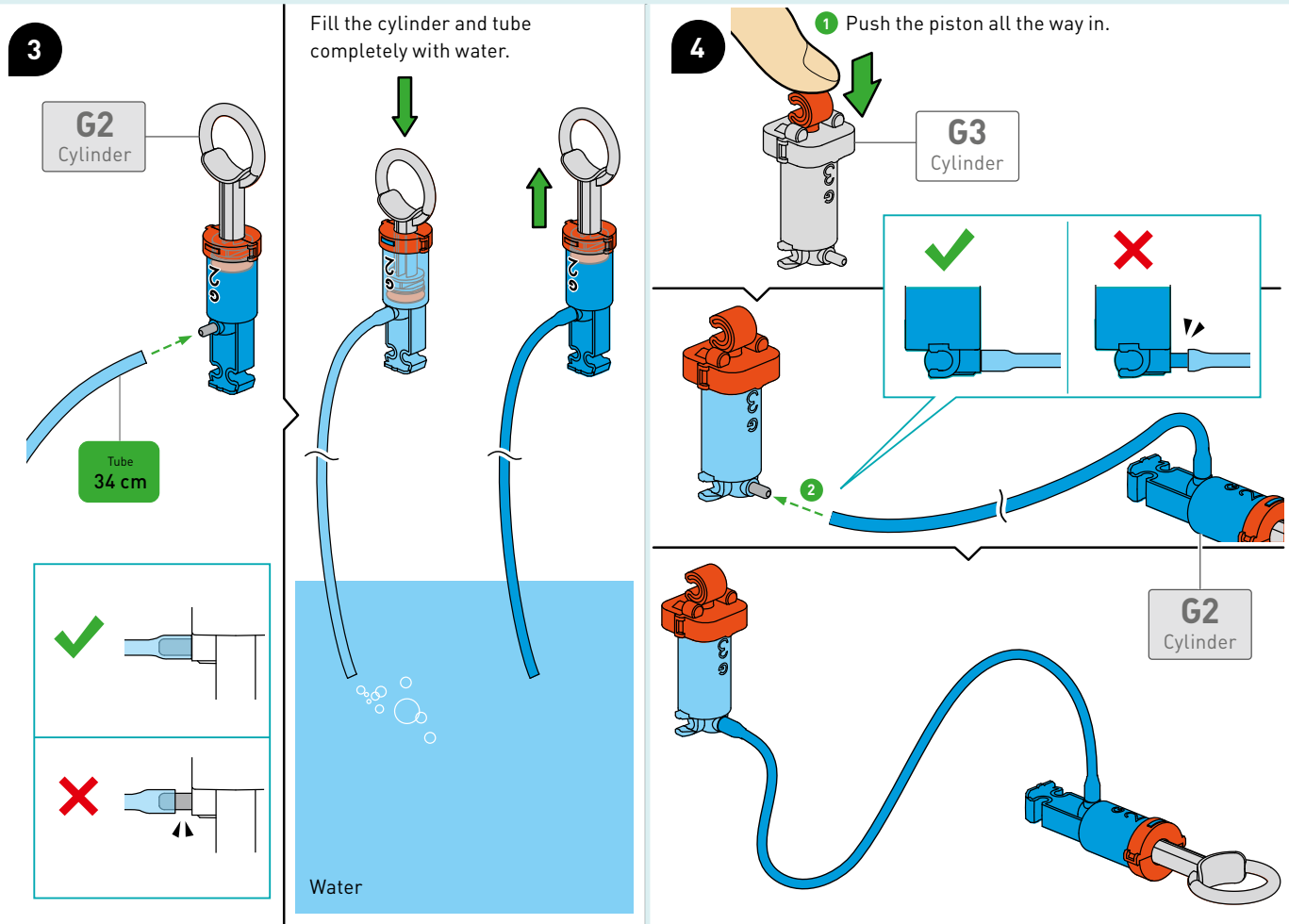
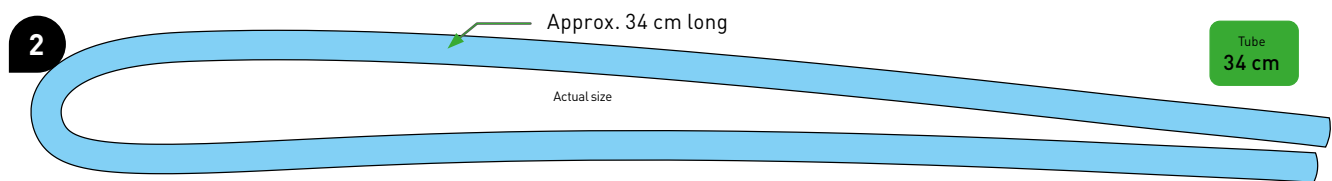
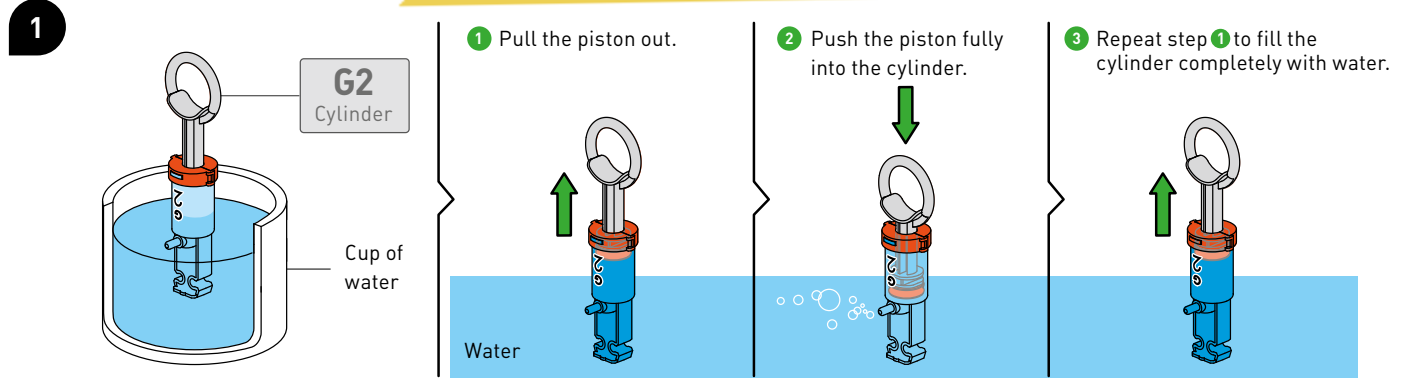
Hydraulic system A



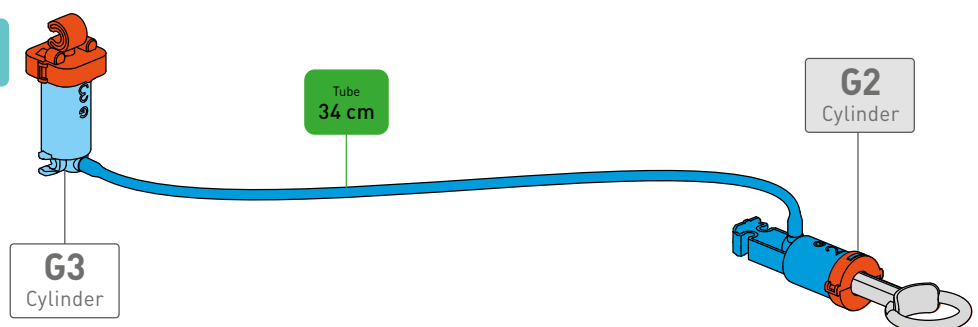
G1
Cylinder

G3 Cylinder

CONNECT G2 TO G3



Hydraulic system B





CHECK IT OUT

Pneumatics and hydraulics

— Pneumatic and hydraulic systems are used in many different types of modern-day machines. They are used when power must be transferred from one location to another. Both systems have specific advantages and disadvantages and are used depending on the application.

— I have hydraulic systems on board.

Hydraulics

— If very large forces have to be transmitted, hydraulic systems are usually used. These also work with cylinders, pistons, and valves, like in the cyborg hand, but they mostly use special hydraulic oils as a medium, instead of water, because these oils can be put under high pressures. Such systems can be found in excavators, some elevators, numerous commercial vehicles, and in the braking systems in cars.

Computer Control

Larger hydraulic systems are controlled with special computers. A sophisticated program evaluates signals coming from the various sensors in the system and activates valves and electric motors at the right moments.

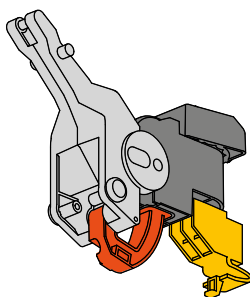
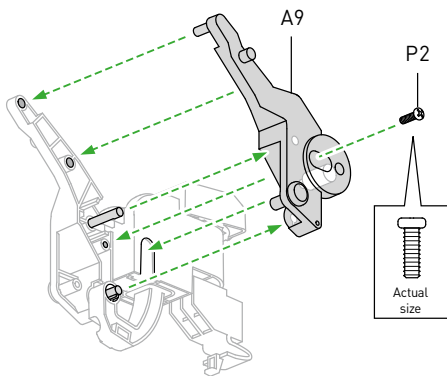
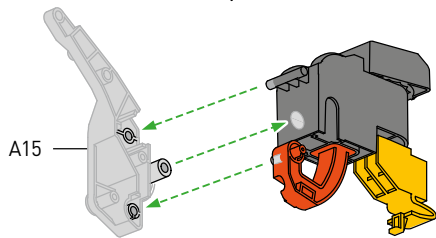
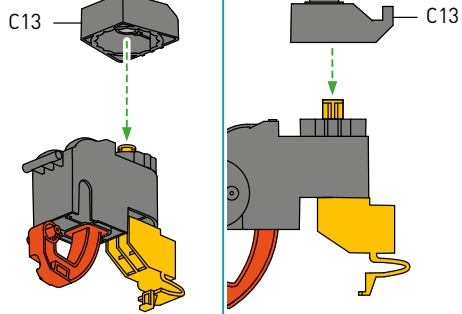
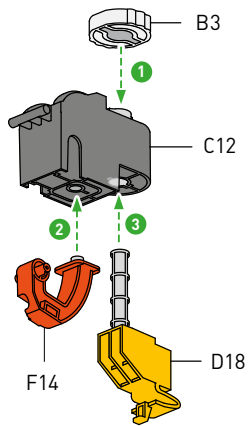
PNEUMATIC SYSTEMS

WORK WITH COMPRESSED AIR, GENERATED BY COMPRESSORS. ELECTRICALLY CONTROLLED VALVES DIRECT THE COMPRESSED AIR INTO CYLINDERS WITH PISTONS IN THEM. THE PISTONS THEN PERFORM THE DESIRED MOVEMENTS. HOWEVER, THESE SYSTEMS CANNOT EXERT EXCESSIVE FORCES, SINCE AIR CAN BE COMPRESSED. THE ADVANTAGE OF PNEUMATICS IS THAT VERY HIGH OPERATING SPEEDS CAN BE ACHIEVED AND COMPRESSED AIR CAN BE CONTROLLED VERY EASILY.

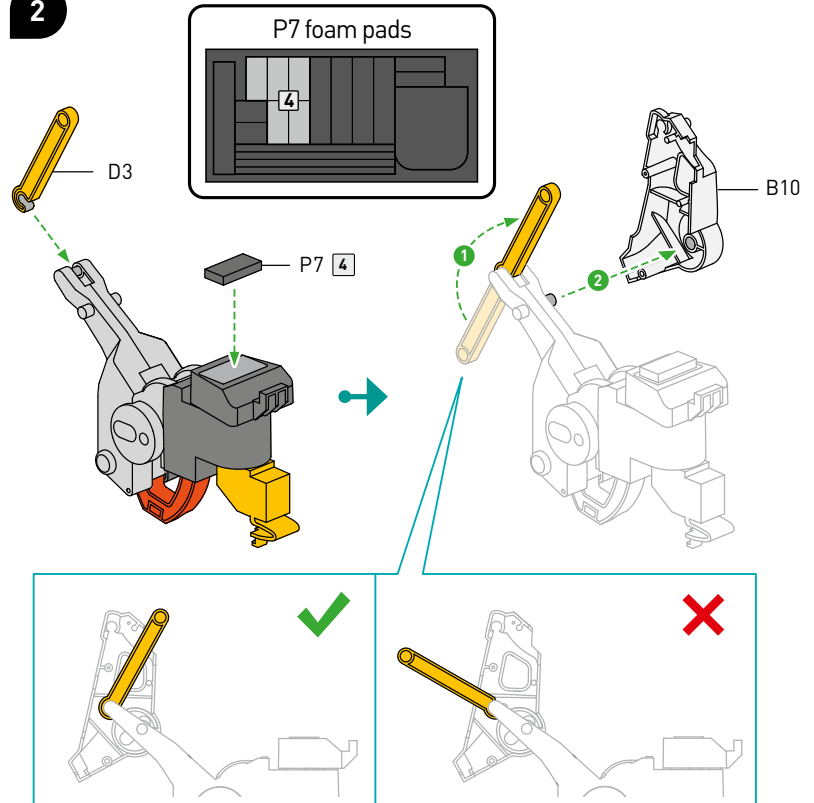


ASSEMBLING THE THUMB

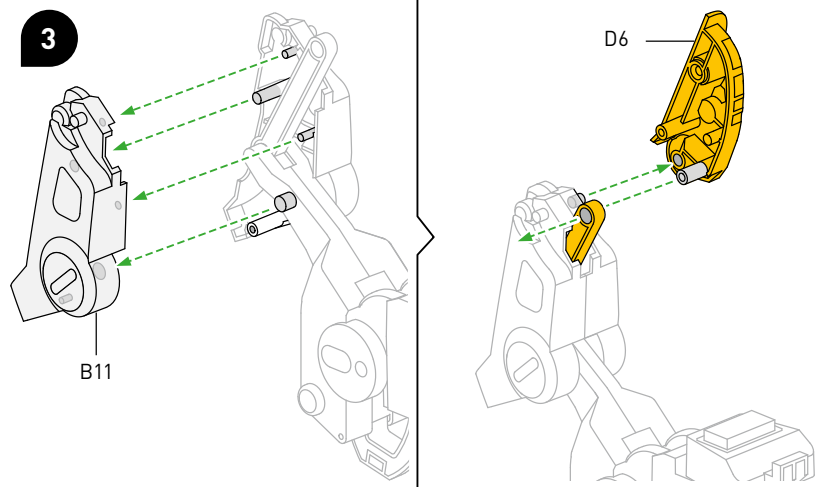
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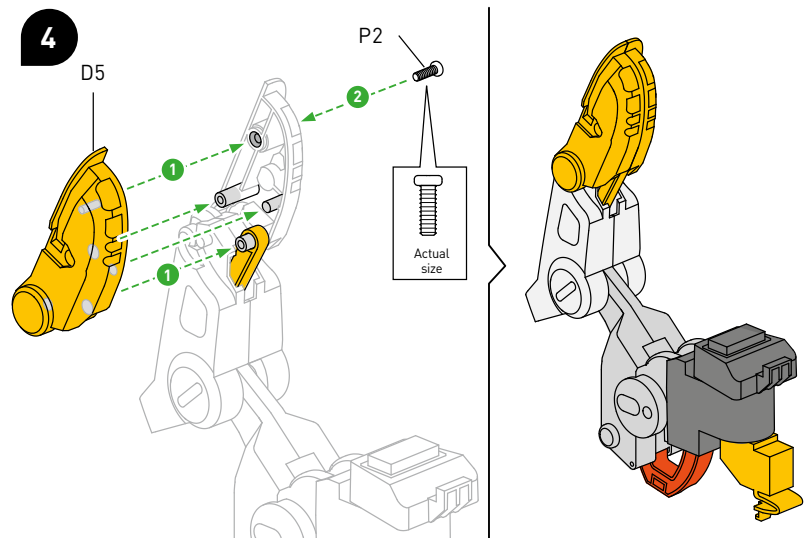
2



3



4





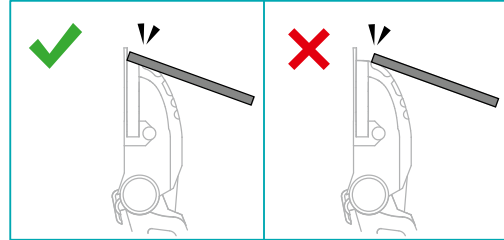
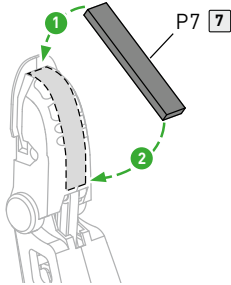
ASSEMBLING THE THUMB

5

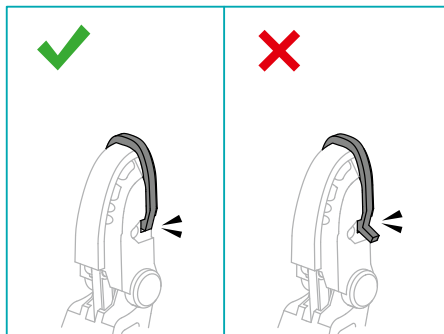
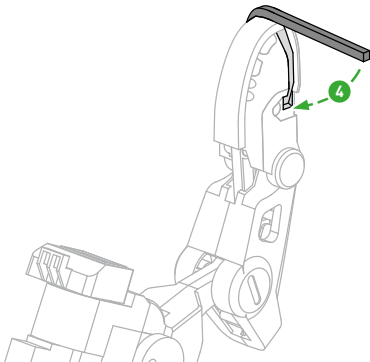
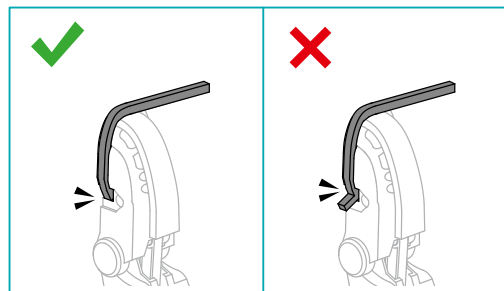
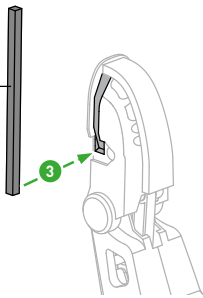
P7 foam pads

7

8



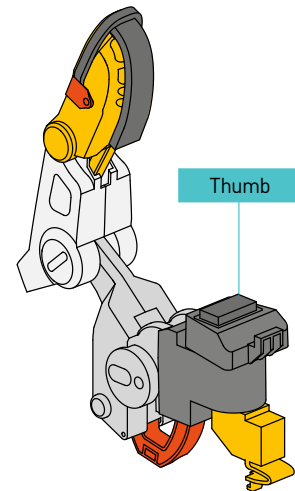
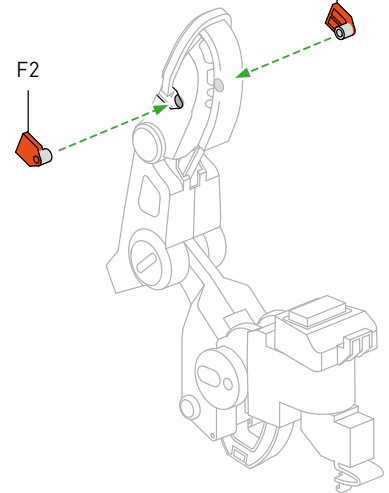
P7 6



6

F2

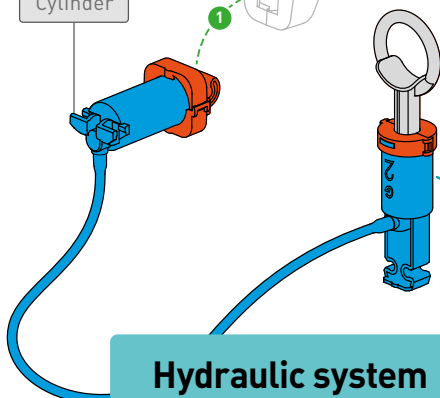
F2



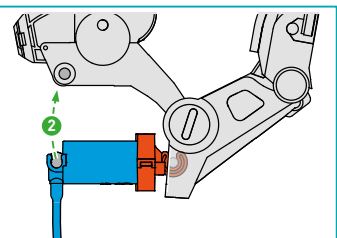
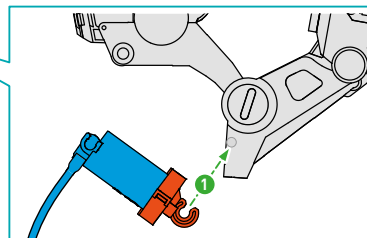
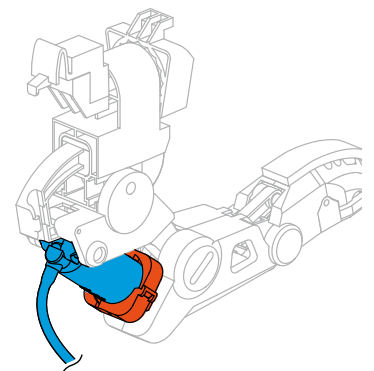
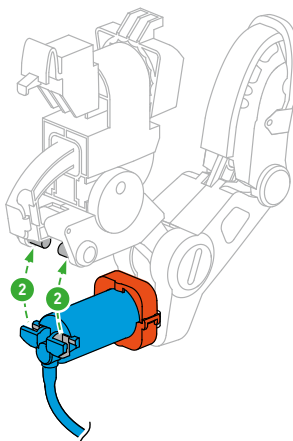
7

Thumb

G3
Cylinder

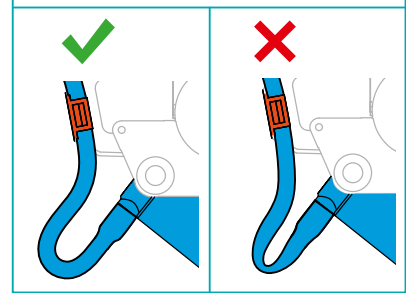
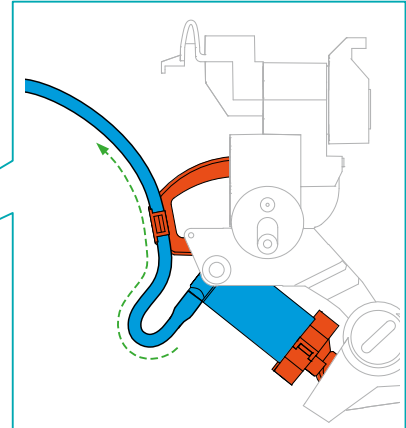
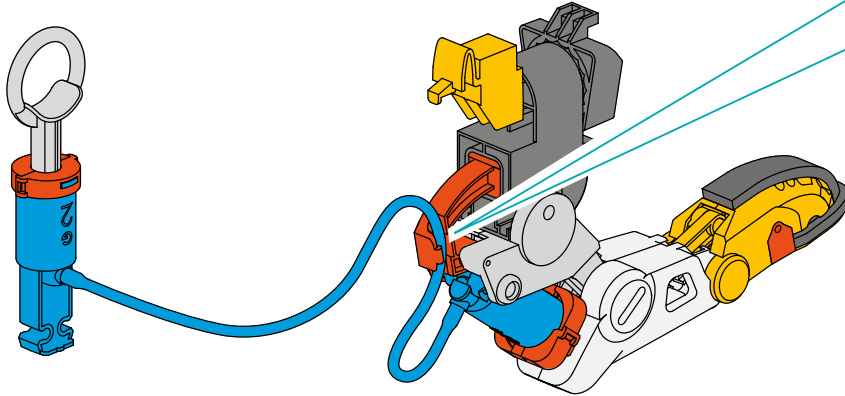


Hydraulic system B



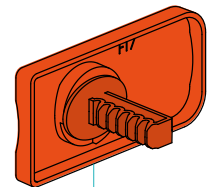
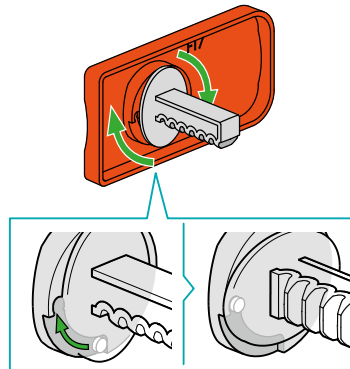
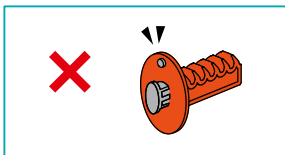
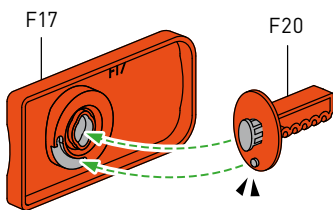


8



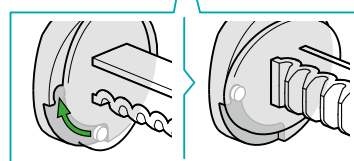
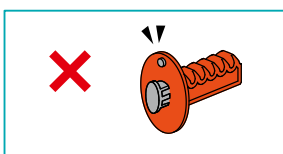
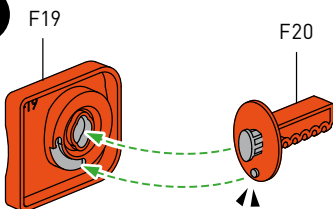
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ASSEMBLE THE RAILS

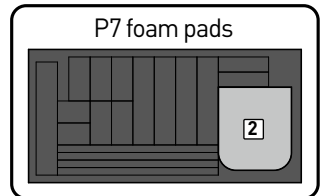
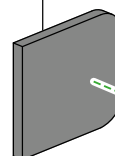


Large rail

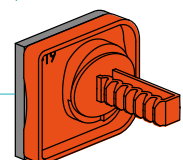
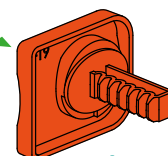
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P7 2



P7 foam pads

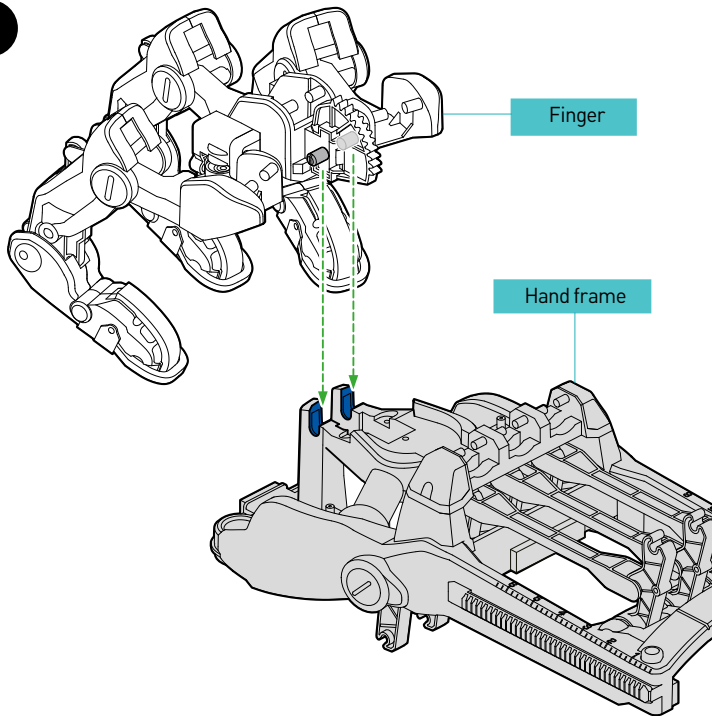


Small rail

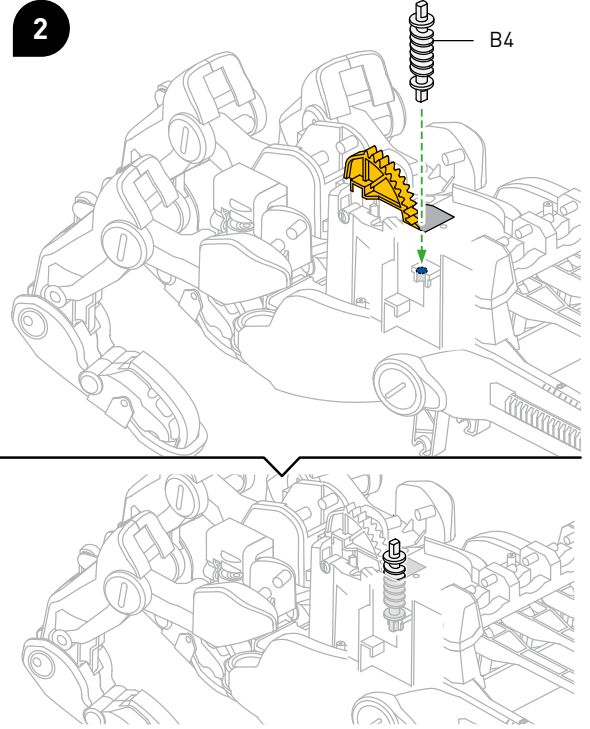


ASSEMBLING THE CYBORG HAND

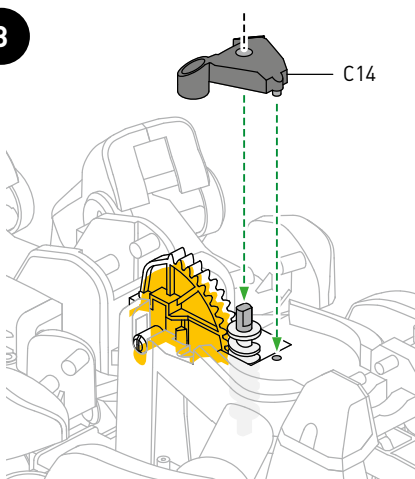
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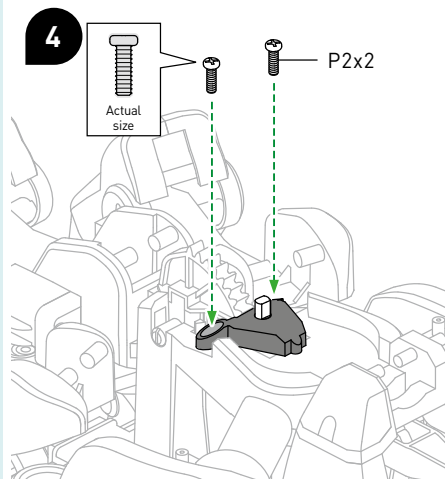
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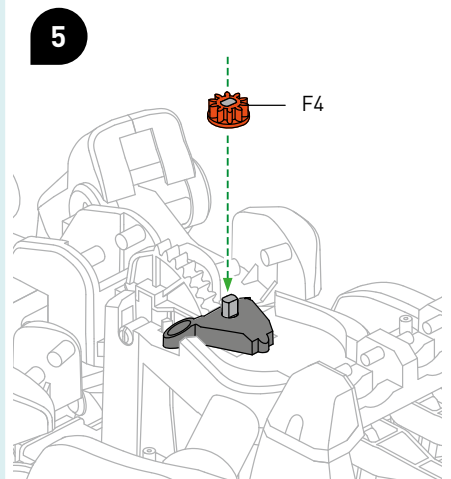
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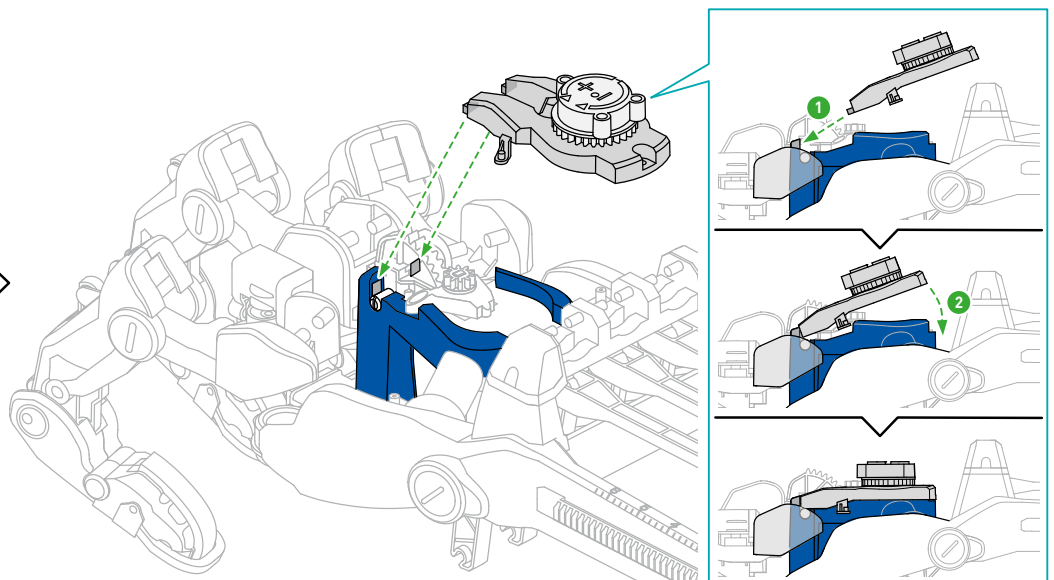
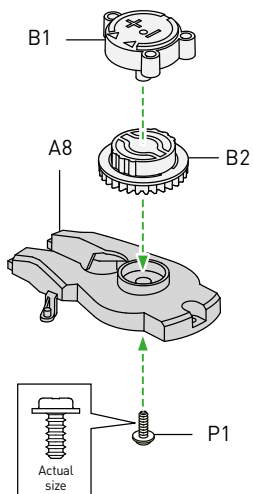
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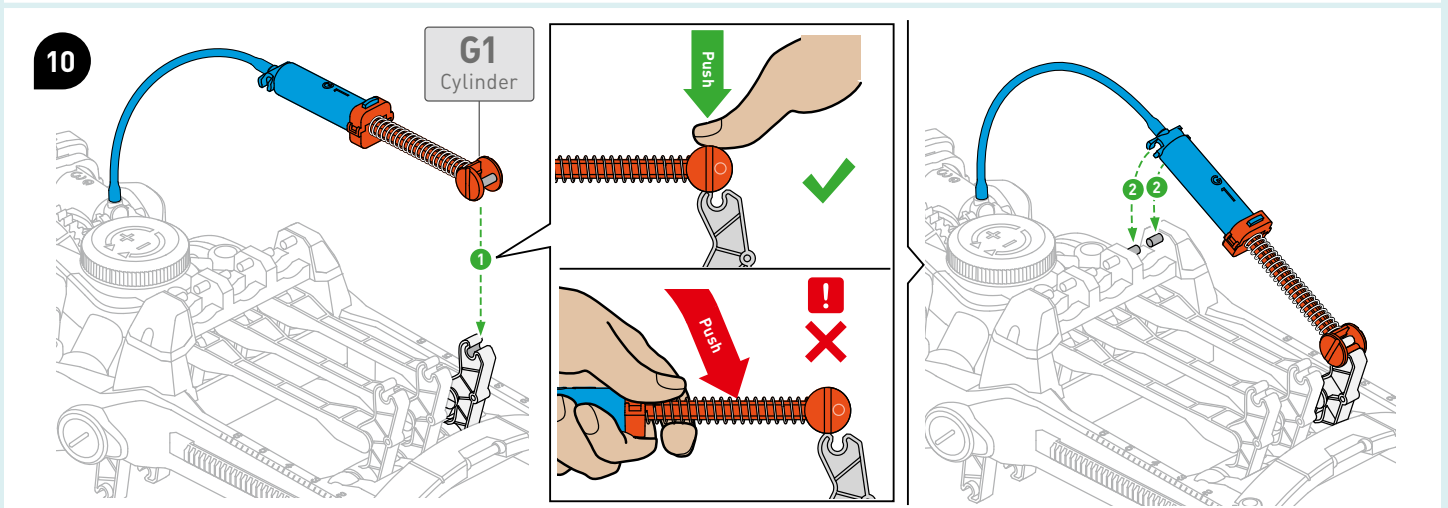
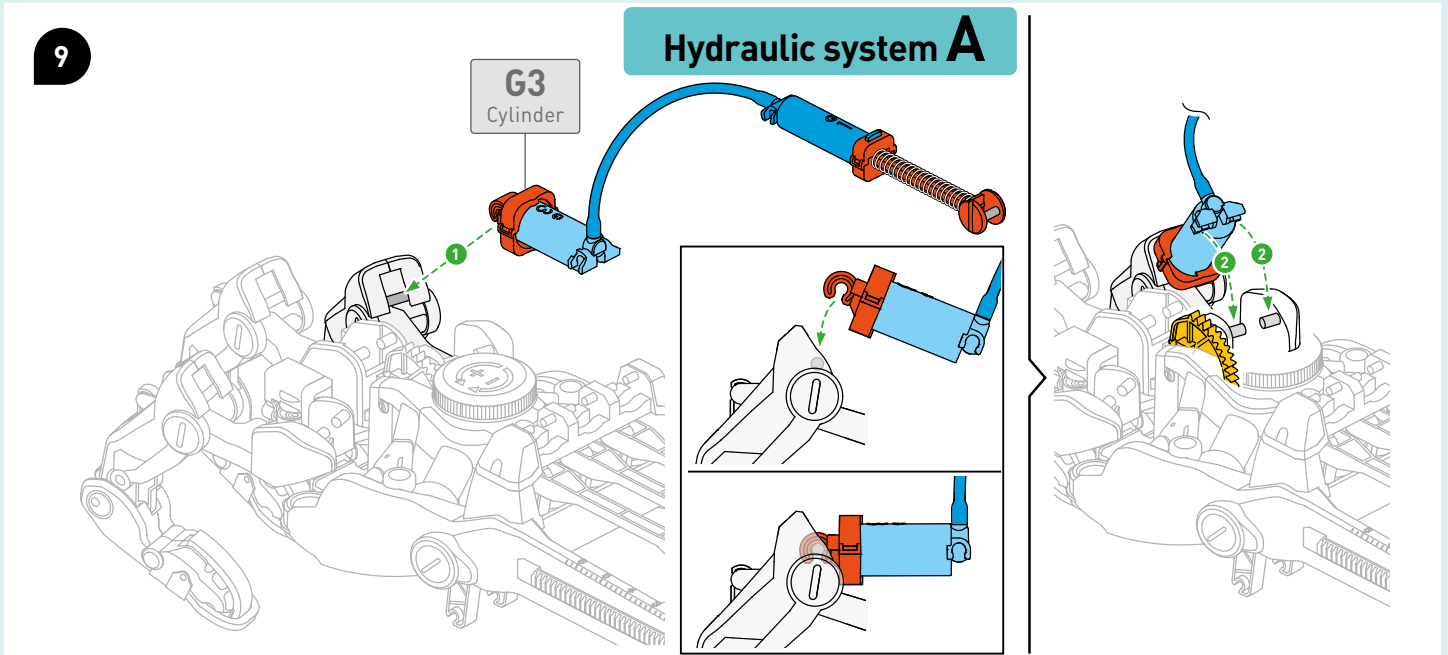
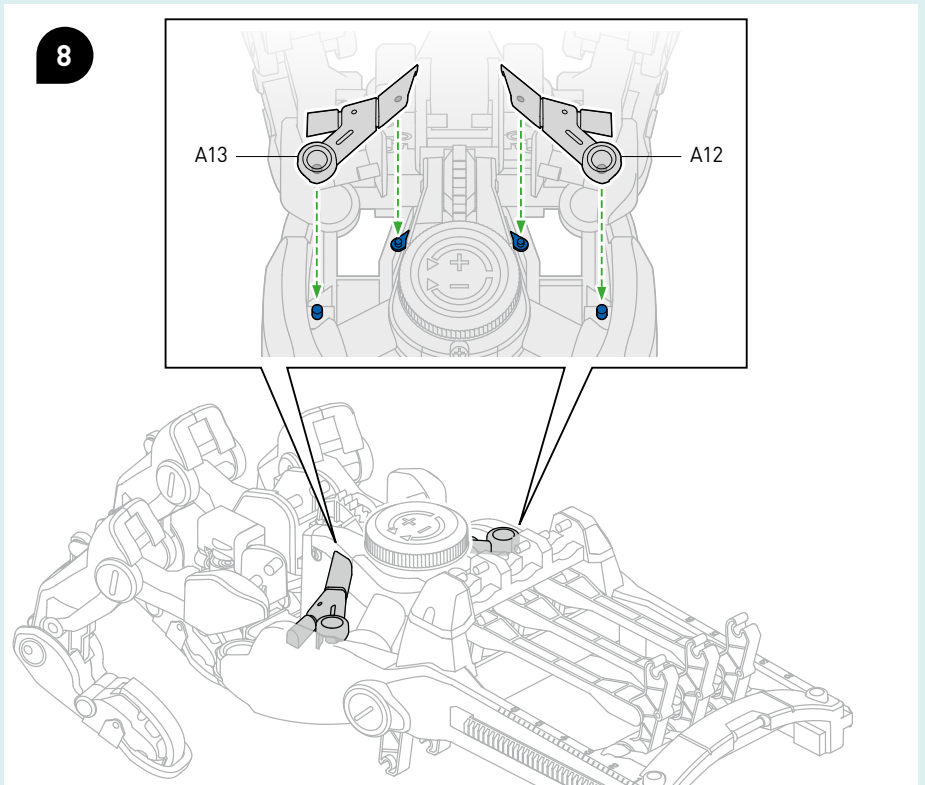
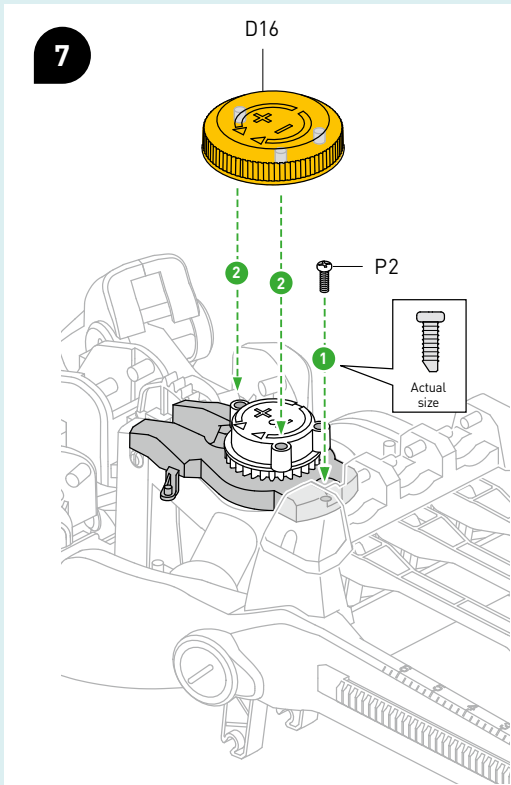


5



6





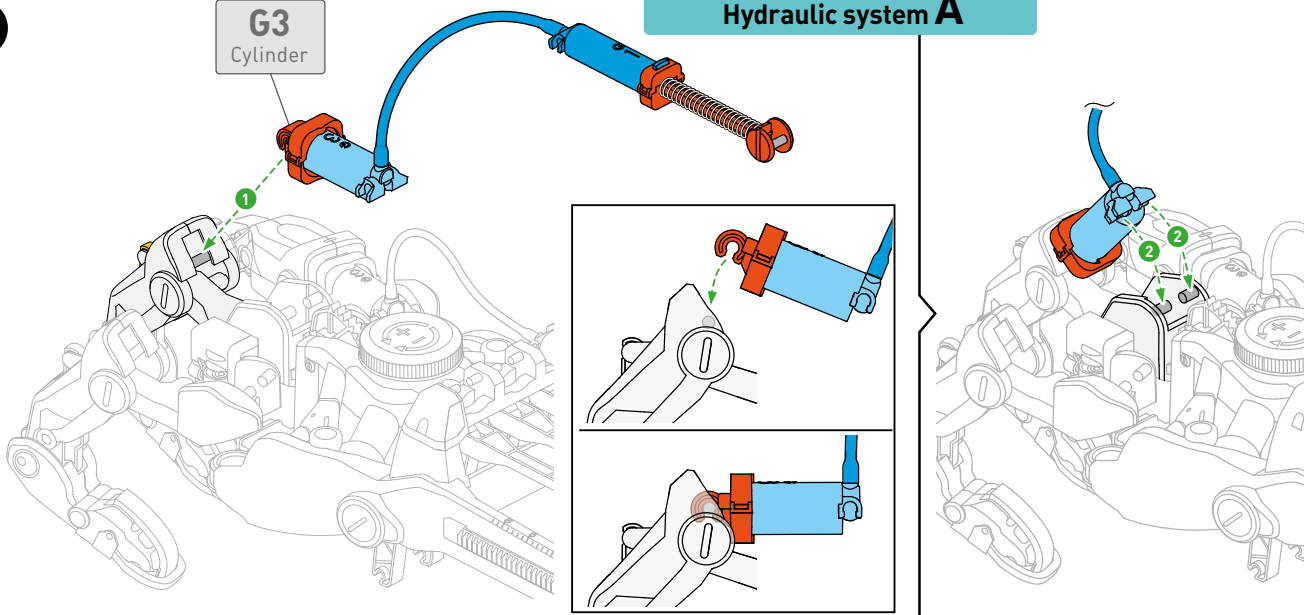


ASSEMBLING THE CYBORG HAND

11

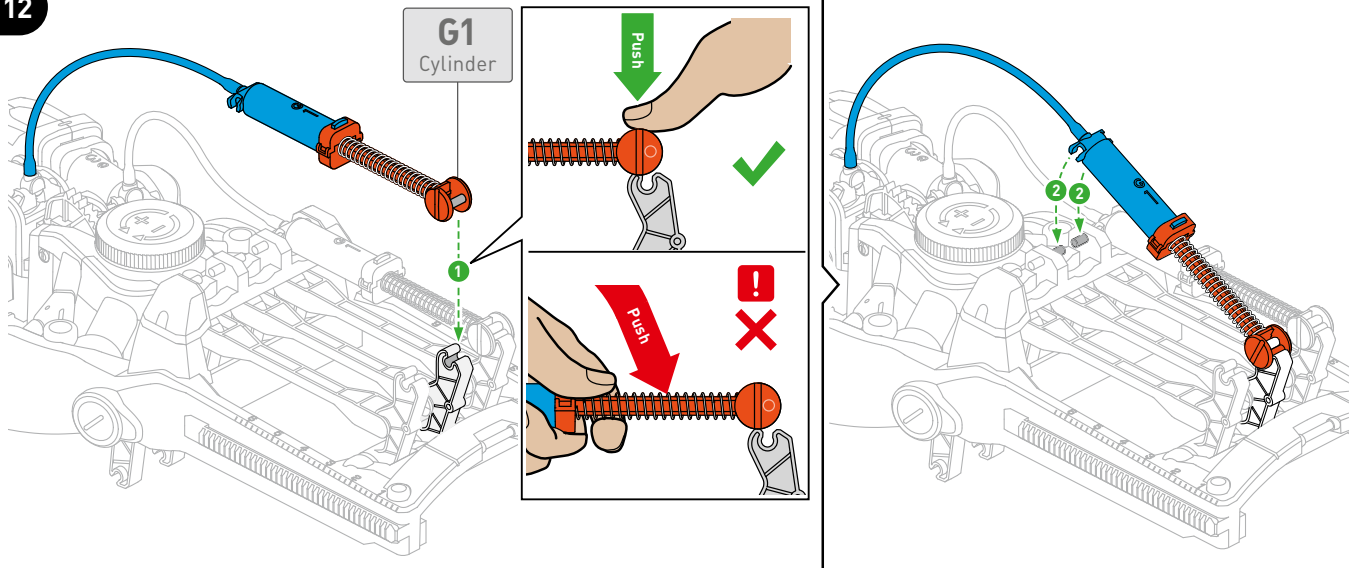
G3
Cylinder

Hydraulic system A



12

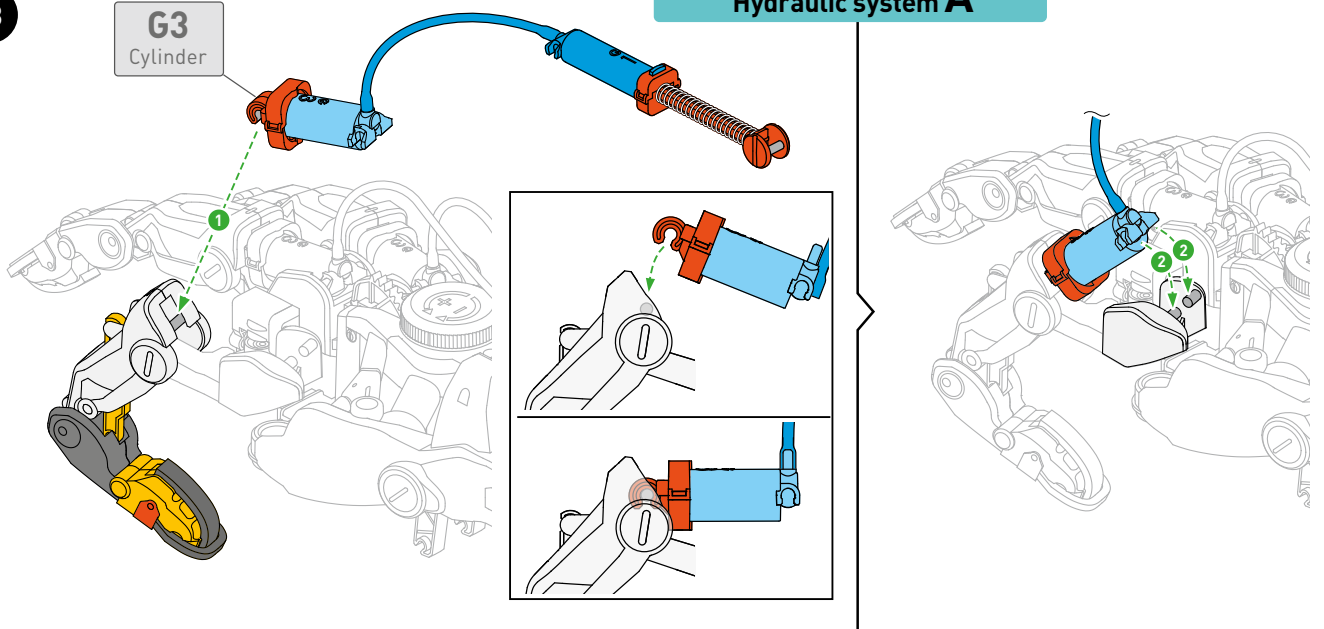
G1
Cylinder



13

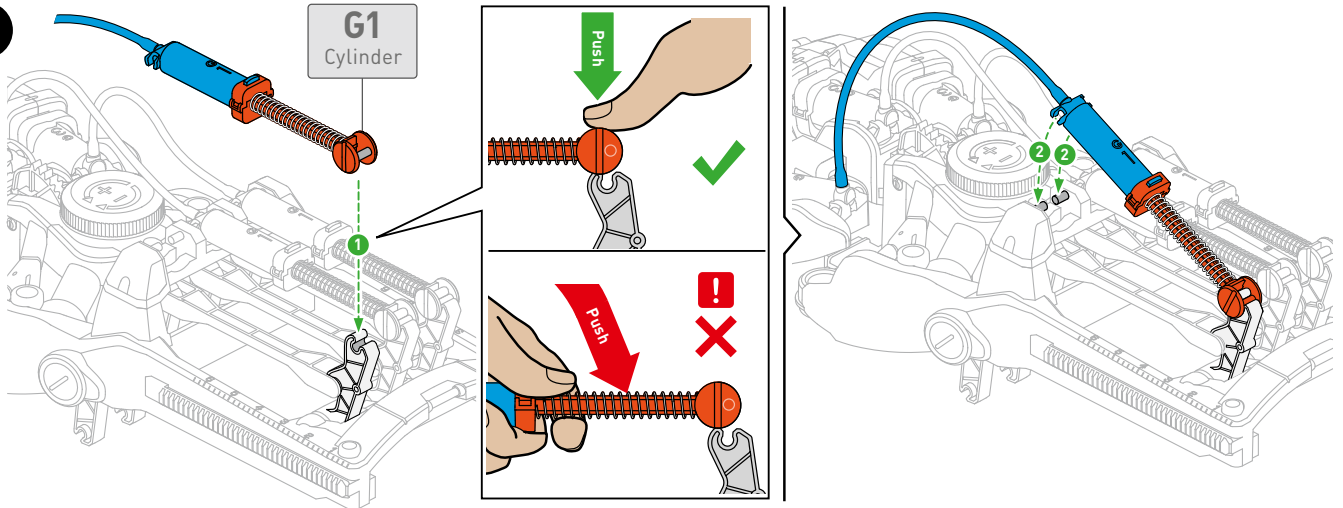
G3
Cylinder

Hydraulic system A

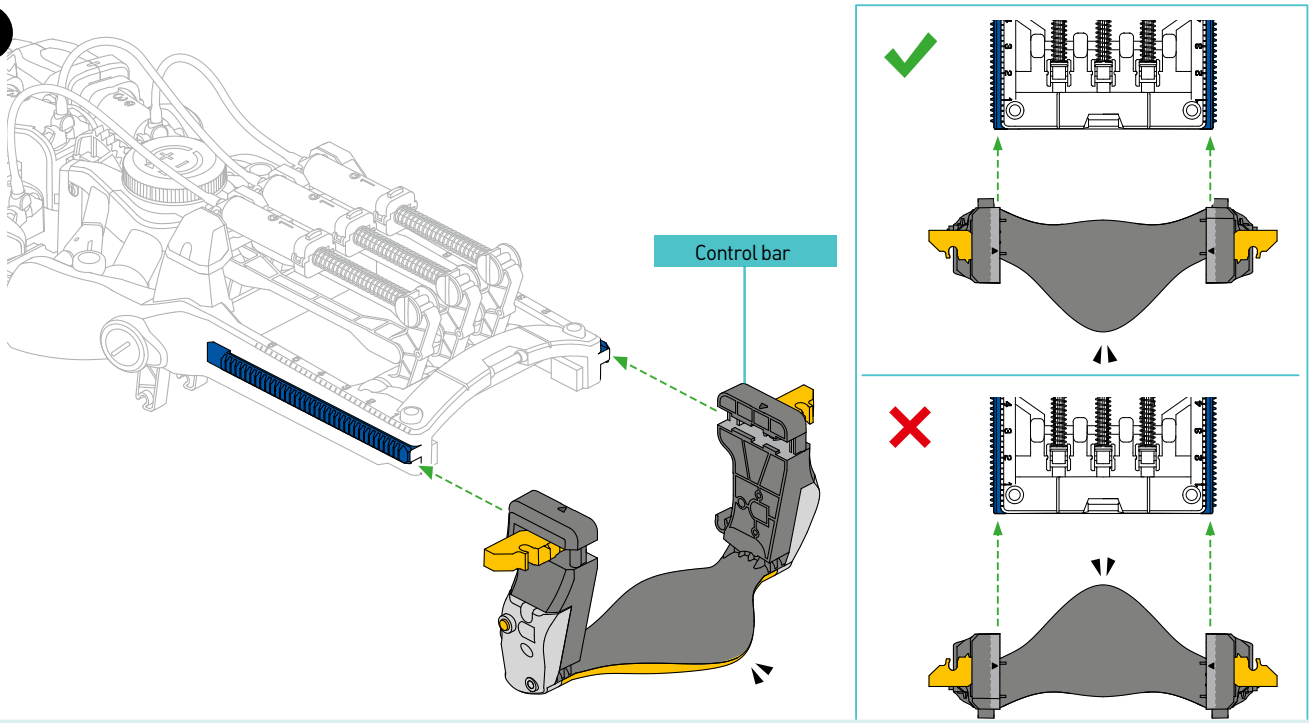




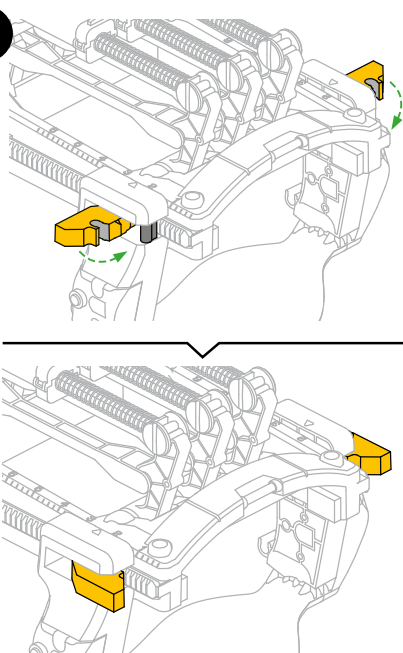
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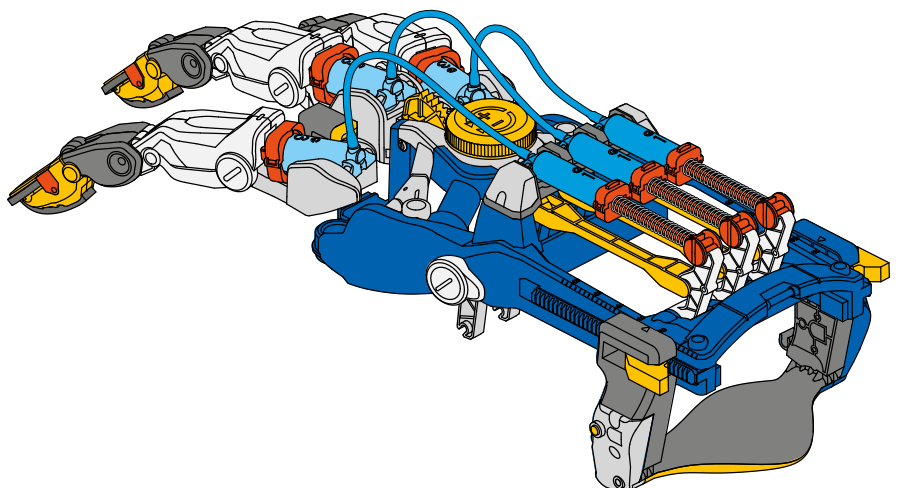
15



16



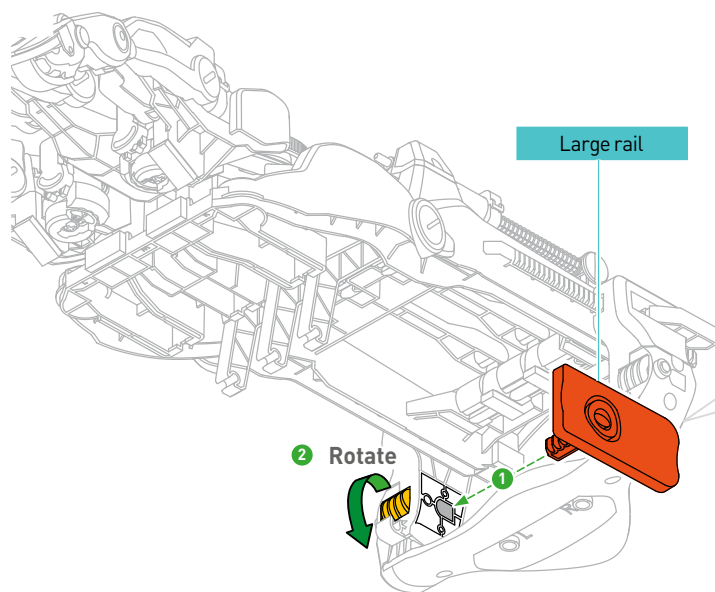
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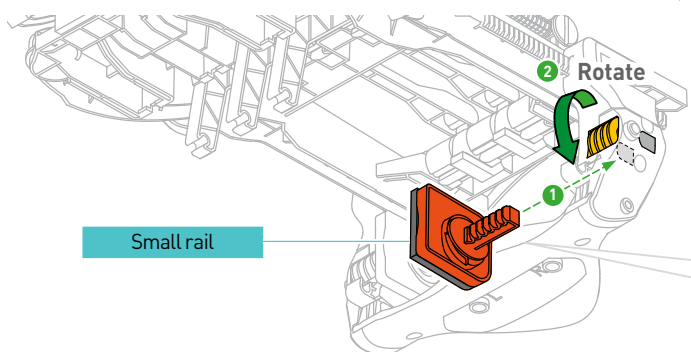
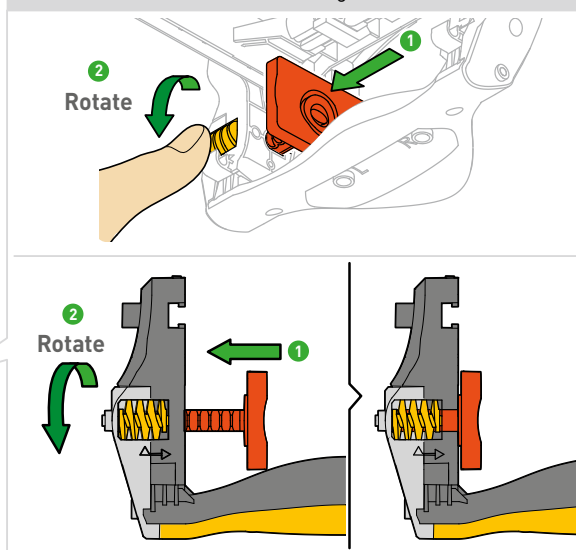
RIGHT-HANDED CONFIGURATION

— For the left-handed configuration, skip ahead to page 36.

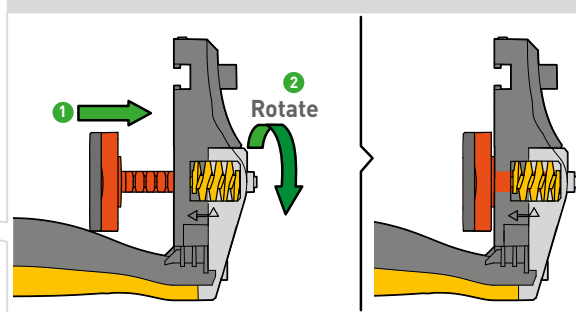
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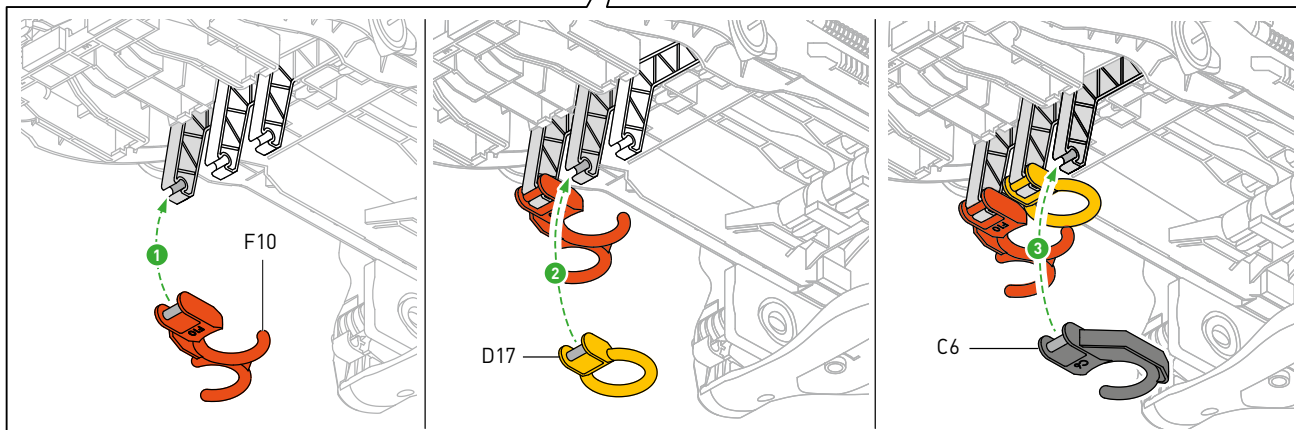
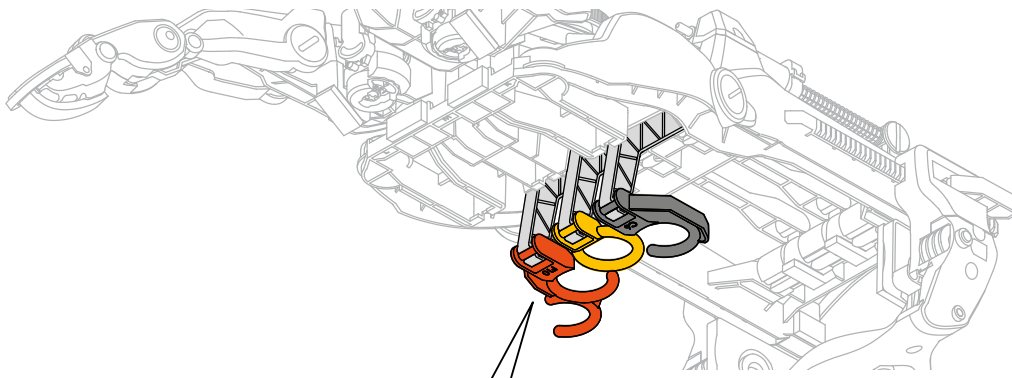
Attach the large rail



Attach the small rail

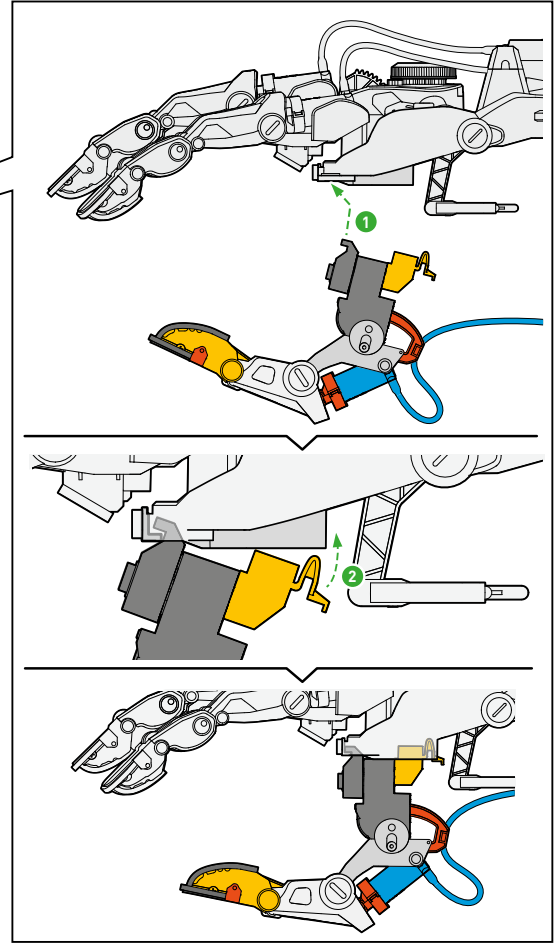
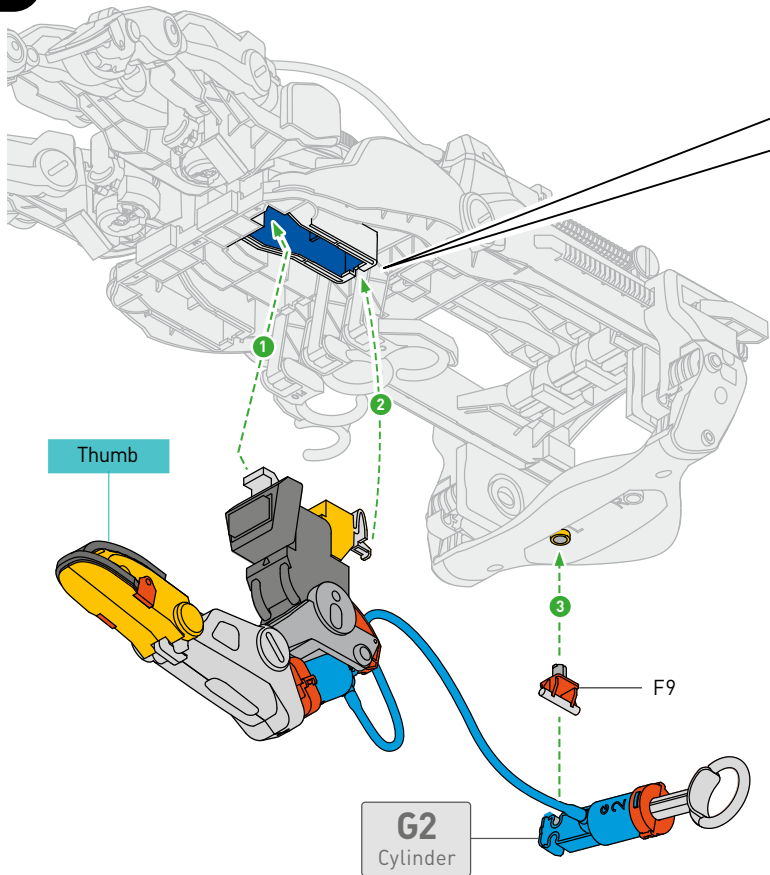


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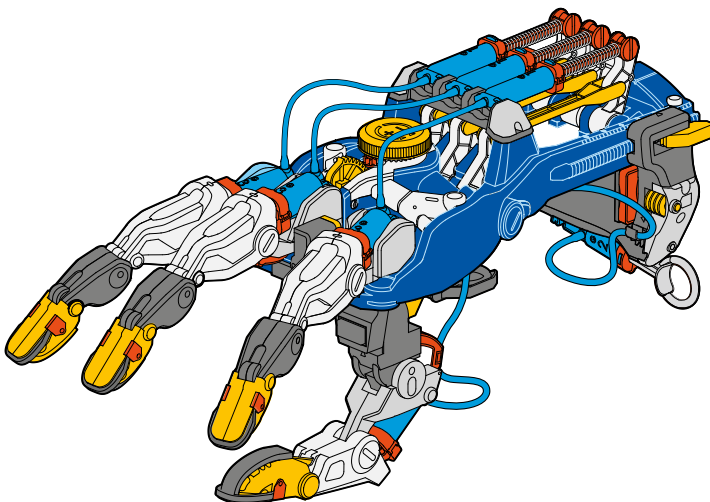
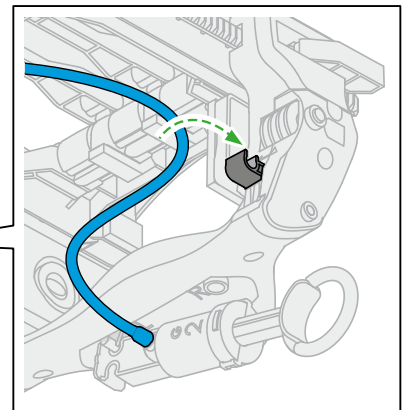
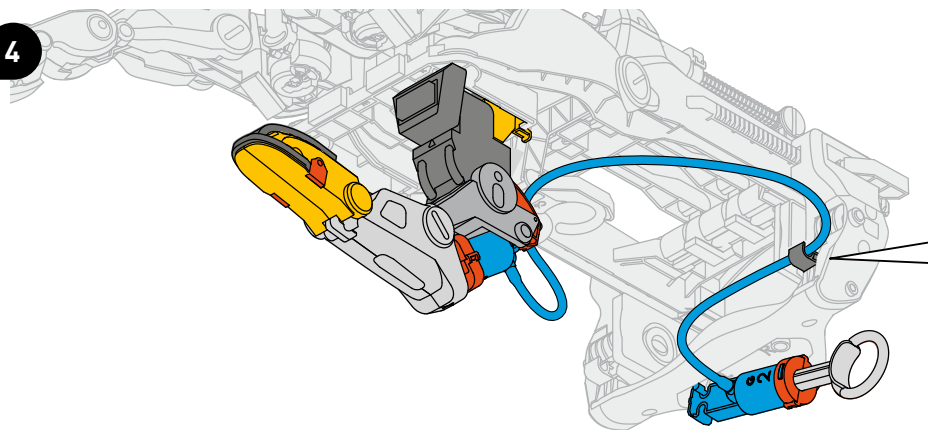




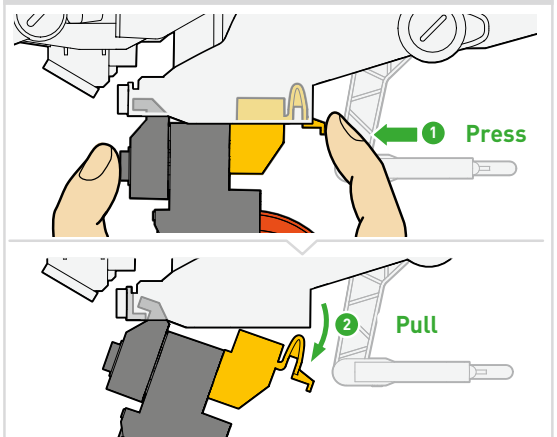
3



4



If you ever want to remove the thumb, here's how:

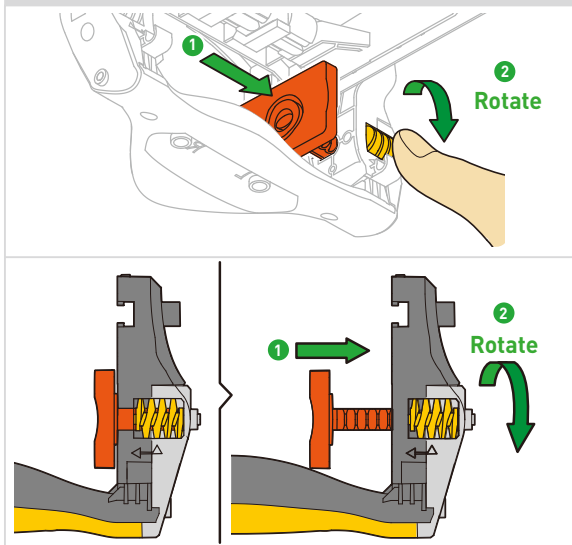


LEFT-HANDED CONFIGURATION

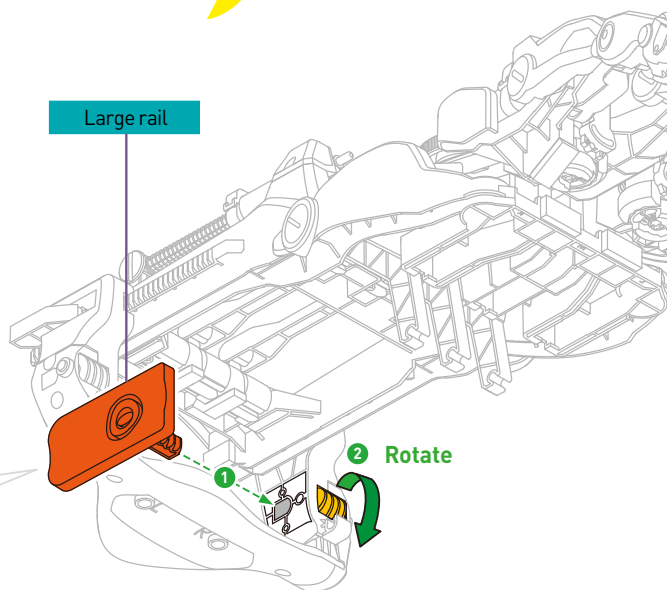
— For the right-handed configuration, go back to page 34.

1

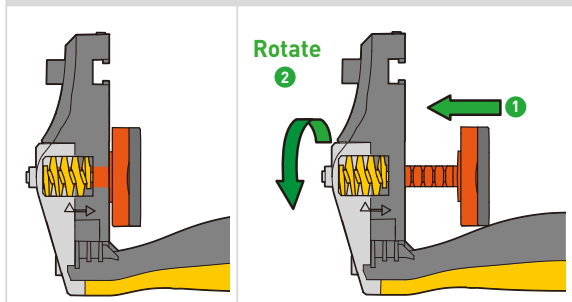
Attach the large rail



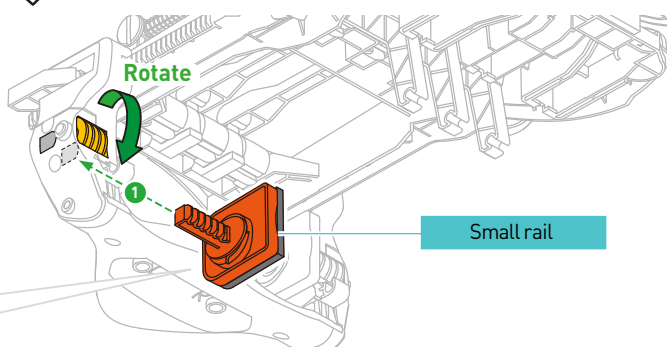
Large rail



Attach the small rail

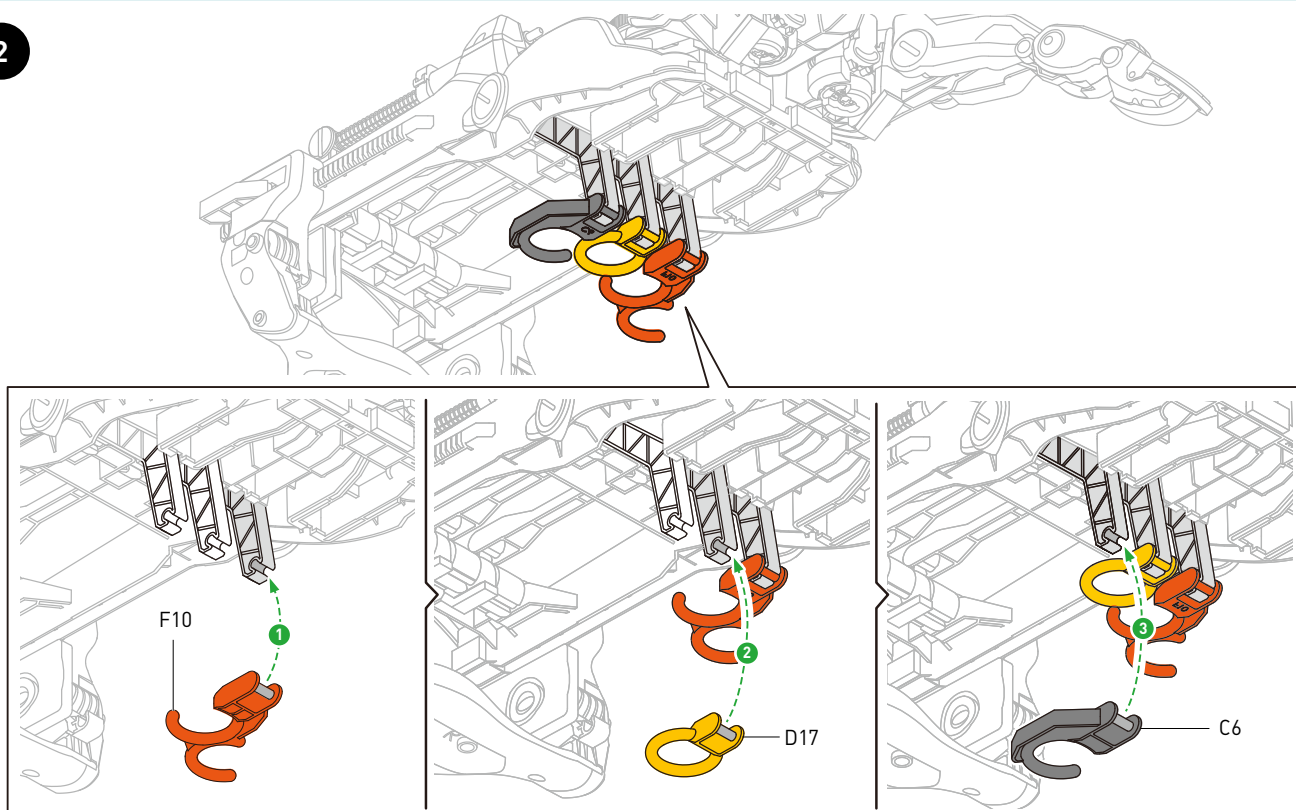


Rotate



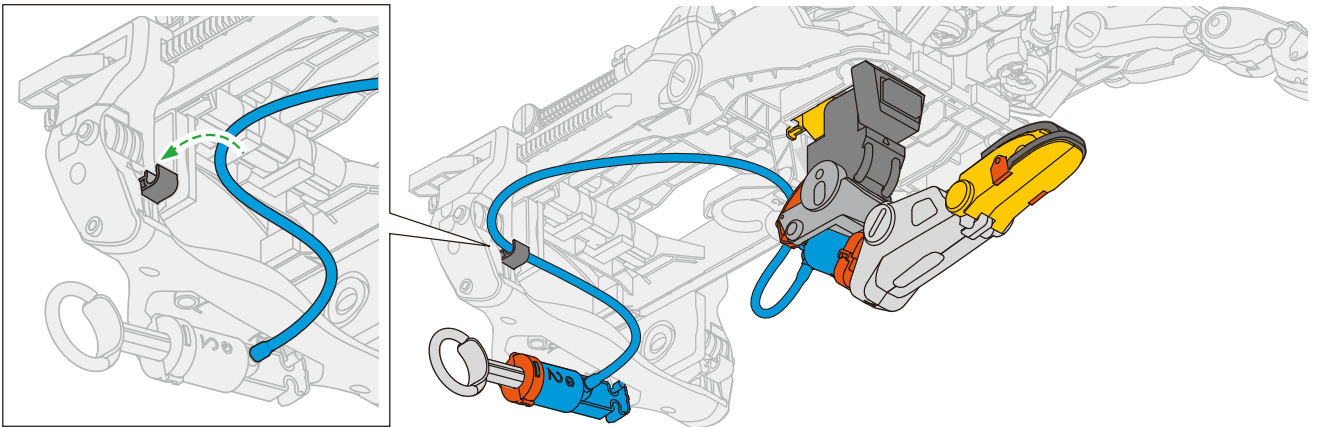
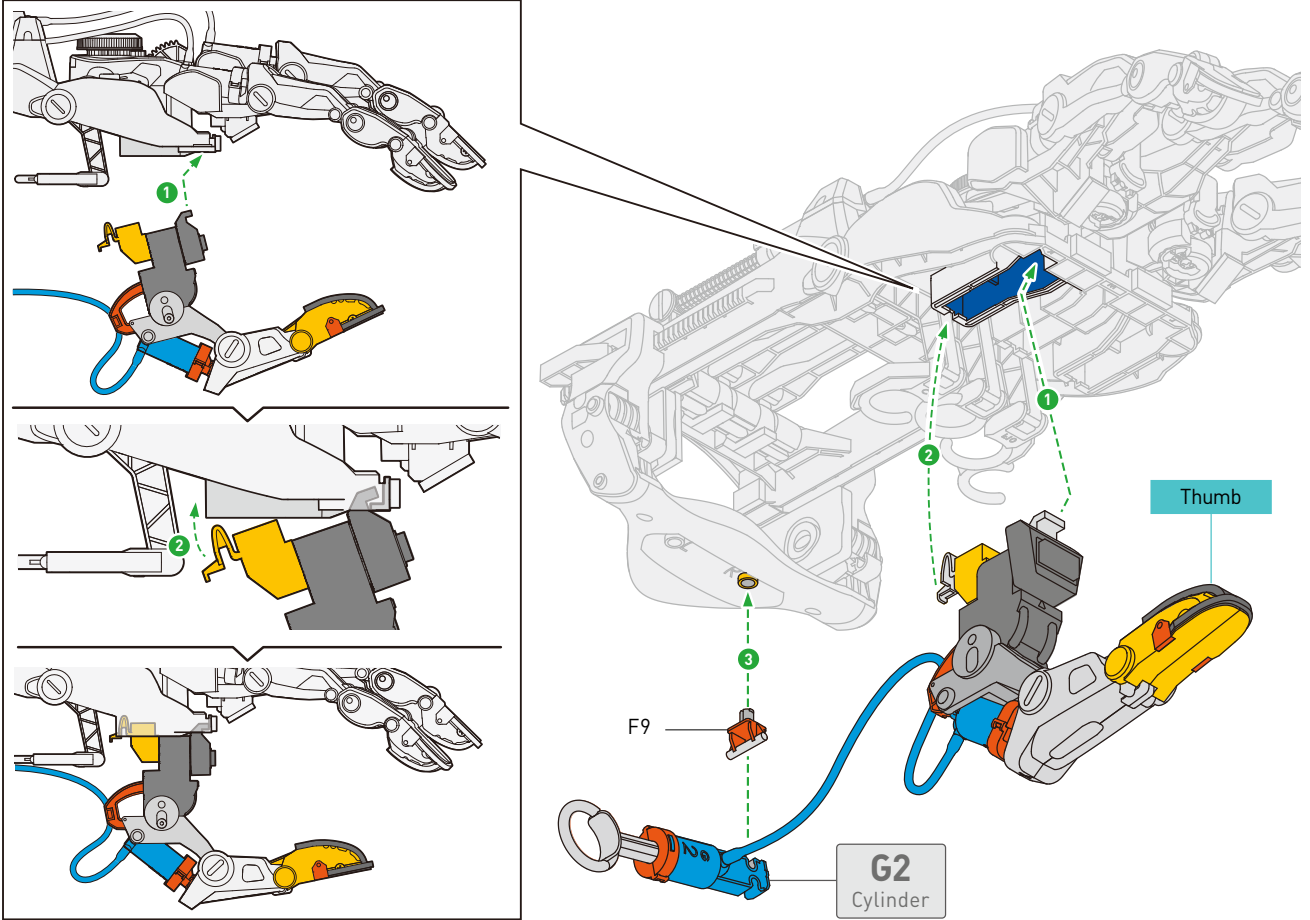
Small rail

2

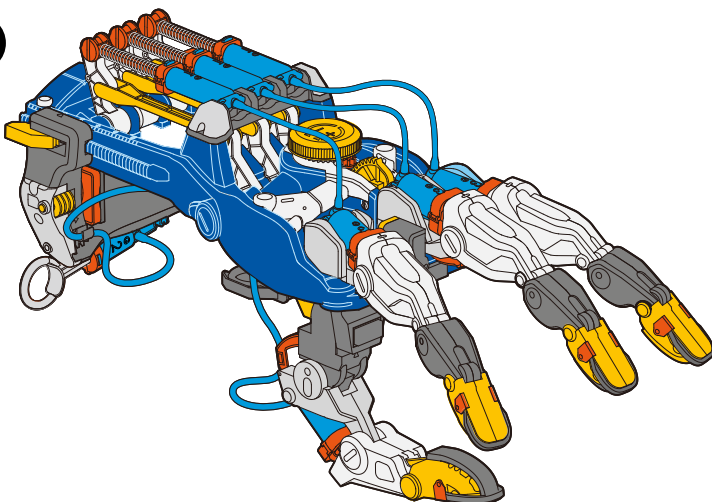




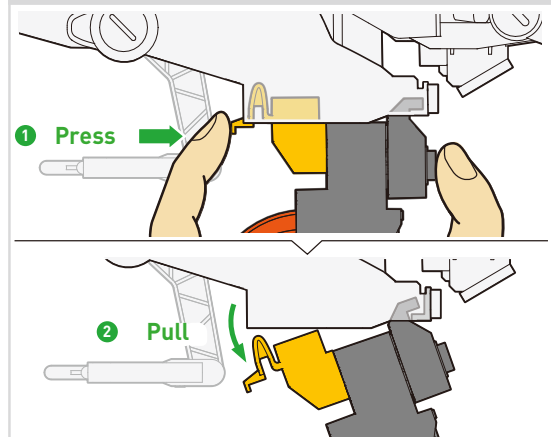
3



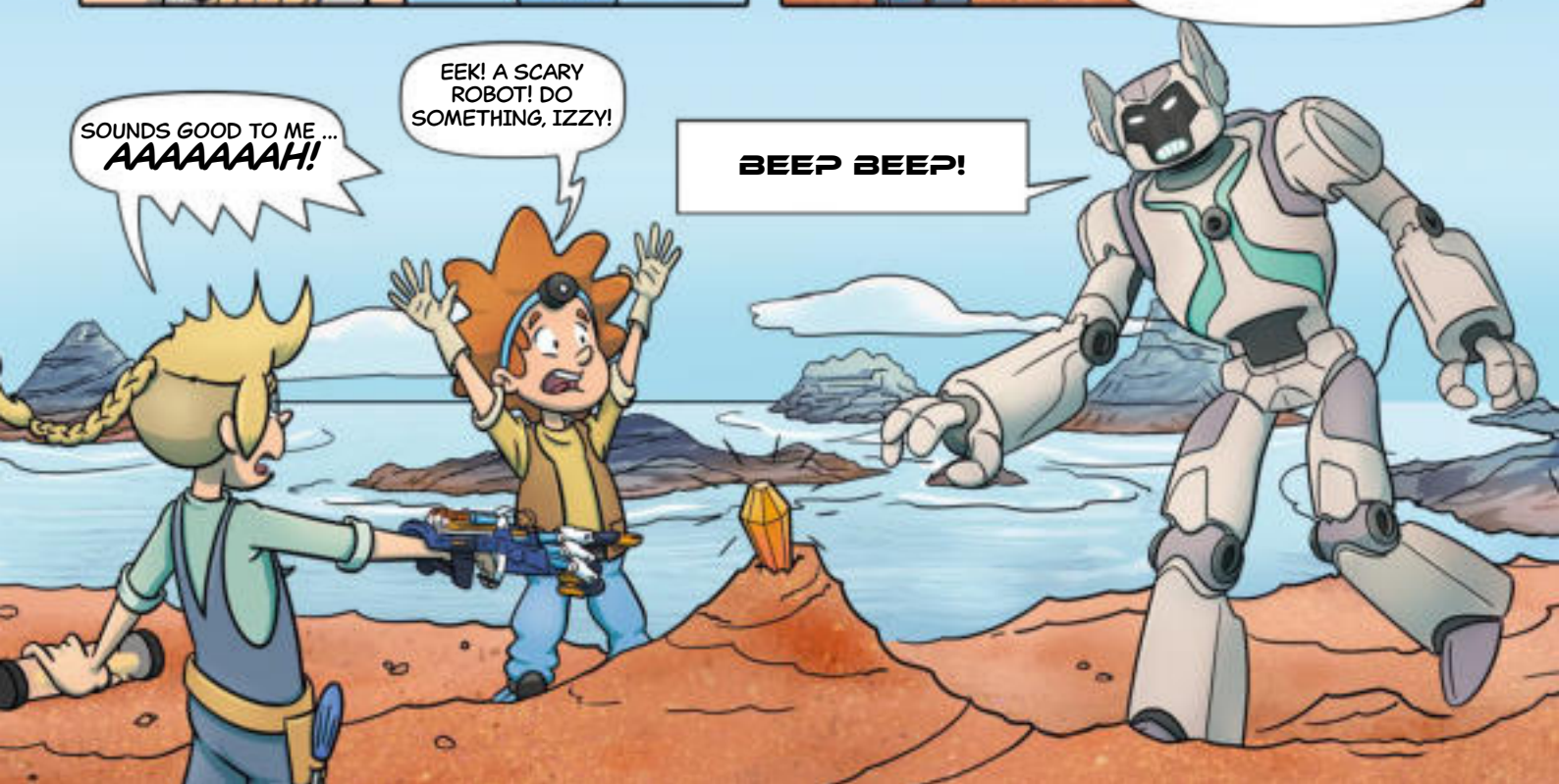
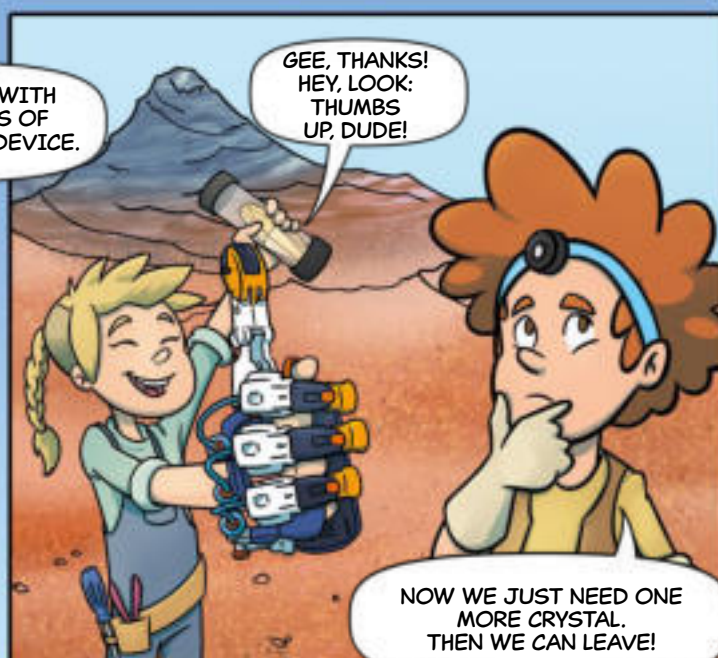
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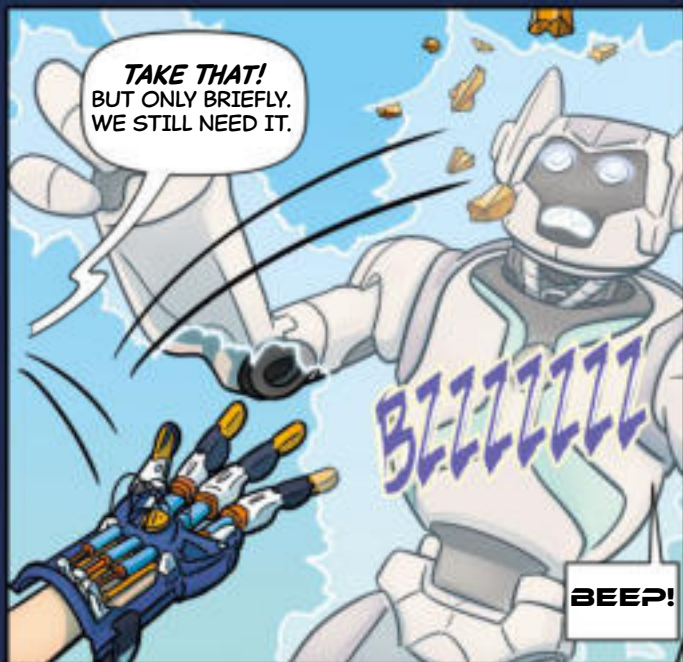


If you ever want to remove the thumb, here's how:



THE CYBORG-HAND

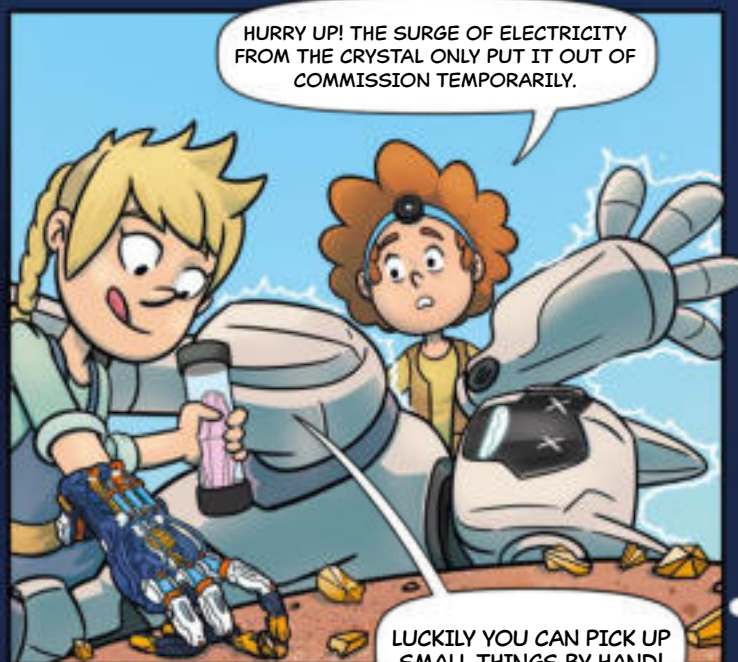




TAKE THAT!
BUT ONLY BRIEFLY.
WE STILL NEED IT.

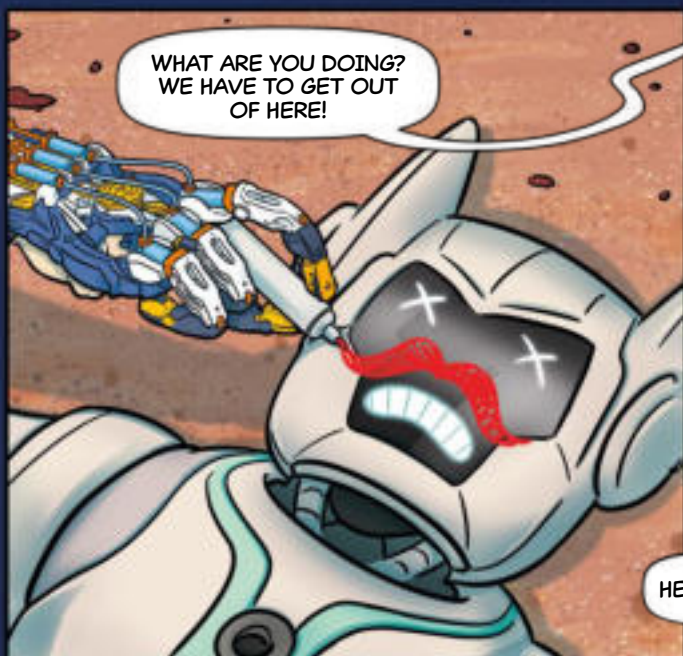
BZZZZZZZZ

BEEP!

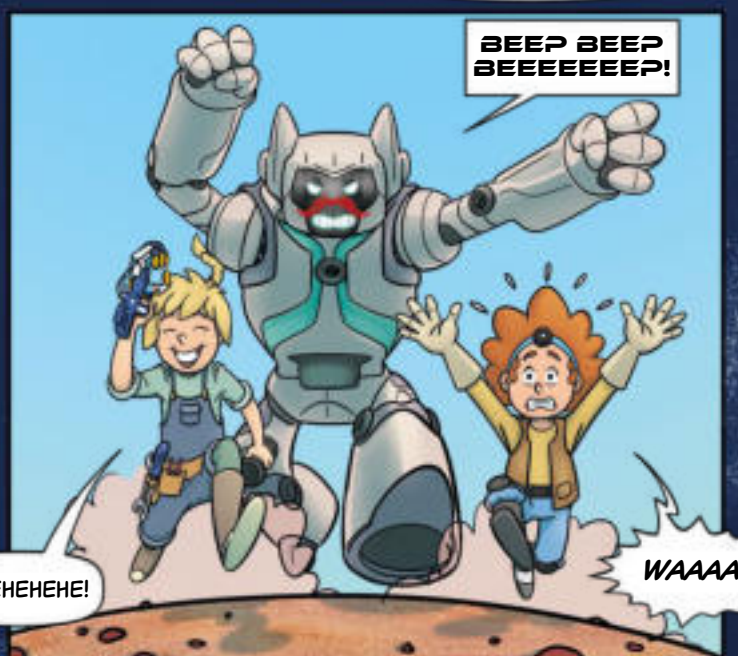


HURRY UP! THE SURGE OF ELECTRICITY
FROM THE CRYSTAL ONLY PUT IT OUT OF
COMMISSION TEMPORARILY.

LUCKILY YOU CAN PICK UP
SMALL THINGS BY HAND!



WHAT ARE YOU DOING?
WE HAVE TO GET OUT
OF HERE!



BEEP BEEP
BEEEEEEEEEP!

HEHEHEHEHE!

WAAAA!



WOW, THAT
WAS CLOSE!

YES, BUT NOW WE HAVE
ENOUGH POWER TO FLY
STRAIGHT TO A NEW
ADVENTURE!

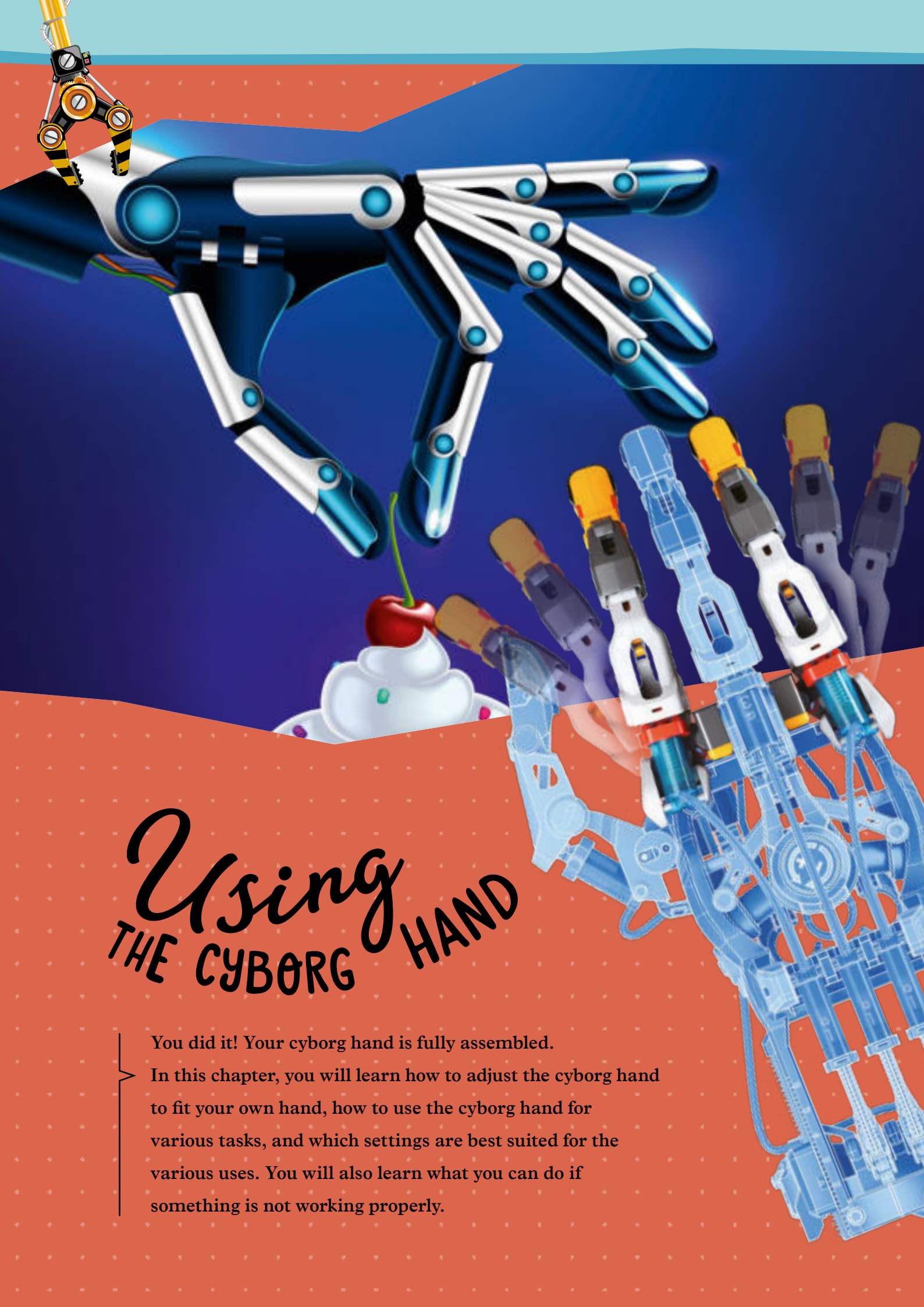
... AND HOPEFULLY
ALSO BACK HOME
AGAIN!

... AND HOPEFULLY
BACK AGAIN.

RELAX, TOM. HERE,
YOU CAN USE THE
CYBORG HAND TO
SCRATCH YOUR HEAD!

OH YES!
THAT FEELS
QUITE NICE.

ONWARD! ... TO THE
NEXT ADVENTURE!



Using THE CYBORG HAND

You did it! Your cyborg hand is fully assembled.

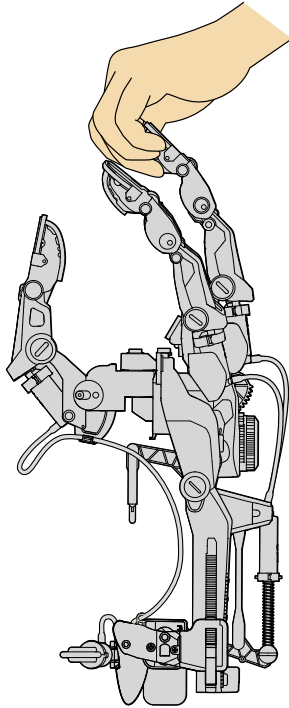
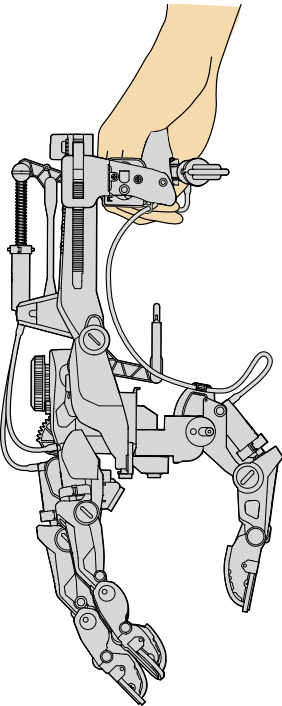
In this chapter, you will learn how to adjust the cyborg hand to fit your own hand, how to use the cyborg hand for various tasks, and which settings are best suited for the various uses. You will also learn what you can do if something is not working properly.



BASIC USAGE INSTRUCTIONS

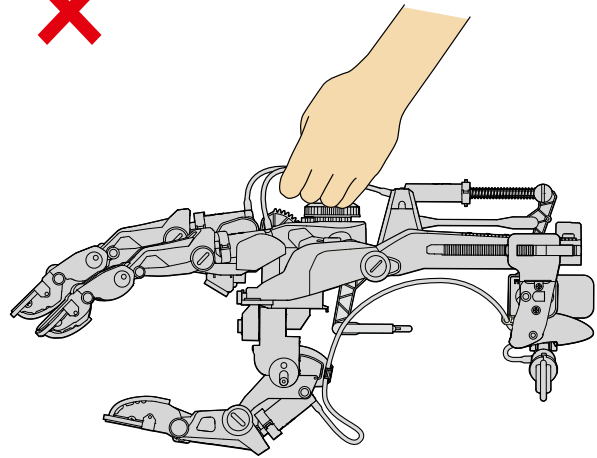


In order for you to have fun with your cyborg hand for as long as possible, there are a few things to consider. When you pick up the hand, hold it as shown in the first picture.



IMPORTANT!

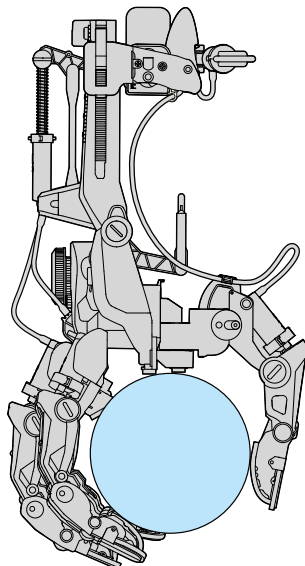
To prevent injury, you should not touch the moving parts of the cyborg hand, especially if it is being operated by someone else.



★ TIPS

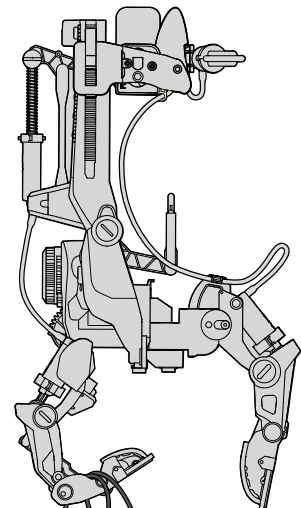
MAKE SURE THE OBJECTS THAT YOU GRAB OR HOLD WITH YOUR CYBORG HAND ARE NOT TOO HEAVY.

YOU SHOULD BE PARTICULARLY CAREFUL WITH OBJECTS THAT YOU LIFT WITH JUST ONE FINGER.



Full grip

Maximum weight
600 g

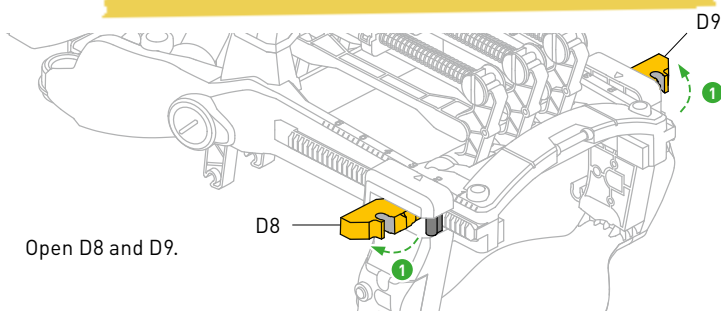


Single finger

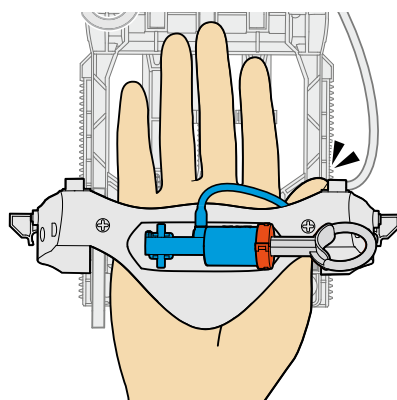
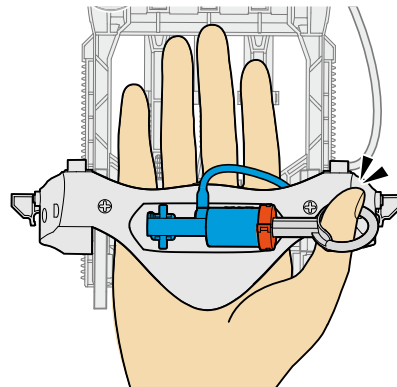
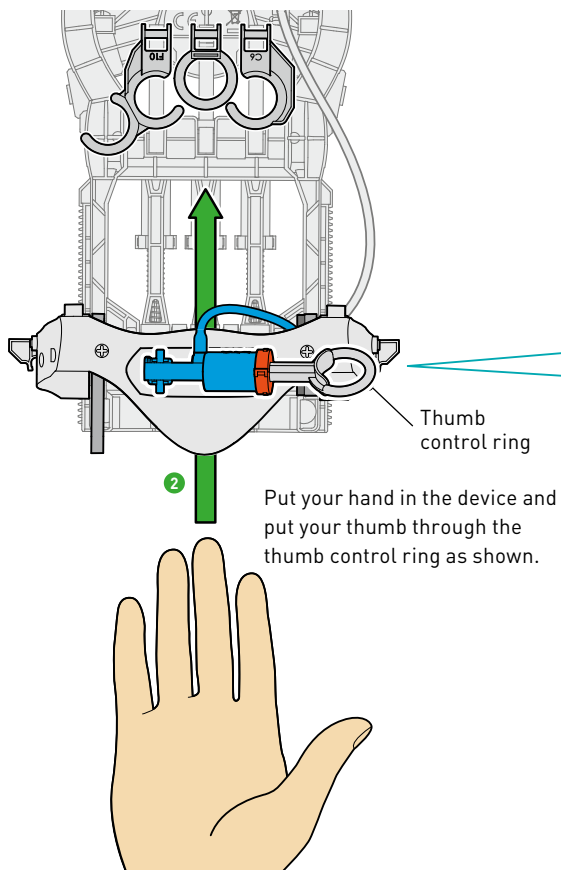
Maximum weight
60 g

HOW TO CUSTOMIZE THE HAND

1

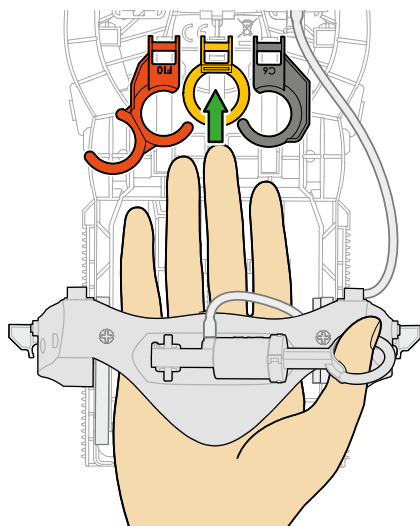


— On the following pages, the hand is shown in the right-handed configuration. The same setting options apply to the left-handed configuration, just mirrored.



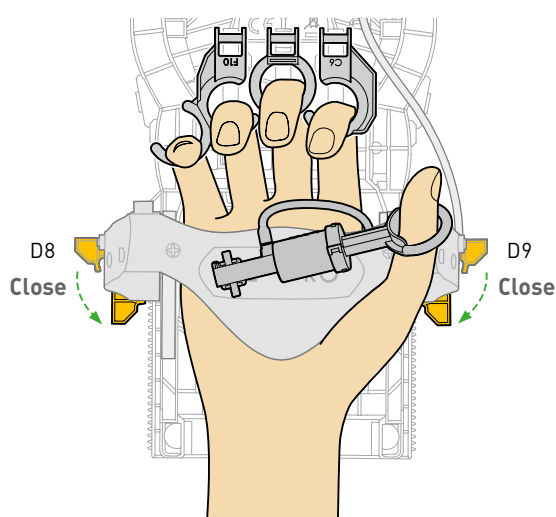
2

Move the palm rest forward or backward until you can comfortably hold the finger control rings with your fingers.



3

When you have found a good position and have a good hold on the device, you can close D8 and D9 again.

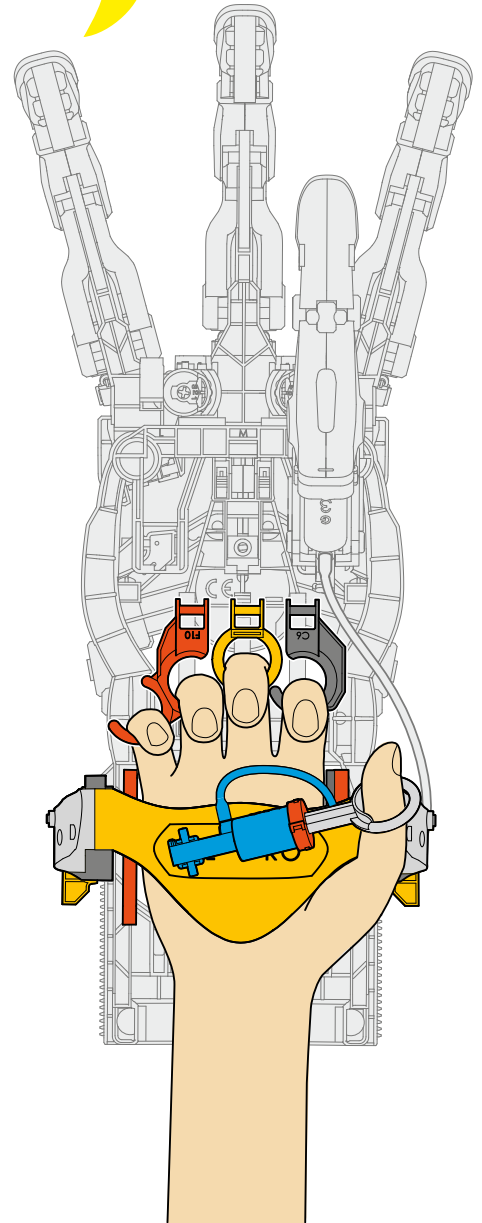
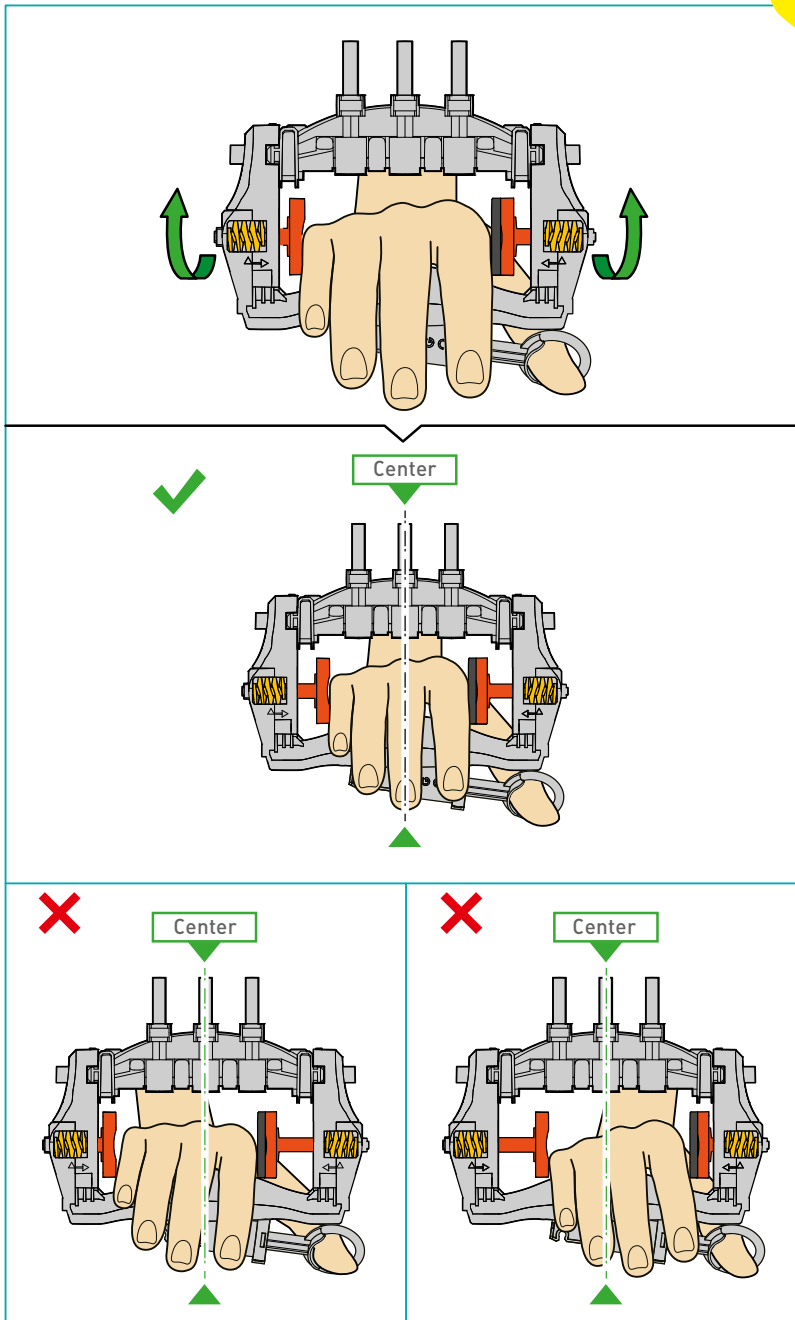




4

Use the two set screws to adjust the position of the two side rails so that your hand is centered on the palm rest.

— After you have adjusted the cyborg hand to your hand and finger length, you can now adjust the width of the palm rest area to your hand.



5

Done!





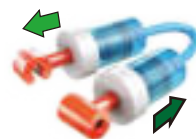
SETTINGS

You can use the central rotary knob on the top of the hand to continuously adjust the degree to which the fingers extend up from the hand.

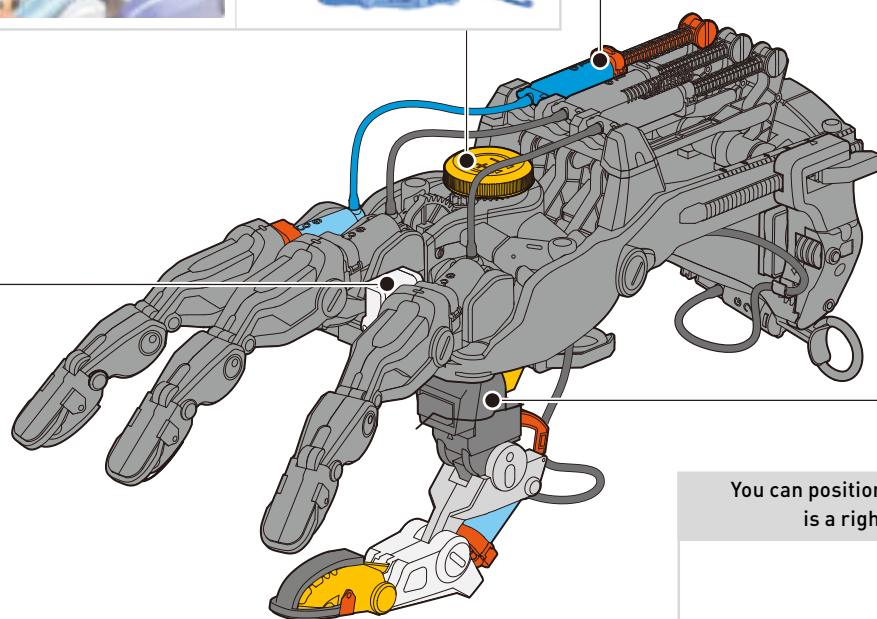
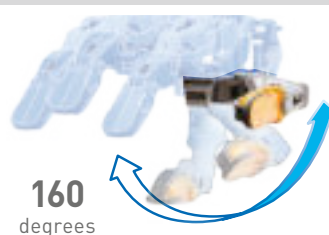


— After you have customized the cyborg hand to fit your own hand, you can play around with the positioning of the cyborg hand's fingers and thumb.

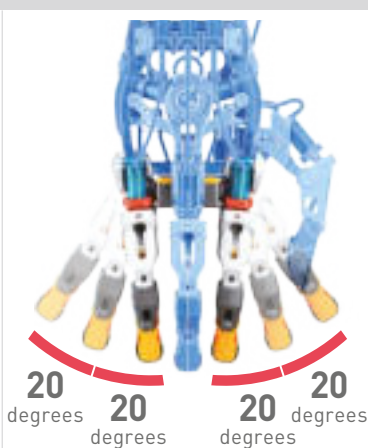
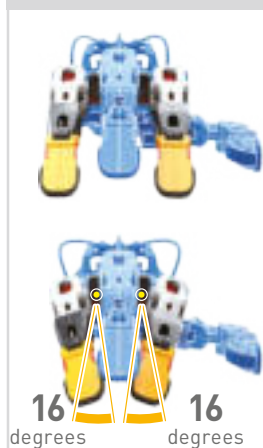
You already experimented with the hydraulic system and its functions during the tests on pages 22 and 23.



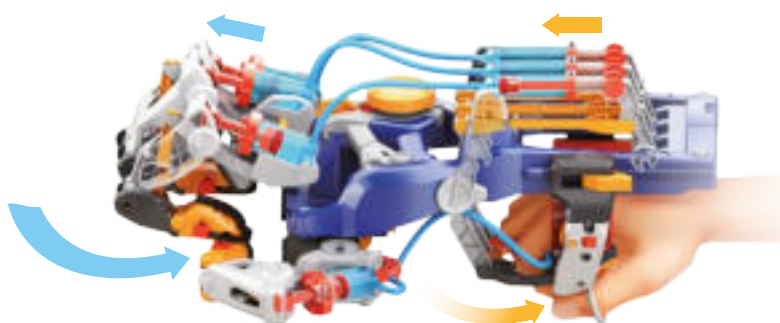
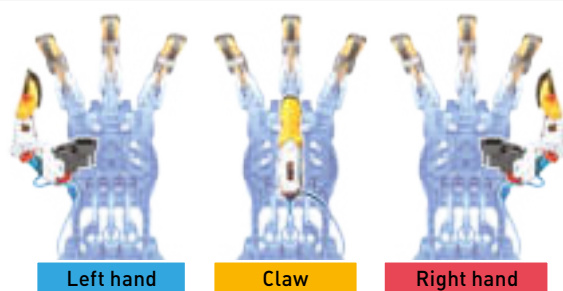
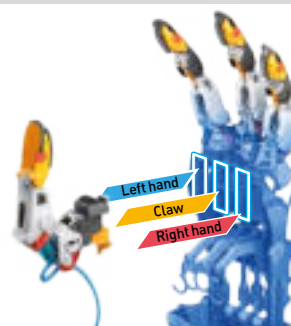
You can rotate the thumb up to 160 degrees.



The position of the fingers can also be adjusted at the finger joints.

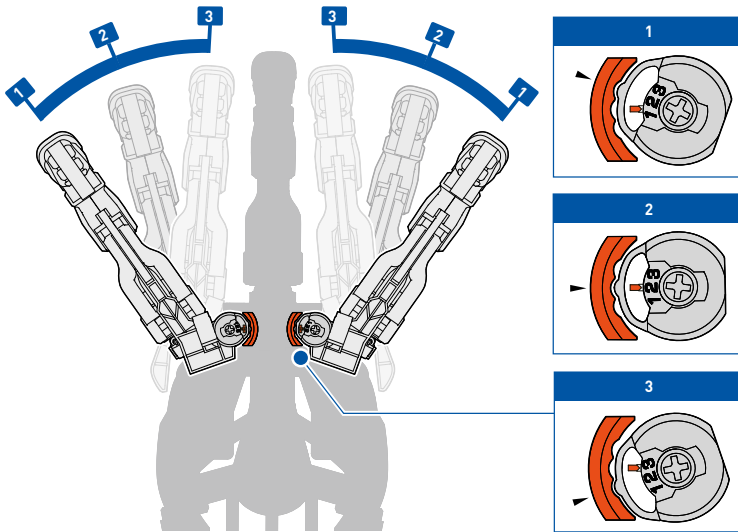


You can position the thumb so that your cyborg hand is a right hand, a left hand, or a claw.

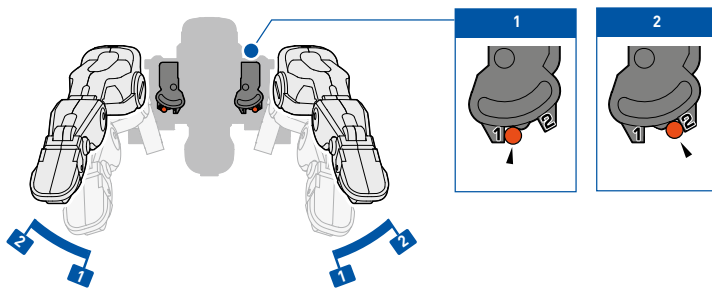


ADJUSTING THE FINGER JOINTS

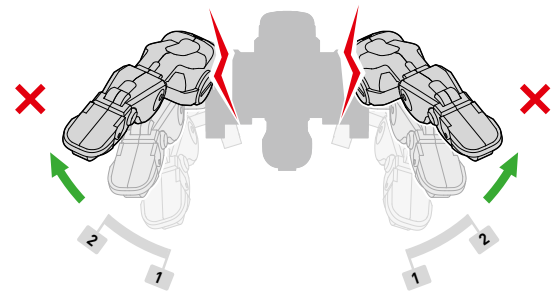
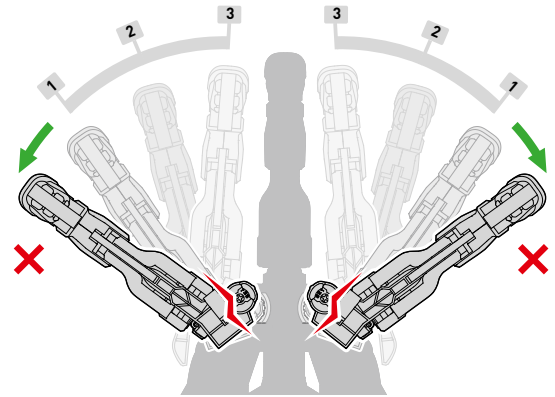
You can adjust the horizontal spread of the two outer fingers in three increments using the adjustment wheel between the fingers.



With the two small switches shown here, you can adjust the extension of the fingers in two increments.



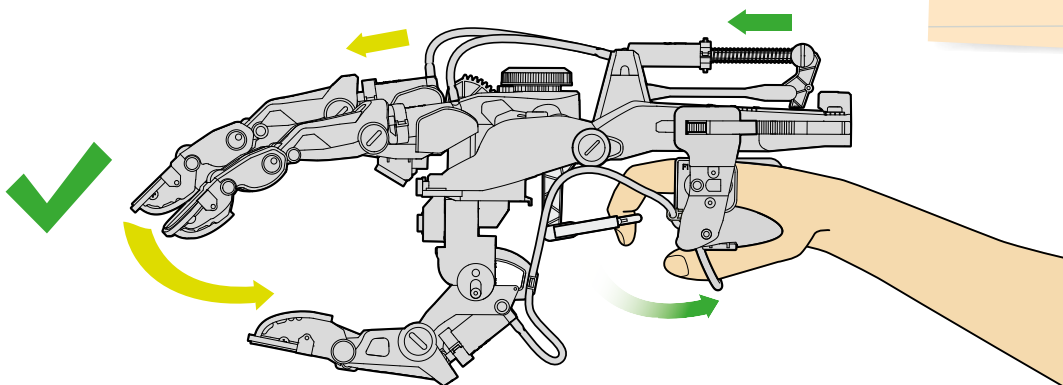
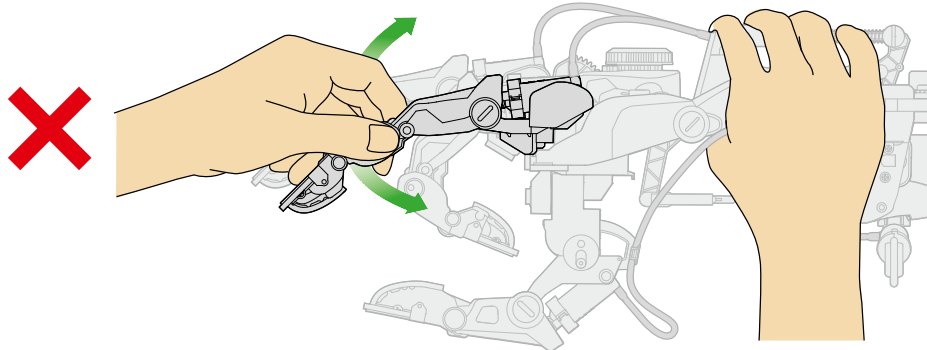
! Do not bend the joints beyond their widest spread or extension. The joints could break.



★ TIPS

HANDLE THE FINGER JOINTS WITH CARE.

PULLING, BENDING, OR TURNING THEM TOO HARD CAN LOOSEN THE TUBES AND CAUSE A LEAK IN THE HYDRAULIC SYSTEM.





EXPERIMENT 3

Picking up small objects

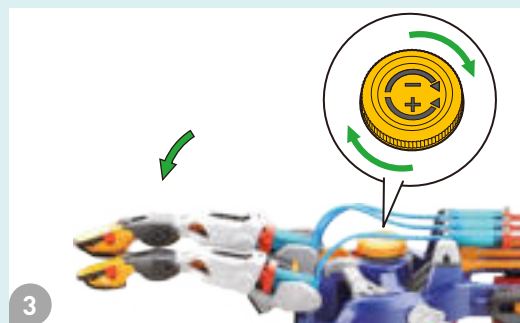
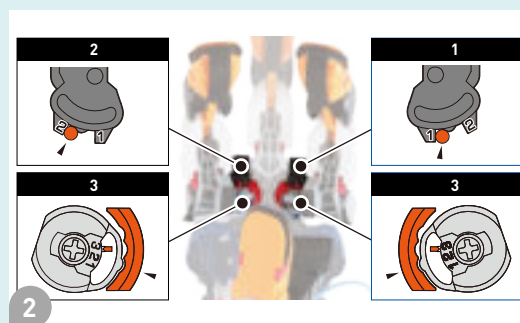
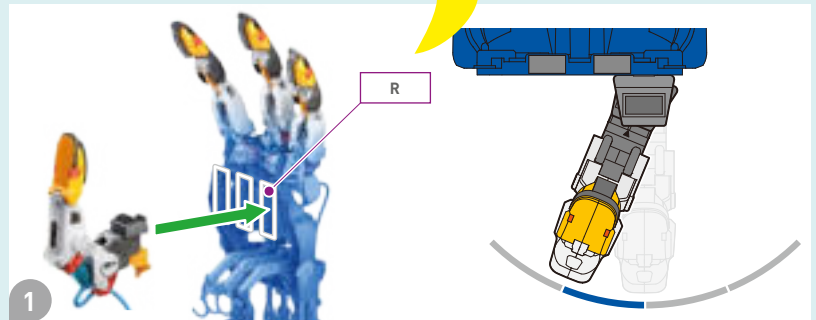
You will need

- Your cyborg hand
- Small objects
- Felt-tip marker

Here's how

1. Insert the thumb into the right thumb slot. (In the left-handed configuration, the thumb goes in the left thumb slot.) Now adjust the angle of the thumb as shown in the picture.
2. Adjust the finger joints. Position the knobs as shown in the picture.
3. Adjust the extension of the fingers. To do this, turn the central rotary knob on the top clockwise until it stops.
4. Adjust the hand until you have found the perfect configuration with which to pick up some small objects. It will take some practice using the hand before you are able to easily pick up various small objects. Keep trying — practice makes perfect!
5. This hand setting is also perfect for drawing with the cyborg hand. To do this, place the marker on the foam pad of the thumb, as shown in the picture. Then pull the index finger control ring toward you to pinch the marker between the index finger and thumb. Now you can draw. But again, practice makes perfect.

— On the following pages, the hand is shown in the right-handed configuration. If you want to do the exercises in the left-handed configuration, you just have to mirror the images.



EXPERIMENT 4

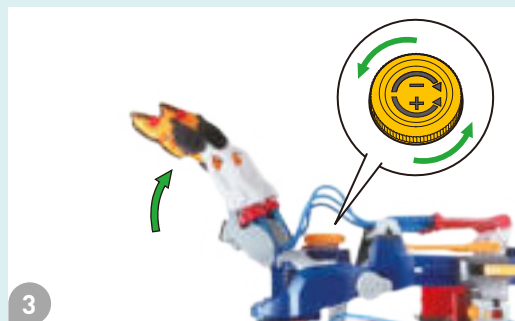
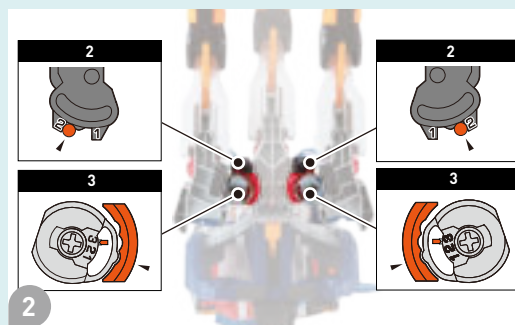
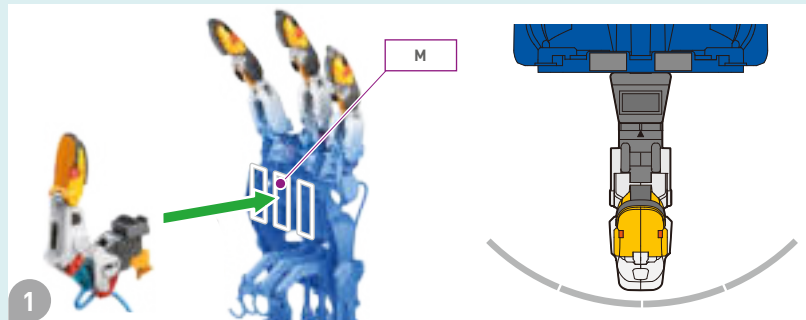
Grabbing large objects

You will need

- Your cyborg hand
- A bigger object

Here's how

1. Place the thumb in the middle thumb slot and adjust the angle of the thumb as shown in the picture.
2. Position the knobs as shown in the picture.
3. Turn the central rotary knob on the top counterclockwise as far as it will go to reach the maximum extension of the fingers.



Maximum weight
150 g





CHECK IT OUT



Exoskeletons

— Your cyborg hand is a machine that you can wear on your body. Therefore, you can call it an exoskeleton. Many people around the world are currently developing artificial exoskeletons because these devices could help people in a lot of different ways.



Medicine

— Many people can no longer perform all the movements they would like to with their own bodies. To help people with physical disabilities, researchers and doctors are developing special exoskeletons. For example, these could help a person learn to walk again after a stroke. And people with paralysis could also use exoskeletons to move around more freely and independently.



Work and Industry

IN THEIR JOBS, MANY PEOPLE HAVE TO LIFT HEAVY THINGS OR PERFORM OTHER MOVEMENTS THAT COULD DAMAGE THE BODY, ESPECIALLY OVER TIME.

HOWEVER, IF WORKERS WEAR EXOSKELETONS, THESE POWERFUL MACHINES CAN PROVIDE MOST OF THE FORCE REQUIRED TO PERFORM DEMANDING PHYSICAL TASKS. THUS, A WORKER'S PERFORMANCE IS INCREASED AND POSSIBLE INJURIES ARE PREVENTED.



—Exoskeletons are even being developed for the military. Soldiers often have to carry large amounts of equipment around or lift very heavy things on the move, which makes them slow and puts them at high risk of injury. For this purpose, exoskeletons have been developed that allow soldiers to carry backpacks weighing up to 200 pounds and to lift other heavy things without effort.

— Lobsters have a particularly hard exoskeleton



Exoskeletons in the animal kingdom

— Around 80 percent of all animal species have an exoskeleton! That includes all arthropods, which includes insects, spiders, crabs, and many other animals. Unlike the skeletons of vertebrates (the subphylum to which we humans belong), the skeletons of arthropods are not inside the body, but serve as protection around the body.

The armor-like exoskeletons are made of hard chitin and proteins. They are jointed — otherwise, the animals would not be able to move.

Exoskeletons protect against environmental factors, but they cannot grow with the animals.

That is why all arthropods must shed their exoskeletons regularly.



If the cyborg hand's fingers are not working, check the following:

1. Check if there is air in the G1 cylinder. If so, complete the steps on page 51.
2. Use pages 20–21 to check that the hydraulic cylinders are assembled correctly.
3. Check that the fingers are correctly assembled and correctly connected together (check on pages 14–16).

If the degree of extension of the cyborg hand's fingers cannot be adjusted properly:

Go to page 30 and check that you have followed steps 1–6 correctly.

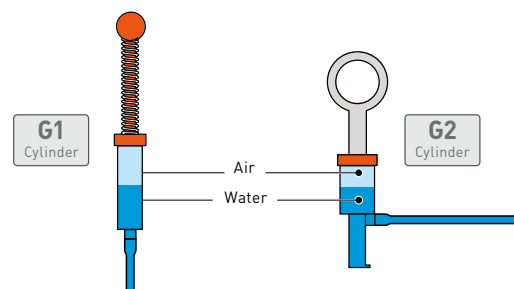


If the cyborg hand's thumb doesn't work properly, check the following:

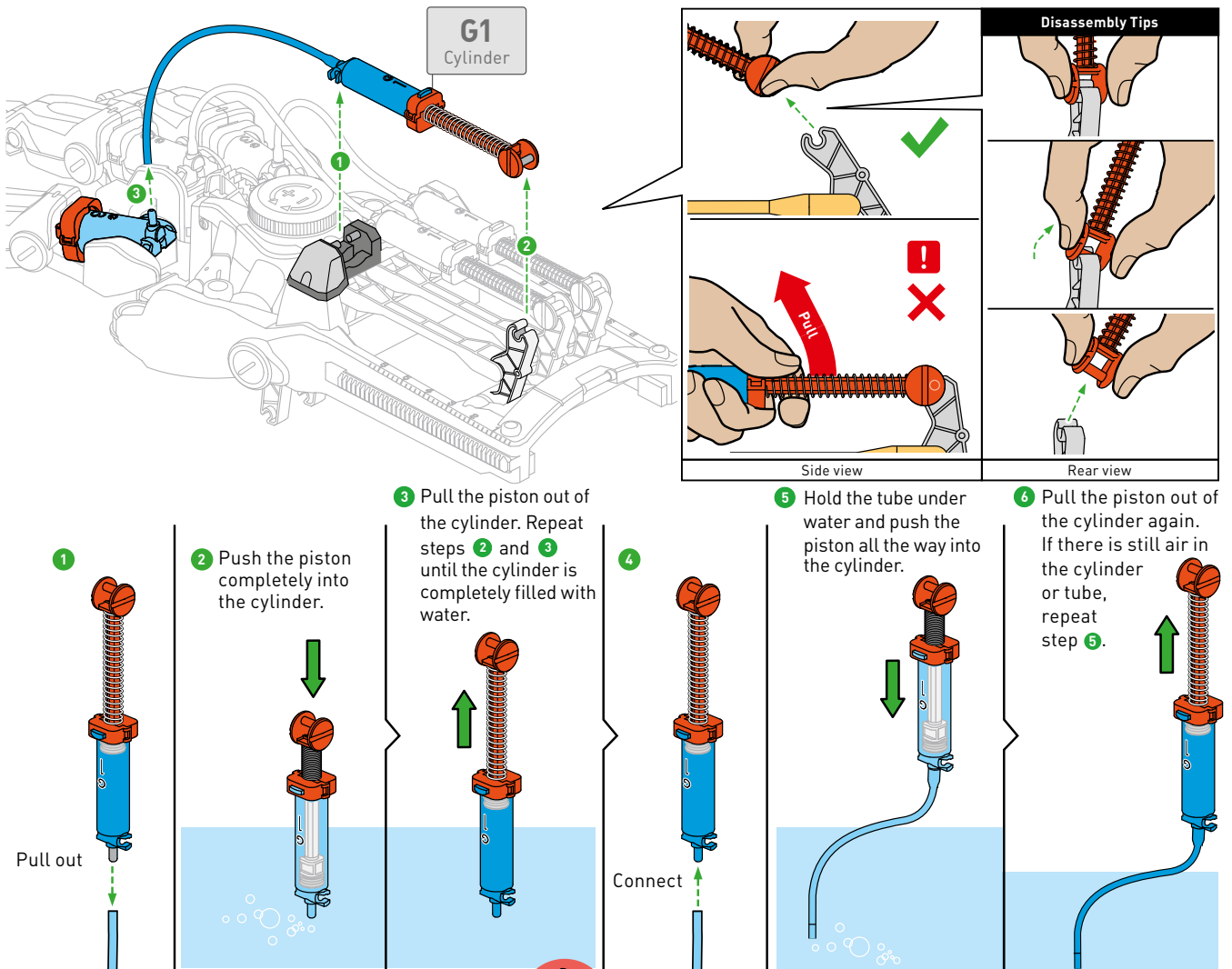
1. Check if there is air in the G2 cylinder. If so, follow the steps on page 53.
2. Check if the hydraulic tube is twisted and blocked.
3. Check that the hydraulic cylinder is assembled correctly. Compare pages 20, 21, and 25.
4. Check that you have assembled the thumb correctly. Go to pages 27–29.

Air in the cylinders limits the function of the hydraulic system. The fingers and thumb will not flex and extend as well if there is air in the hydraulic systems.

Regardless of how long you have played with the cyborg hand, air can get into the hydraulic system from time to time. You can find out how to get rid of it on the next page.

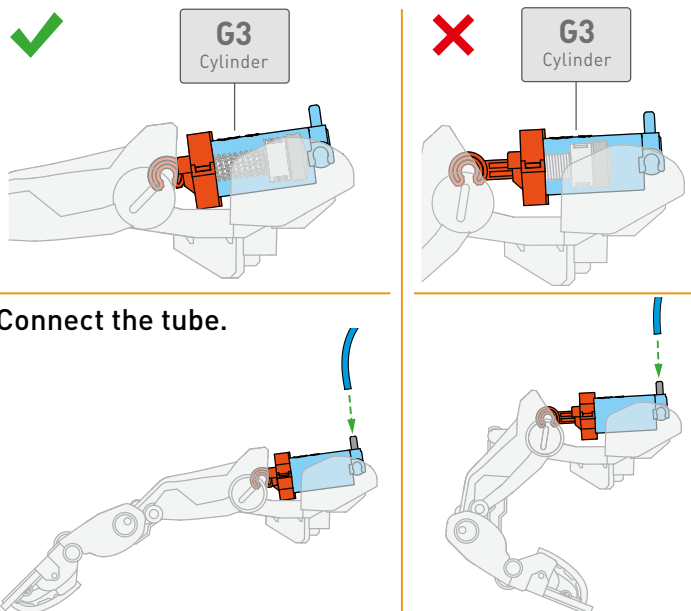


Do the fingers' hydraulic systems leak or are there air pockets in them? Then do the following:



Here's how to properly connect the tube to the G3 cylinder.

Push the piston all the way into the G3 cylinder so that no excess air remains.





What is a cyborg?

— Maybe there is someone in your family or in your class with a pacemaker or a PROSTHESIS. If so, you already know a cyborg! That's because a cyborg is simply a combination of a human and a MACHINE — in other words, a being that consists of both artificial and natural body parts. There are even people who would say that you are a cyborg if you wear eyeglasses, but then a lot of people would be cyborgs, and that would be a bit boring.

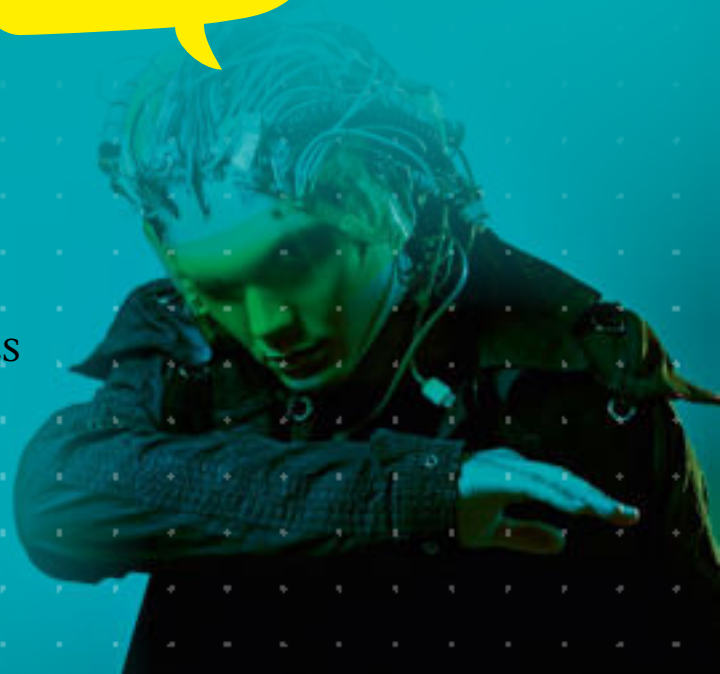
— This boy has a cochlear hearing implant, which enables him to hear.



The origin of the term "cyborg"

— Two scientists named Manfred Clynes and Nathan Kline came up with the term "cyborg," combining the words "cybernetic" and "organism." That was about 60 years ago, in 1960. At that time, their goal was to make people more fit for life in outer space using hightech equipment that could be implanted inside them. But, sixty years later, we are still a long way from that.

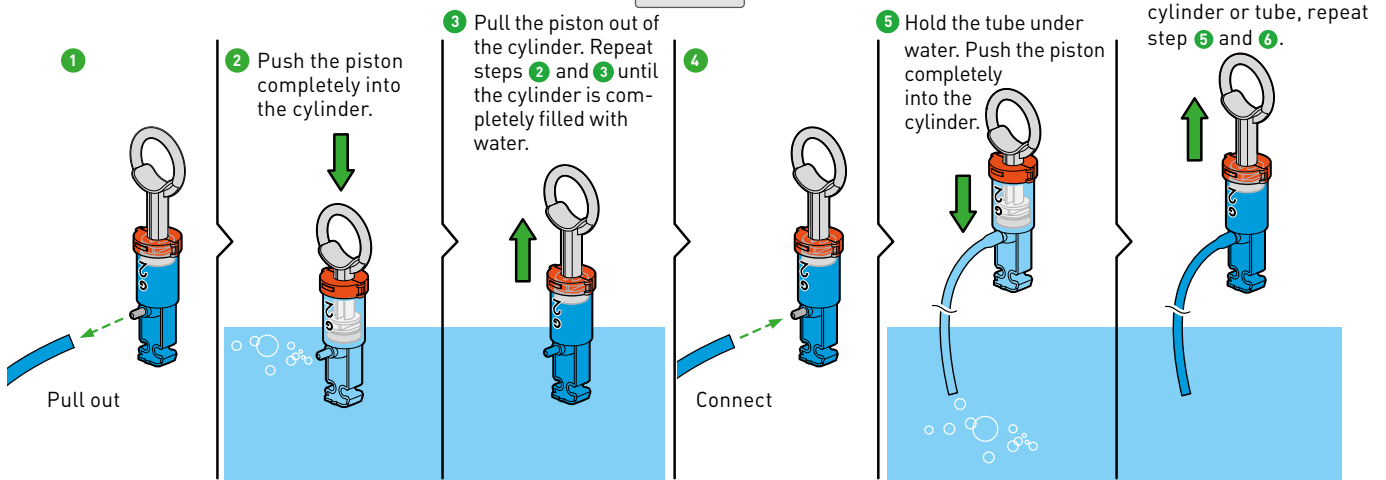
— Did Clynes and Kline imagine a cyborg that looked like this?



— In the future, however, we will certainly see more people wearing various TECHNOLOGICAL DEVICES on or in their bodies. And maybe one day we will really ask ourselves whether the person standing in front of us is human or a machine.

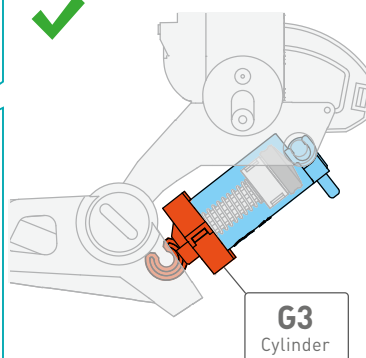
TROUBLESHOOTING

Does the thumb's hydraulic system leak or is there an air pocket in it? Then do the following:

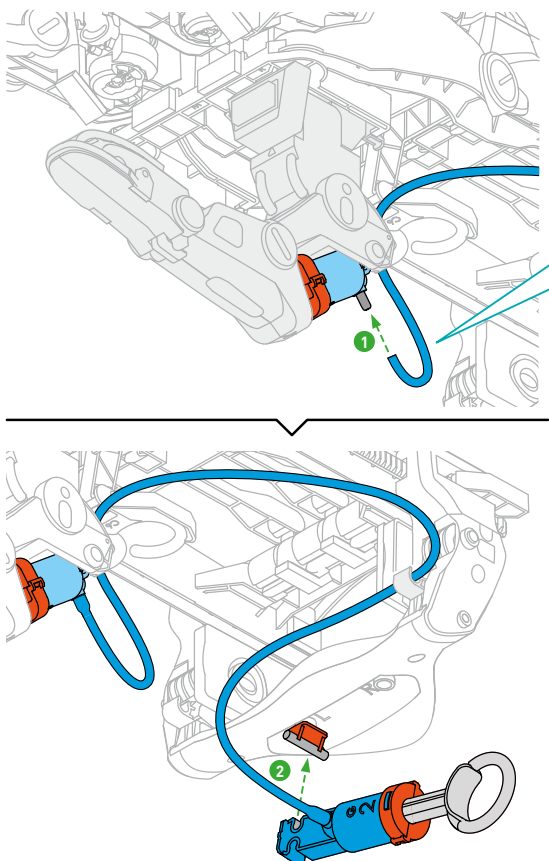
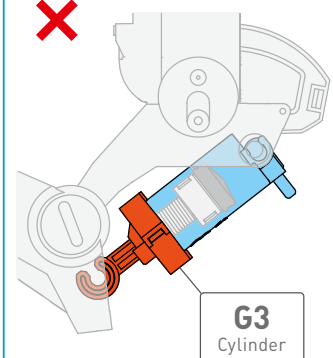


! Here's how to properly connect the tube to the G3 cylinder.

Push the piston all the way into the G3 cylinder so that no excess air remains.



Connect the tube.





EXPERIMENT 5

Mysterious air pressure

You will need

- Clear plastic cup
- Plastic bowl of water

Here's how

1. Fill the bowl with water.
2. Dip the cup in it so it fills with water. Then, turn it over under the water.
3. Now partially pull the cup out of the water. As long as its opening remains under the surface of the water, it will not empty out. As soon as air penetrates, all of the water in the cup runs out.



DID YOU KNOW ...

... that a drinking straw only works thanks to air pressure? Sucking at the top creates a vacuum in it, and therefore the air pressure pushes the drink into the straw from below.



WHAT'S HAPPENING?

— We live at the bottom of a huge ocean of air. The air column above us weighs heavily on us. We usually don't feel this so-called air pressure, mainly because all of the parts of our bodies are experiencing the same pressure and we are adapted to it. A vacuum (airless space) “feels” the full force of the air pressure. Such a vacuum would form if the water hanging in the cup flowed down under its own weight. But this is prevented by the external air pressure — it is far greater than the weight of the water in the cup. It is similar with household suction cups: Pressing creates a **vacuum** between them and the surface they are stuck to, so the **air pressure** presses the suction cup firmly against the surface.

